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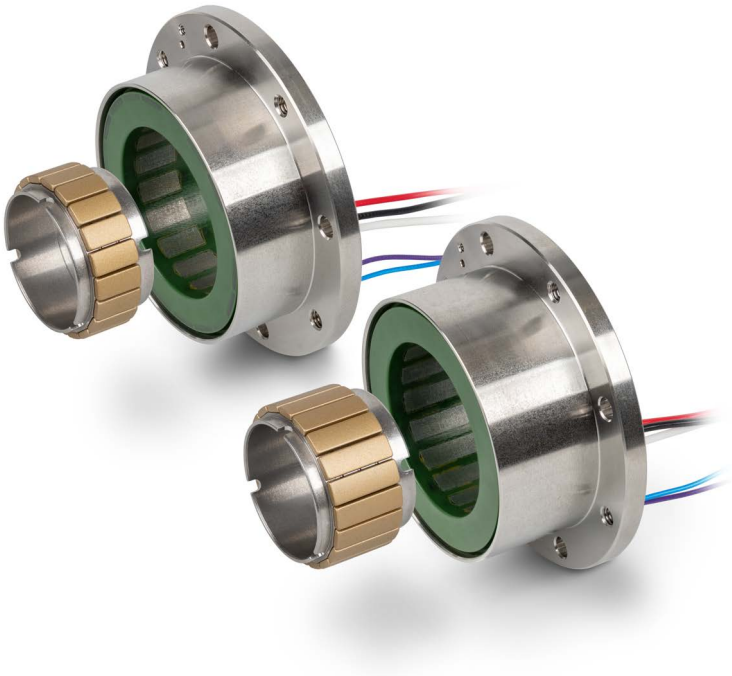
EC frameless DT

Dynamic Torque

Installation Manual



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READ THIS FIRST

BY PRINCIPLE, THE «EC FRAMELESS DT» COMPRISES PARTS THAT PRODUCE STRONG MAGNETIC FIELDS. IT IS THEREFORE MOST IMPORTANT THAT YOU ARE AWARE OF THE CONSEQUENCES OF THESE MAGNETIC FORCES, THAT YOU TAKE THE APPROPRIATE PRECAUTIONARY MEASURES, AND THAT YOU COMMUNICATE THIS FACT TO PERSONS IN YOUR VICINITY!

***These instructions are intended for qualified technical personnel. Prior commencing with any activities**…*
- *you must carefully read and understand this manual and*
- *you must follow the instructions given therein.*

***The «EC frameless DT»** is considered as partly completed machinery according to EU Directive 2006/42/EC, Article 2, Clause (g) and **is intended to be incorporated into or assembled with other machinery or other partly completed machinery or equipment**.*
***Therefore, you must not put the device into service**,…*
- *unless you have made completely sure that the other machinery fully complies with the EU directive's requirements!*
- *unless the other machinery fulfills all relevant health and safety aspects!*
- *unless all respective interfaces have been established and fulfill the herein stated requirements!*

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1 GENERAL INFORMATION

1.1 About this document

1.1.1 Intended purpose

The purpose of the present document is to familiarize you with the direct drive «EC frameless DT». It will highlight the tasks for safe and adequate installation and/or commissioning. Follow the described instructions …

- to avoid dangerous situations,
- to keep installation and/or commissioning time at a minimum,
- to increase reliability and service life of the described equipment.

1.1.2 Target audience

The present document is intended for trained and skilled personnel. It conveys information on how to understand and fulfill the respective work and duties.

1.1.3 How to use

Throughout the document, the following notations and codes will be used.

Notation	Meaning
(n)	refers to an item (such as part number, list item, etc.)
➔	denotes “see”, “see also”, “take note of” or “go to”
Color coding	find information on the colors used on page 13

Table 1-1 Notation used

1.1.4 Symbols & signs

In the course of the present document, the following symbols and signs will be used.

Type	Symbol	Meaning
Safety alert DANGER		Indicates an **imminent hazardous situation**. If not avoided, it **will result in death or serious injury**.
WARNING		Indicates a **potential hazardous situation**. If not avoided, it **can result in death or serious injury**.
CAUTION		Indicates a **probable hazardous situation** or calls the attention to unsafe practices. If not avoided, it **may result in injury**.
Prohibited action	 (typical)	Indicates a dangerous action. Hence, **you must not**!
Mandatory action	 (typical)	Indicates a mandatory action. Hence, **you must**!

Type	Symbol	Meaning
Requirement, Note, Remark		Indicates an activity you must perform prior to continuing, or gives information on a particular point that must be observed.
Best practice		Indicates an advice or recommendation on the easiest and best way to further proceed.
Material Damage		Indicates information particular to possible damage of the equipment.

Table 1-2 Symbols and signs

1.1.5 Trademarks and brand names

For easier legibility, registered brand names are listed below and will not be further tagged with their respective trademark. It must be understood that the brands (the list below is not necessarily concluding) are protected by copyright and/or other intellectual property rights even if their legal trademarks are omitted in the later course of this document.

Brand Name	Trademark Owner
DELO-ML®	© DELO Industrie Klebstoffe GmbH & Co. KGaA, DE-Windach
EPO-TEK®	© Epoxy Technology, Inc., USA-Billerica, MA
Loctite®	© Henkel AG & Co. KGaA, DE-Düsseldorf
NORD-LOCK®	© Nord-Lock International AB, SE-Malmö
omniFIT®	© Henkel AG & Co. KGaA, DE-Düsseldorf
Pico-Clasp	© Molex, USA-Lisle, IL

Table 1-3 Brand names and trademark owners

1.1.6 Copyright

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1.2 About the device

The direct drive «EC frameless DT» is a high-performance, high-torque, dynamic brushless DC internal rotor motor (BLDC motor). It is available in various sizes and is designed to be incorporated into a specially adapted outer body that serves both as the motor's supporting structure and as torque-carrying device.

The «EC frameless DT» composes two main parts:

- **Stator with electric connections**; for installation into a customer-provided outer body (such as housing, machine structure, or carrier system)
- **Magnetic rotor**; for on-site assembly with the installed stator and the customer-provided torque-carrying device

Outer body, motor shaft, and bearings are not part of the «EC frameless DT»'s scope of delivery and are being designed for a particular case of application by the customer.

Important note on the design
The «EC frameless DT» is a sensorless motor and does not feature any Hall sensor signals. As an option, maxon offers the «TSX MAG» encoder.

1.3 About the safety precautions

Safety first—always!

BY PRINCIPLE, THE «EC FRAMELESS DT» COMPRISES PARTS THAT PRODUCE STRONG MAGNETIC FIELDS. IT IS THEREFORE MOST IMPORTANT THAT YOU ARE AWARE OF THE CONSEQUENCES OF THESE MAGNETIC FORCES, THAT YOU TAKE THE APPROPRIATE PRECAUTIONARY MEASURES, AND THAT YOU COMMUNICATE THIS FACT TO PERSONS IN YOUR VICINITY!

READ THE FOLLOWING INSTRUCTIONS CAREFULLY BEFORE YOU ENGAGE WITH ANY WORK AND FOLLOW THE INSTRUCTIONS GIVEN AT ALL TIMES!

- Make sure that you have read and understood the note “READ THIS FIRST” auf Seite A-2!
- Do not engage with any work unless you possess the stated skills (➔Kapitel “1.1.2 Target audience” auf Seite 1-5)!
- Consult ➔Kapitel “1.1.4 Symbols & signs” auf Seite 1-5 to understand the subsequently used indicators!
- You must observe any regulation applicable in the country and/or at the site of implementation with regard to health and safety/accident prevention and/or environmental protection!

DANGER

High voltage and/or electrical shock
Touching live wires causes death or serious injuries!
- *Consider any power cable as connected to live power, unless you have proven the opposite!*
- *Make sure that neither end of cable is connected to live power!*
- *Make sure that the power source cannot be engaged while work is in process!*
- *Obey lock-out/tag-out procedures!*
- *Make sure to securely lock any power engaging equipment against unintentional engagement and tag it with your name!*

WARNING

Strong magnetic field
High magnetic force can cause serious injuries!
- *Keep stator and rotor mechanically blocked at all times! Do so by using a mechanical locking device, a mounting aid, or non-magnetic spacers!*
- *Make sure to remove/keep clear any metal parts or metallic items—also such as cardiac pacemakers, implants, watches, bracelets, credit cards, mobile phones, etc—before you approach the motor!*
- *Use only non-magnetic tools when you work on the motor or in its vicinity!*
- *Put up warning signs stating STRONG MAGNETIC FIELDS around the installation area and at the storage location!*
- *Inform persons around of the potential danger. Instruct them accordingly and request them to follow the precautionary measures!*

WARNING

Pinching and shearing risk
Sudden movement and shift of the rotor can cause serious injuries!
To prevent sudden shift during installation you must keep both stator and rotor blocked at all times. Do so by using a mechanical locking device, a mounting aid, or non-magnetic spacers!

Strong magnetic field
The high magnetic forces produced by the device constitute an imminent hazard to persons wearing a cardiac pacemaker or metal implants.

All persons who possibly may suffer impairment caused by strong magnetic fields must not approach the device and must stay clear and in a safe distance of at least two (2) meters.

General rules
- *Make sure that all associated devices and components are installed according to local regulations.*
- *Be aware that, by principle, an electronic apparatus cannot be considered fail-safe. Therefore, you must make sure that any machine/apparatus has been fitted with independent monitoring and safety equipment. If the machine/apparatus should break down, if it is operated incorrectly, if the control unit breaks down or if the cables break or get disconnected, etc., the complete drive system must return—and be kept—in a safe operating mode.*
- *Be aware that you are not entitled to perform any repair on components supplied by maxon motor.*

Electrostatic sensitive device (ESD)
- *Wear electrically conductive clothing and footwear.*
- *Observe ESD protective measures.*

2 SPECIFICATIONS

In its catalog data sheets maxon specifies the motor data with block commutation (according to «Standard Specification no. 101», which you can find in the maxon catalog in chapter “Technology short and to the point”. For detailed information and values consult the data sheets in the ➔Appendix as of page 27.

The motor data listed below refer to field-oriented control (FOC) and therefore differ from the catalog data based on block commutation. In connection with FOC maxon recommends using the «TSX MAG» encoder module, which can generate both incremental and commutation signals (Hall signals).

2.1 Technical Data

Parameter					DT38S	DT38M	DT50S	DT50M
Key data [a]	Nominal voltage [b]			VDC	21.6		43.2	
	Nominal speed			rpm	9'160	4'690	5'260	3'480
	Nominal torque [c]			mNm	110	201	352	442
	Nominal current			A	6.68	6.25	5.98	4.89
	Motor constant [d]			$\frac{mNm}{\sqrt{W}}$	38.4	62.3	91.3	123
	Winding NTC @ 25 °C			K	5 kΩ ±1%, beta (25…85 °C): 3'490			
Inputs and Outputs (optional) [e]	Incremental and commutation signals				H1, H2, H3 2-channel incremental encoder with own NTC			
Dimensions	Weight	Rotor		g	12	20	28	40
		Stator	Flange	g	54	65	95	107
			Other		59	84	95	123
			Total		113	149	190	230
		Overall weight		g	125	169	218	270
	Ø outside (ØR1)			mm	55		72	
	Ø stator lamination			mm	38		50	
	Ø inside (ØS2)			mm	17		28	
	Length (LM)			mm	19	25	22	27
Environment	Ambient temperature			°C	−40…+100			
	Humidity			%	5…90 (condensation not permitted)			

Parameter					DT65S	DT65M	DT85M	DT85L
Key data [a]	Nominal voltage [b]			VDC	43.2			
	Nominal speed			rpm	3440	1930	2'830	1'630
	Nominal torque [c]			mNm	776	1260	1'900	3'050
	Nominal current			A	8.43	7.73	15.4	14.1
	Motor constant [d]			$\frac{mNm}{\sqrt{W}}$	190	282	364	542
	Winding NTC @ 25 °C			K	5 kΩ ±1%, beta (25…85 °C): 3'490			
Inputs and Outputs (optional) [e]	Incremental and commutation signals				H1, H2, H3 2-channel incremental encoder with own NTC			
Dimensions	Weight	Rotor		g	44	71	98	153
		Stator	Flange	g	151	185	215	266
			Other		182	268	428	621
			Total		333	453	643	887
		Overall weight		g	377	524	741	1'040
	Ø outside (ØR1)			mm	88		108	
	Ø stator lamination			mm	65		85	
	Ø inside (ØS2)			mm	35.5		47	
	Length (LM)			mm	25	33	33	43
Environment	Ambient temperature			°C	−40…+100			
	Humidity			%	5…90 (condensation not permitted)			

[a] The values refer to field-oriented control (FOC).

[b] The nominal voltage is based on the assumptive supply voltage of 24 or 48 VDC for a positioning controller with a maximum output voltage of 90% of the supply voltage (0.9 x V_{CC}).

[c] If the stator is mounted in a metallic, thermally conductive housing, heat transfer is usually improved (typically by 50%) and operation with higher nominal torques is possible.

[d] The motor constant indicates the electrodynamic torque (without friction, etc.), which occurs with current heat losses of 1 W. It is an important parameter for the strength of a motor.

[e] Choice between multiple functions.

Table 2-4 Technical data (typical)

2.2 Dimensional Drawings

For dimensional drawings see ➔Appendix as of page 27.

2.3 Nameplate

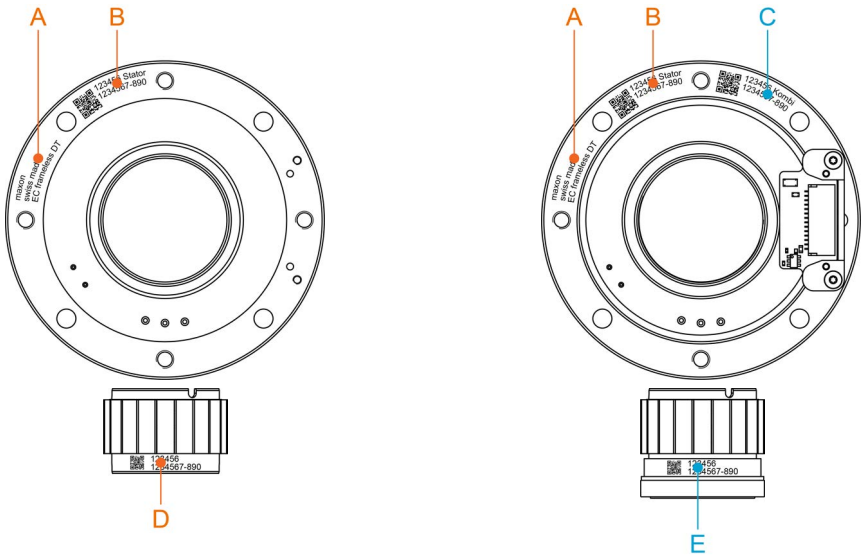

Figure 2-1 Nameplate (typical) – EC frameless DT without (left) and with TSX MAG encoder (right)

Part	A	B	C
Stator	Manufacturer Origin Type	Data Matrix Code Production data Production ID and consec. #	Data Matrix Code Production data Production ID and consec. #

Part	D
Rotor	Data Matrix Code Production data Production ID and consec. #

Part	E
Rotor with pilot rotor	Data Matrix Code Production data Production ID and consec. #

Table 2-5 Labeling details

2.4 Standards

The described device has been successfully tested for compliance with the below listed standards.

Standards & Specifications		
Manufacturing	101	Standard Specification for maxon EC motor

Table 2-6 Standards

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3 INSTALLATION

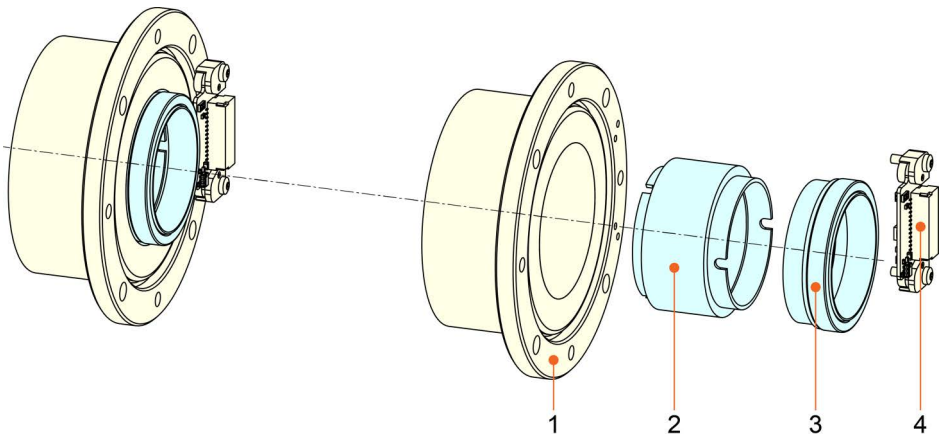
The motor's two main components—stator with electric connections and magnetic rotor—come in unmounted condition in packaged cases.

Precautions with multiple packaging
Depending on the order volume, several rotors are supplied in the same packaging.
When removing a rotor, you must ensure that the rotors remaining in the packaging are and remain fixed. Otherwise, they may attract each other magnetically and thus be damaged.

Motor versions with encoder (with optional «TSX MAG») have an additional pilot rotor equipped to the rotor and the stator carries a built-in encoder module. The four components are paired with each other during the manufacturing process and thus form a final unit. It is therefore important that you handle and install the rotor and stator paired.
For motor versions without encoder, rotor and stator are not paired.

Important note on the design
*The components for motor versions **with encoder** are matched and paired with each other. Install them in the paired state.*

BESIDES SPECIAL PRECAUTIONS IN RESPECT TO HEALTH AND SAFETY, THE «EC FRAMELESS DT» MUST BE INSTALLED IN A PARTICULAR AND SPECIFIC WAY. FOR BOTH SAFE AND EASY INSTALLATION AS WELL AS RELIABLE OPERATION CLOSELY FOLLOW THE BELOW DESCRIBED INFORMATION IN GIVEN ORDER.



1 Stator
2 Rotor
3 Pilot rotor (only in connection with TSX MAG)
4 TSX MAG encoder (optional)

Figure 3-2 Main components

3.1 General Rules

Check on the safety matters and rules (➔page 7) before you proceed.

BY PRINCIPLE, THE «EC FRAMELESS DT» COMPRISES PARTS THAT PRODUCE STRONG MAGNETIC FIELDS. IT IS THEREFORE MOST IMPORTANT THAT YOU ARE AWARE OF THE CONSEQUENCES OF THESE MAGNETIC FORCES, THAT YOU TAKE THE APPROPRIATE PRECAUTIONARY MEASURES, AND THAT YOU COMMUNICATE THIS FACT TO PERSONS IN YOUR VICINITY!

BEFORE YOU ENGAGE WITH ANY WORK, READ, UNDERSTAND, AND FOLLOW THE SAFETY PRECAUTIONS AS OF PAGE 7!

OBSERVE THE FOLLOWING NOTICE ON THE PREREQUISITES FOR PERMISSION TO COMMENCE INSTALLATION.

The «EC frameless DT» is considered as partly completed machinery according to EU Directive 2006/42/EC, Article 2, Clause (g) and **is intended to be incorporated into or assembled with other machinery or other partly completed machinery or equipment**.

WARNING

Risk of injury
Operating the device without the full compliance of the surrounding system with the EU Directive 2006/42/EC may cause serious injuries!
- *Do not operate the device, unless you have made completely sure that the other machinery fully complies with the EU directive's requirements!*
- *Do not operate the device, unless the other machinery fulfills all relevant health and safety aspects!*
- *Do not operate the device, unless all respective interfaces have been established and fulfill the requirements stated in this document!*

WARNING

Pinching and shearing risk
Sudden movement and shift of the rotor can cause serious injuries!
To prevent sudden shift during installation you must keep stator and rotor blocked at all times. Do so by using a mechanical locking device, a mounting aid, or non-magnetic spacers!

Electrostatic Sensitive Devices (ESD)
- *Wear electrically conductive clothing and footwear.*
- *Observe ESD protective measures.*

Requirements for operation
The function of the drive is only guaranteed if all specified design characteristics and tolerances are met. Do only continue if this is actually the case. If this is not the case you must rectify the deviations, first.
Safe, trouble-free, long-term operation is only possible…
- *if the defined properties of the outer body (such as housing, machine structure, or carrier system) as well as the motor shaft and its bearings are met, and*
- *if centering and axial position of stator and rotor are carried out with sufficient accuracy!*

Possible irreversible damage of motor
Until completion of the installation, individual components can be permanently damaged by improper handling.
- *Handle the components with particular care.*
- *Pay special attention to cleanliness.*
- *Make sure that no impurities, foreign objects, or particles penetrate the drive or can be attracted by the motor magnets.*

Thermal behavior
The values given in the data sheet for nominal torque (maximal continuous torque), thermal resistances, and nominal current (maximal continuous current) refer to the motor mounted to a plastic plate with limited heat dissipation capability and free convection.
When mounted to a metal flange, the thermal resistance R_{th2} can be reduced by up to 80%. Thus, technical measures (such as good ventilation, heat-conducting metallic mounts, or heat sinks) can substantially reduce temperatures and significantly increase performance.

3.2 Design Guidelines

Important note on the design
The correct technical design of the bearing arrangement and the integration into the application's housing are the sole responsibility of the customer.
- *maxon does not make any suggestions as to how a customer-side integration into the respective application must be designed and laid out or what it should look like.*
- *The points listed below are intended to serve as an aid and to show (in a non-exhaustive manner) which drive-side aspects need to be taken into account in a customer-built design.*
- *The points listed below do not claim to be complete.*

3.2.1 Geometric Tolerances

The dimensional drawings (see ➔Appendix as of page 27) show the shape and position tolerances of stator to rotor. Other tolerances may apply to specific motor designs, which will be communicated by appropriate means.

Compliance with the designated tolerances is vital and guarantees that the motor achieves the specified performance data (such as torque and speed). Even minor deviations from the specified form and position tolerances will result in a reduction of the performance data. Exceeding deviations can lead to stripping of the rotor, to an increased cogging torque, and to permanent damage to the motor.

maxon therefore urgently recommends that the specified form and position tolerances indicated in the dimensional drawings be observed.

3.2.2 Mechanical Design

The customer's components (for example housing and shaft) must be designed for the expected mechanical loads and forces in terms of strength, rigidity, and stability.

3.2.3 Magnetic Forces

The rotor of the «EC frameless DT» is equipped with strong magnets. As a result, large forces can occur in both the axial and radial directions. Note this in particular with regard to the following topics:

- Bearing arrangement
- Calculations for strength and stiffness
- Joining the individual components during assembly
- Maintenance
- Dismantling and deconstruction

With rotor and stator arranged in accordance to the specifications on the dimensional drawings (see ➔Seite 2-11), then the axial and radial forces emanating from the magnetic field are minimal.

3.2.4 Heat Dissipation

The stator of the «EC frameless DT» must be thermally well connected to the customer's housing. This can be achieved by the design and material selection of the housing and via suitable fit tolerances.

3.2.5 Bearing and Fixation of the Rotor

maxon recommends the use of ball bearings with an ISO tolerance class P5 or higher.

maxon recommends to join the rotor of the «EC frameless DT» and the customer's counterpart (shaft) by adhesive bonding. It is important to ensure that the bonded joint is designed that the maximum motor torque can be transmitted with a sufficient safety margin over the entire operating range.

Possible irreversible damage of motor
The rotor is not designed to produce a force-fit torque transmission to the customer shaft by means of a press fit (interference fit, shrink fit).
maxon explicitly advises against a press fit.

The following data are to be understood as recommendations. They apply to common models and methods under typical conditions and do not claim to be complete or correct. For manufacturers and sources of supply see ➔page 6.

Drive	Shaft material	Adhesive	Shaft tolerance	Surface finish
EC frameless DT38S	Steel	Ergo 4430 DELO-ML 5327	17 f7	≤ R_a 1.6
EC frameless DT38M				
EC frameless DT50S	Steel	Ergo 4430 DELO-ML 5327	28 f7	≤ R_a 1.6
EC frameless DT50M				
EC frameless DT65S	Steel	Ergo 4430 DELO-ML 5327	35.5 f7	≤ R_a 1.6
EC frameless DT65M				
EC frameless DT85M	Steel	Ergo 4430 DELO-ML 5327	47 f7	≤ R_a 1.6
EC frameless DT85L				

Table 3-7 Fixation of the rotor – recommended adhesives

3.2.6 Fixation of the Stator

maxon recommends to fix the stator of the «EC frameless DT» axially using bolted connections. This axial screw connection also serves as a non-positive transmission of the torque.

Requirements for operation
Use only screws that, once installed, do not protrude the inside front face of the stator flange. Too long screws can damage the printed circuit board, thus possibly causing electrical breakdown and destruction of the motor.

The following data are to be understood as recommendations. They provide an overview of the recommended fastening screws and the minimum tightening torques for safe torque transmission. An application-specific screw calculation as to VDI guideline 2230 must be taken into account.

The screw connections must be tightened to the appropriate torque using a torque wrench.

Drive	Screws	Property class	Tightening torque
EC frameless DT38S	3 x M3	min A2-80 / 6.8	1 Nm ±0.2
EC frameless DT38M			
EC frameless DT50S	4 x M4	min A2-80 / 6.8	2.5 Nm ±0.5
EC frameless DT50M			
EC frameless DT65S	4 x M4	min A2-80 / 6.8	2.5 Nm ±0.5
EC frameless DT65M			
EC frameless DT85M	4 x M4	min A2-80 / 6.8	2.5 Nm ±0.5
EC frameless DT85L			

Table 3-8 Fixation of the stator – recommended bolted joints

The screw connections must locked and secured using threadlocker or Nord-Lock safety washers. For manufacturers and sources of supply see ➔page 6.

Material pair or Combination of parts	Product	Remark
Steel screw / **Aluminum** casing **Steel** screw / **Steel** casing	DELO-ML 5327	[g]
	EPO-TEK 301-2G	[g]
	Loctite 222	[f]
	Nord-Lock	[f]
	omniFIT 230L	[f]

[f] detachable connection [g] inseparable, rigid connection

Table 3-9 Fixation of the stator – recommended screw locks

3.2.7 Tools & Equipment

- Hand tools, non-magnetic
- Cleaning agent
- Lint-free cloths
- Centering aids for rotor and stator, non-magnetic
- Mounting fixture (for example hand-lever press or drill stand)

3.3 Mechanical Installation

Recommended procedure
The installation approach that matches your case of application depends on your setup, your actual application design, and your specific mounting conditions.
Observe the recommendations and analogously adjust the procedure as to your case of application.

WARNING

Pinching and shearing risk
Sudden movement and shift of the rotor can cause serious injuries!
To prevent sudden shift during installation you must keep stator and rotor blocked at all times. Do so by using a mechanical locking device, a mounting aid, or non-magnetic spacers!

Protect hands and fingers
Put on well-fitting, cut-resistant protective gloves.

Two variants of mounting options are schematically shown below, which must be understood as a general guide. The actual conditions depend on the respective customer application.

For easier differentiation, color coding is used in illustrations of individual components are shown:

Yellow	Stator of the «EC frameless DT»	Light yellow	Housing (by customer)
Blue	Rotor of the «EC frameless DT»	Light blue	Shaft (by customer)

1) Fasten rotor on shaft

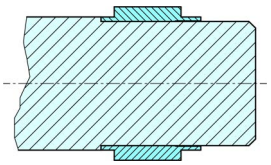


Figure 3-3 Mounting the rotor

2) Position and align the shaft with the housing. Support the shaft.

Figure 3-4 Positioning shaft and housing

3) Mount and fasten stator in a guided and controlled position.

Figure 3-5 Mounting the stator

4) Check installation position of rotor and stator as to dimensional drawing's specifications (➔as of page 27).

Figure 3-6 Checking the installation position

3.4 Electrical Installation

Electrical Interface—possible permanent damage

- *Handle connections and cables with special care!*
- *Do not kink cable, do not bend around small radii, do not route around sharp edges!*
- *Do not apply tensile stress, use strain relief!*

3.4.1 Connections

3.4.1.1 Motor

By default, the «EC frameless DT» is supplied without connector. It has three individual strands to connect to the motor windings 1, 2, and 3 as well as two additional individual strands for the NTC thermistor.

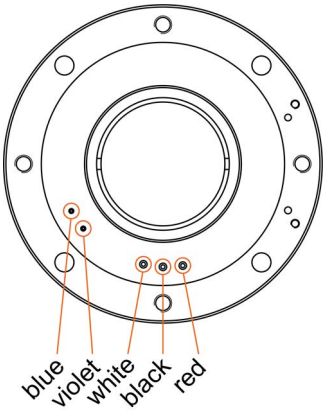


Figure 3-7 Motor connections

Color	Signal	Description
red [h]	W1	Motor winding 1
black [h]	W2	Motor winding 2
white [h]	W3	Motor winding 3
violet [i]	NTC_IN	Thermistor
blue [i]	NTC_OUT	Thermistor

[h] AWG24 for DT38, AWG18 for DT50 & DT65 and AWG16 for DT85

[i] AWG18 for all sizes

Table 3-10 Terminal assignment – Motor strands

3.4.2 Temperature Monitoring

3.4.2.1 Motor: Temperature Sensor

The «EC frameless DT» is equipped with two in parallel connected temperature sensors based on the NTC thermistor principle (NTC; Negative Temperature Coefficient). The data sheet (➔as of page 27) shows the equivalent resistance of this parallel circuit. Thereby, a negative temperature coefficient is used, which is associated with a decreasing electrical resistance as the temperature increases.

The NTC thermistor are each positioned between two motor windings. The direct coupling to the winding results in a delay-free and very accurate temperature measurement. This leads to a minimal delay of the temperature measurement and to a higher thermal resistance (lower measured temperature). For this reason, temperature monitoring is primarily suitable for continuous operation, whereby the actual temperature measurement depends on the mounting conditions and requires testing.

The NTC thermistor does not perform linear. The respective temperature can be calculated using the following parameters (find the corresponding values in the data sheet; ➔Appendix as of page 27):

Motionless, permanently energized motor
If the rotor does not turn while the same winding is permanently energized, no uniform heating takes place in the motor. In this case, the formula can only serve as an approximation.

$$T(R) = \frac{1}{\frac{\ln\left(\frac{R}{R_{25}}\right)}{beta} + \frac{1}{T_{25}}}[K]$$

$$T_{25} = 298.15[K]$$

$beta$	Constant (temperature coefficient) optimized for the operating range of the motor
R_{25}	Nominal resistance at standard temperature T_{25}
T_{25}	Standard temperature of 25 °C (298.15 K)

4 MAINTENANCE

4.1 Periodic Inspection

The «EC frameless DT» as a whole and its individual parts are maintenance-free.

Outer body, motor shaft, and bearings are customer-made parts. For their maintenance and repair consult the relevant instructions. Thereby observe the following:

If you perform maintenance on outer body, motor shaft, and bearings:

- Before you start: Be aware of the necessary safety precautions (➔page 7) and strictly follow the general rules (➔page 14).
- Verify the correct position of the motor before re-commissioning.

4.2 Storage

Observe all safety aspects (➔“About the safety precautions” auf Seite 1-7) and the stated environmental conditions (➔“Technical Data” auf Seite 2-9).

Physically separate the storage location to prevent all persons who possibly may suffer impairment caused by strong magnetic fields from approaching the device and force them to stay clear in a safe distance of at least two (2) meters. Put up warning signs stating STRONG MAGNETIC FIELDS.

4.3 Decommissioning & Dismantling

Dismantling follows basically the Installation in reverse order (➔Kapitel “3.2 Design Guidelines” auf Seite 3-15). Be aware of the necessary safety precautions (➔page 7) and strictly follow the general rules (➔page 14).

4.4 Disposal

In no case dispose used components with normal domestic waste.

Dispose used components only via official collection sites or a certified recycling company. Draw to attention that the high magnetic forces produced by the device constitute an imminent hazard to persons wearing a cardiac pacemaker or metal implants.

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maxon

DECLARATION OF INCORPORATION

Declaration of Incorporation of partly completed Machinery according to EU Directive 2006/42/EC, Annex II 1B.

Manufacturer	maxon motor ag Brünigstrasse 220 CH-6072 Sachseln Switzerland	
Authorized representative to compile the relevant technical documentation	maxon motor ag Brünigstrasse 220 CH-6072 Sachseln Switzerland	
Product	EC frameless DT	Direct current electric motor, comprising stator, rotor, and connector cables

The manufacturer declares that the aforementioned product is considered partly completed machinery complying with all essential requirements of EC Directive 2006/42/EC (Directive on Machinery). It is intended, exclusively, to be incorporated into machinery or partly completed machinery and therefore does not yet meet all requirements of the Directive on Machinery.

Applied harmonized standards: EN ISO 12100:2010

The special technical documentation according to Annex VII, Part B has been prepared and will be made available to the national authorities at their request.

The product must not be put into service until the machinery into which the aforementioned product is to be incorporated has been declared in conformity with the provisions of the Directive on Machinery.

Sachseln, December 17, 2021, on behalf of the manufacturer

Daniel von Wyl
Managing Director maxon motor ag

Dominik Stockmann
Director R&D Motors & Encod

LIST OF FIGURES

LIST OF TABLES

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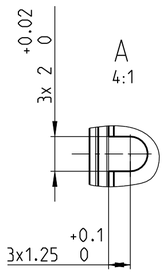
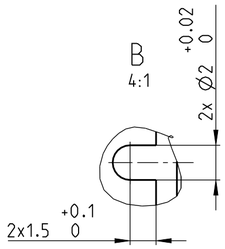
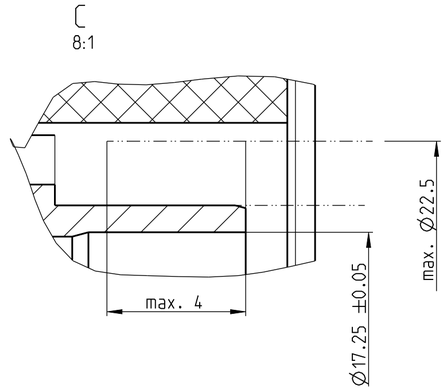
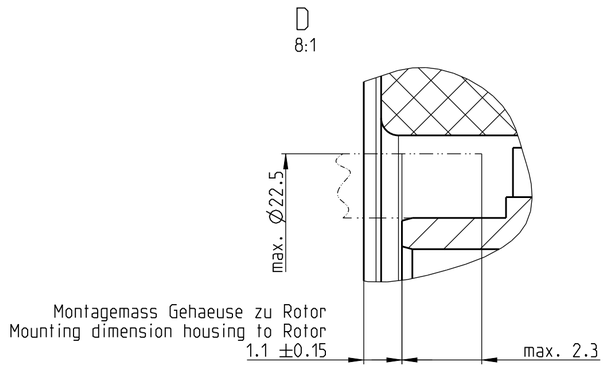
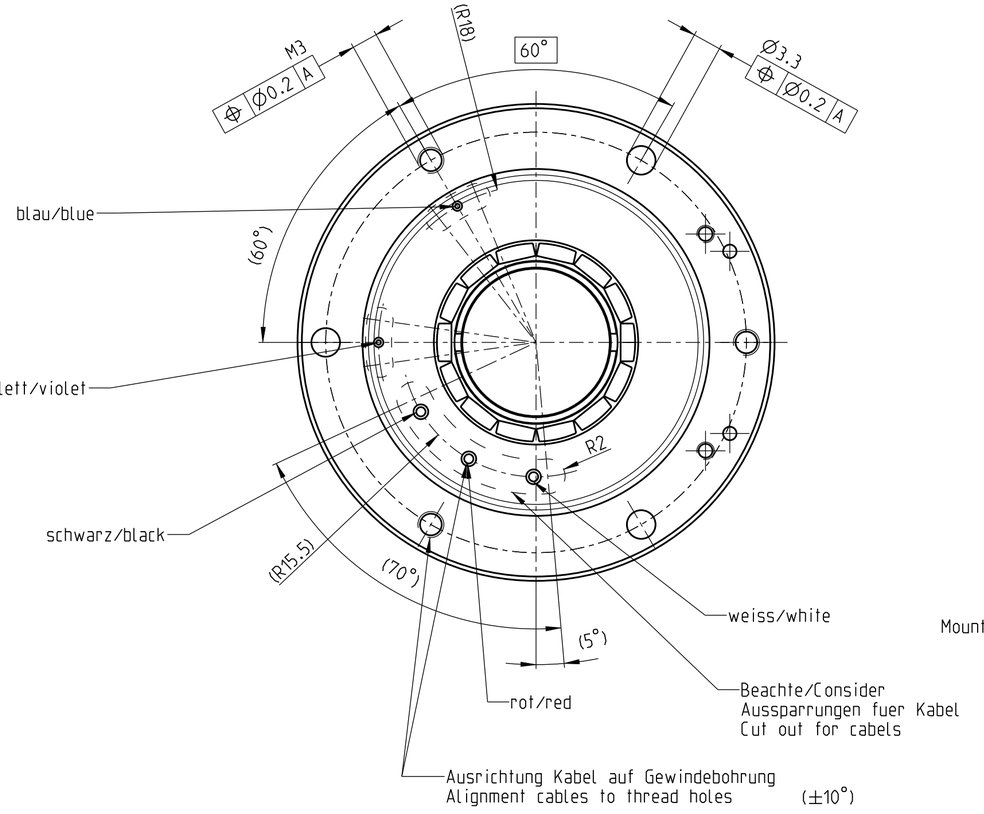
APPENDIX

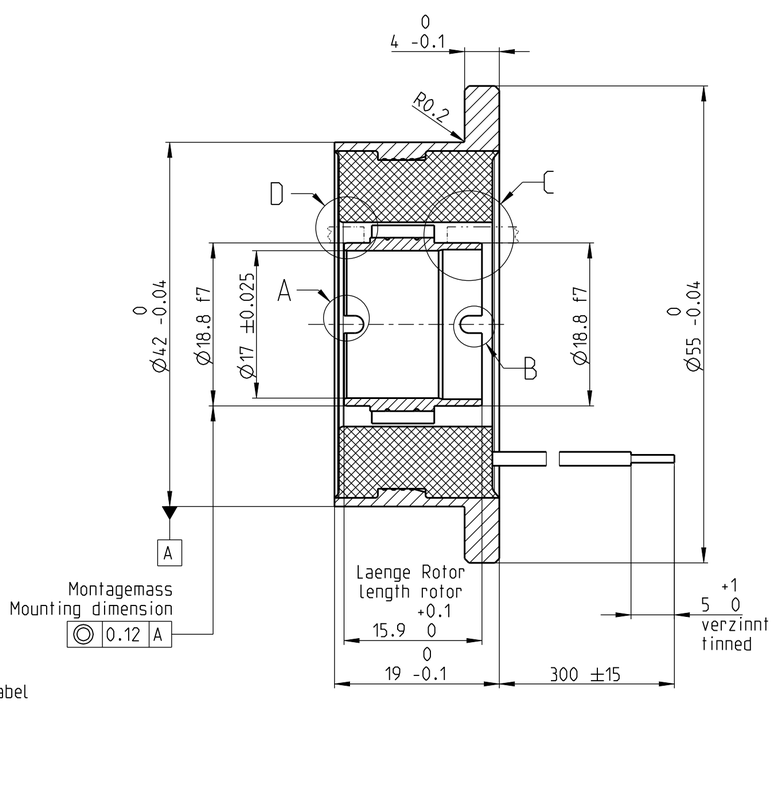


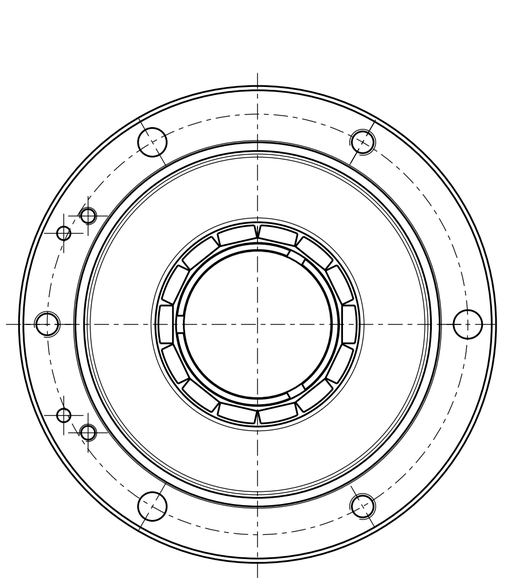


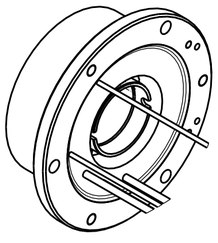












Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel weiss cable white	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= Wicklung 4 = winding 4
AWG24	Kabel blau cable blue	= Wicklung 5 = winding 5

Rotor und Stator werden getrennt angeliefert
Rotor and Stator delivered seperated

	EC frameless DT38S						
PART NUMBER	FINISHED PRODUCT				BASIC NUMBER		
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A	
ISO 8015	ISO 2768:1989-m	ISO 965-1	N/A	ISO 1302:2002	N/A	N/A	
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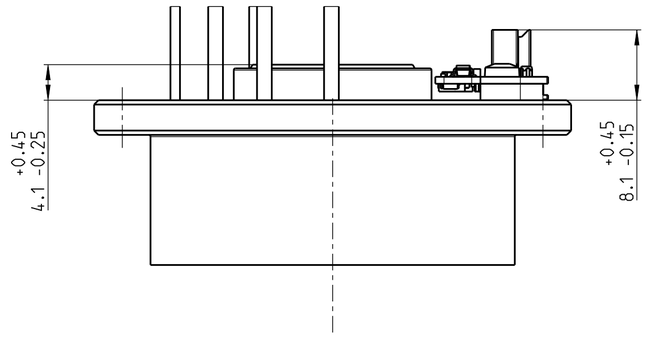
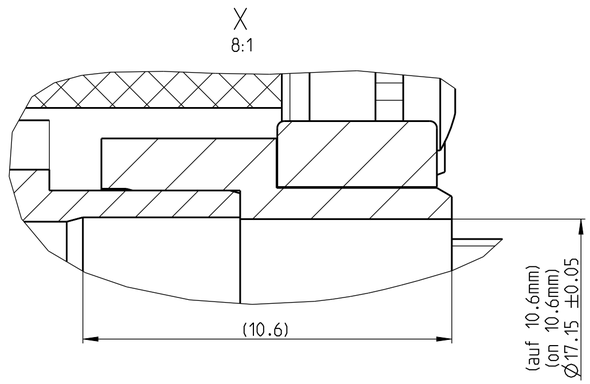
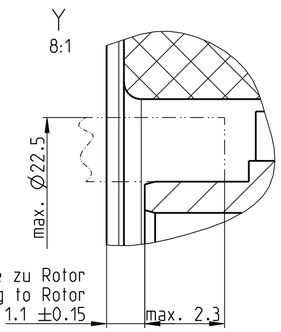
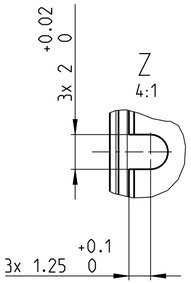
			MODIFIED	06.09.2023	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1
			RELEASED	06.09.2023	MMAGSATH		
PART NUMBER	PART REVISION	DOCUMENT NUMBER: 9757281				DOC REVISION: 05	
maxon		www.maxongroup.com					

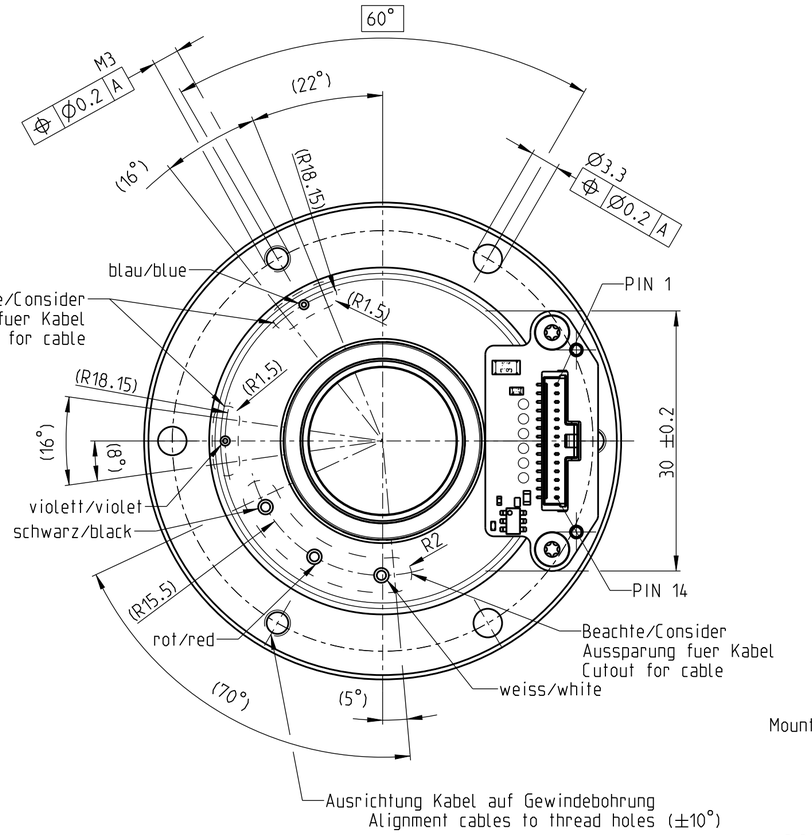


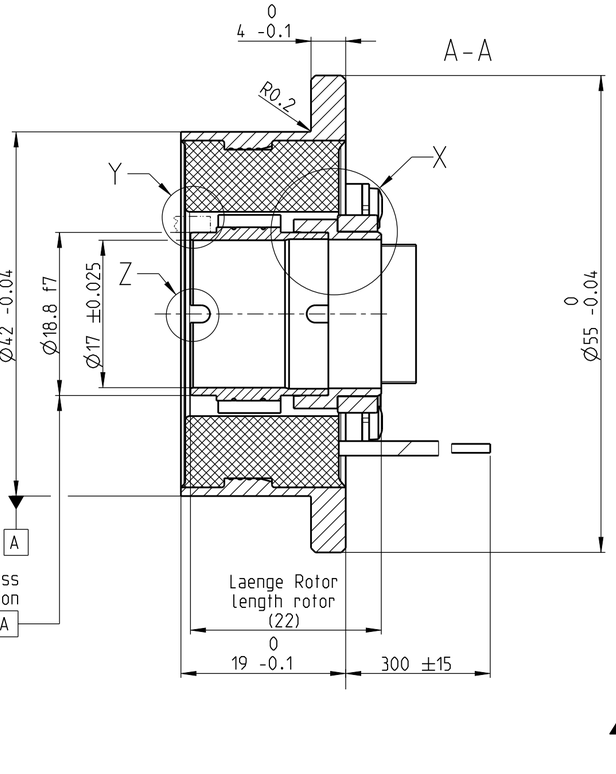


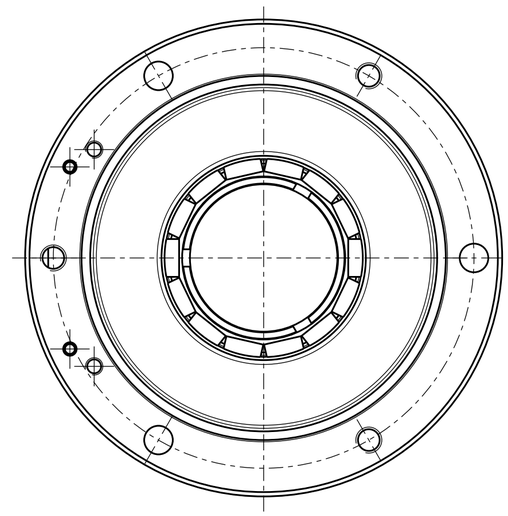


Montagemass Gehaeuse zu Rotor
Mounting dimension housing to Rotor
1.1 ±0.15
max. 2.3









Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
PIN 8	N.C.
PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-

Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
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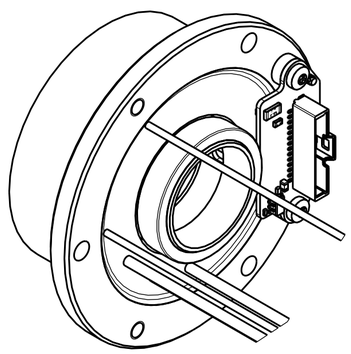
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blau	= NTC out

3:2



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

	maxon tacho ENC TSC MAG						
	maxon motor EC frameless DT38S						
PART NUMBER	FINISHED PRODUCT					BASIC NUMBER	
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A	
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	ISO 1302:2002	N/A	N/A	
DOCUMENT TYPE	Dimensional Drawing	CO-NO: A100031350	DATE	NAME	SCALE	2:1	3D MODEL
TITLE		CREATED	04.04.2023	mmagsath	SHEETS	A2/1/1	9757098
EC frameless DT38S + TSX MAG (axial)		MODIFIED	17.11.2023	MMAGRENI	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	17.11.2023	MMAGMUAG	mm	ISO 5456-1	
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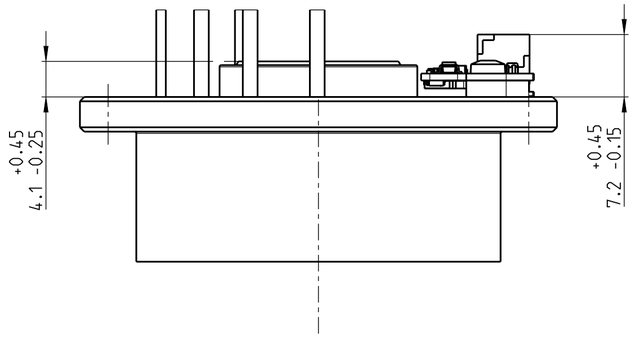
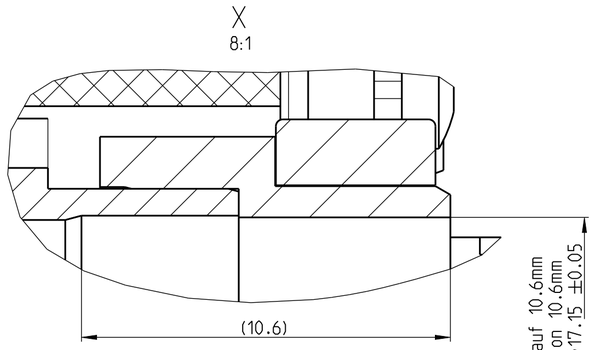
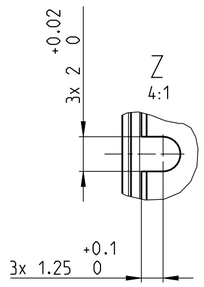
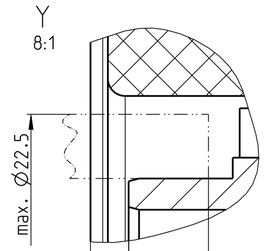
maxon		www.maxongroup.com					

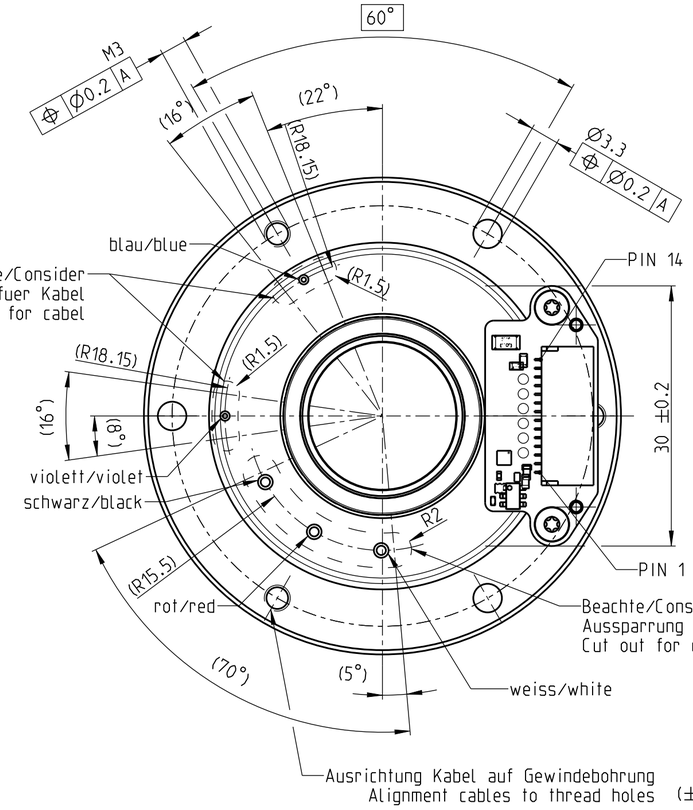


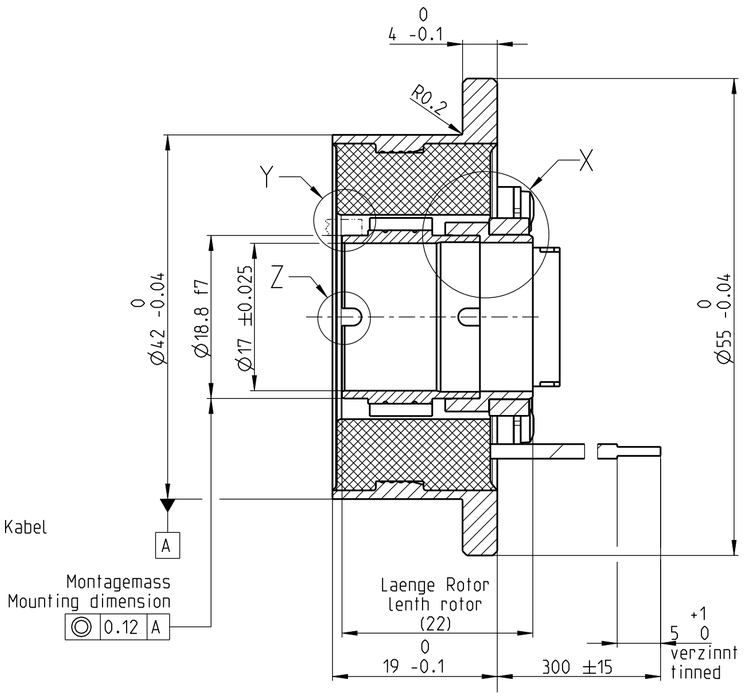


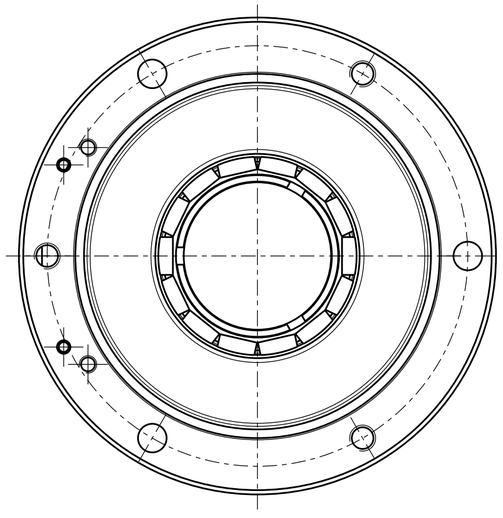




Montagemass Gehaeuse zu Rotor
Mounting dimension housing to Rotor
1.1 ±0.15
max. 2.3







Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
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PIN 8	N.C.
PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
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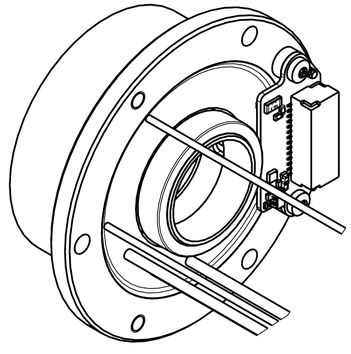
AWG18	Kabel weiss cable white	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

3:2



ACHTUNG / ATTENTION

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	maxon motor EC frameless DT38S						
PART NUMBER	FINISHED PRODUCT					BASIC NUMBER	
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A	
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	ISO 1302:2002	N/A	N/A	
DOCUMENT TYPE	Dimensional Drawing		CO-NO: A100031350	DATE	NAME	SCALE	2:1	3D MODEL
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EC frameless DT38S + TSX MAG (radial)			MODIFIED	17.11.2023	MMAGRENI	DIMENSION UNITS	PROJECTION METHOD	
			RELEASED	17.11.2023	MMAGMUAG	mm	ISO 5456-1	
PART NUMBER	PART REVISION	DOCUMENT NUMBER					DOC REVISION
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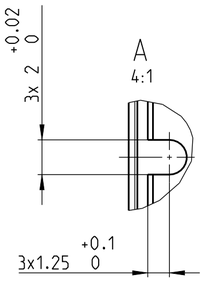
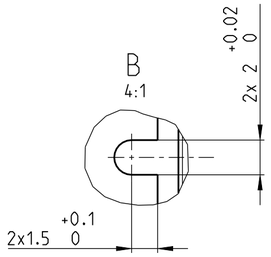
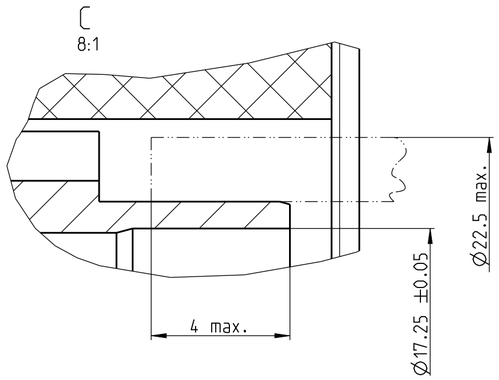
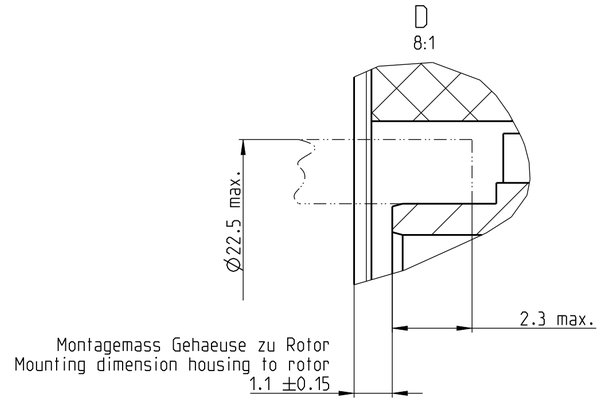
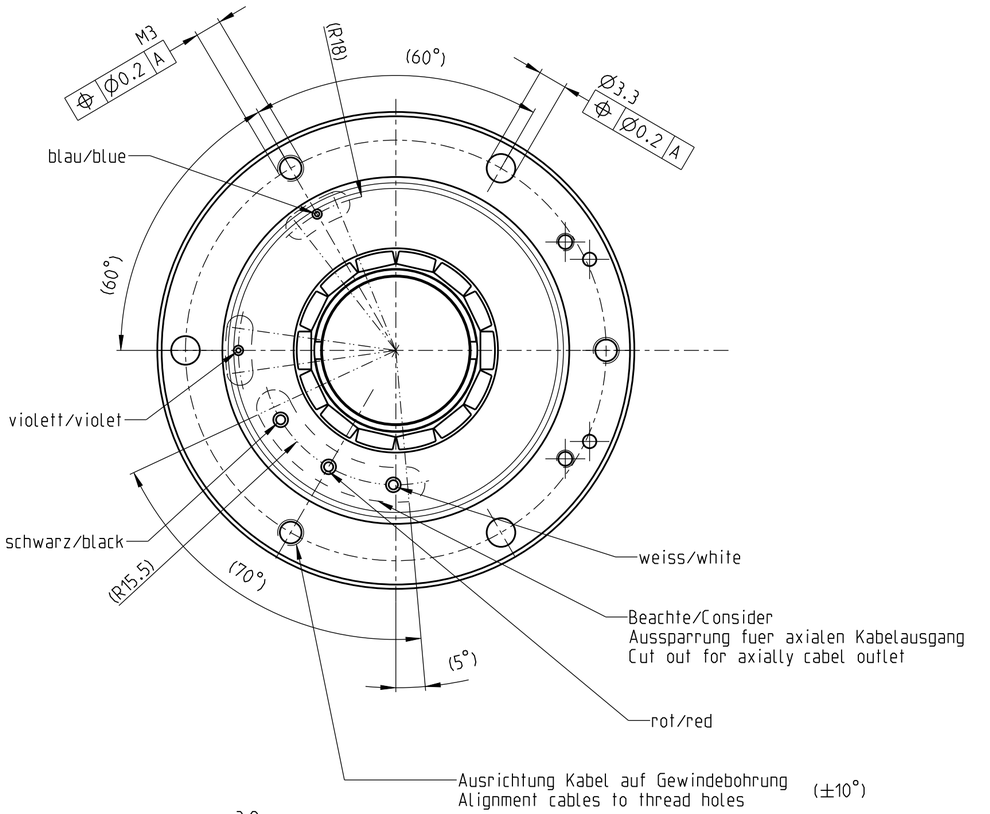
maxon		www.maxongroup.com					

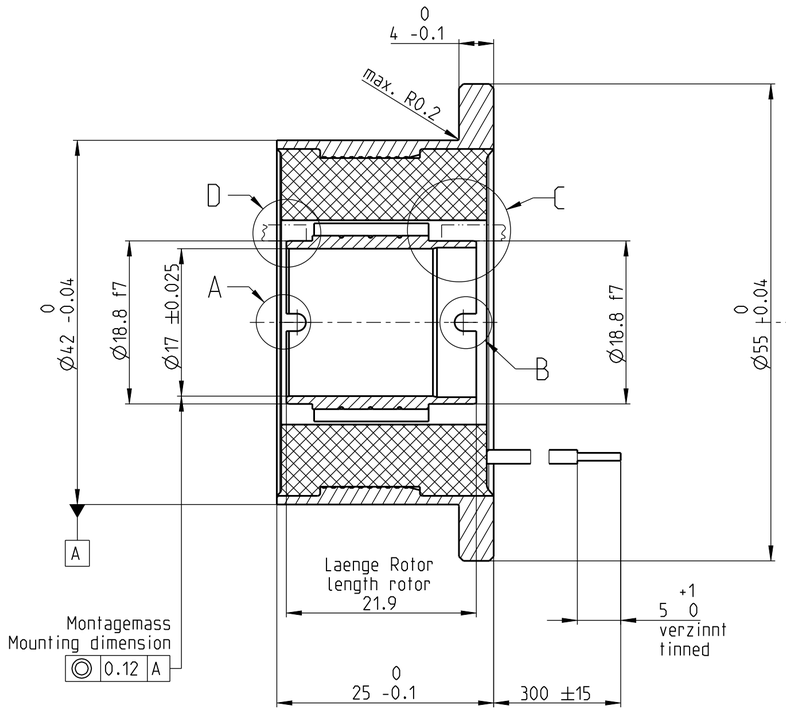


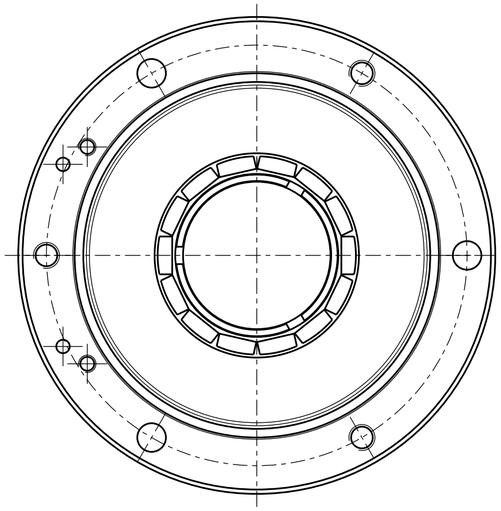












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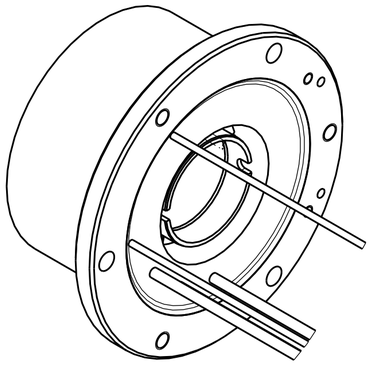

Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel weiss cable white	= Wicklung 3 = winding 3
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AWG24	Kabel blau cable blue	= NTC out

Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

	EC frameless DT38M							
PART NUMBER	FINISHED PRODUCT					BASIC NUMBER		
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES		EDGES	N/A N/A	
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	N/A		N/A	N/A	
DOCUMENT TYPE	Dimensional Drawing		CO-NO: A100030968	DATE	NAME	SCALE	2:1	3D MODEL
TITLE			CREATED	15.09.2022	MMAGMRHI	SHEETS	A2/1/1	9488995
EC frameless DT38M			MODIFIED	07.09.2023	MMAGRENI	DIMENSION UNITS	PROJECTION METHOD	
			RELEASED	07.09.2023	MMAGMUAG	mm	ISO 5456-1	
PART NUMBER		PART REVISION	DOCUMENT NUMBER					DOC REVISION
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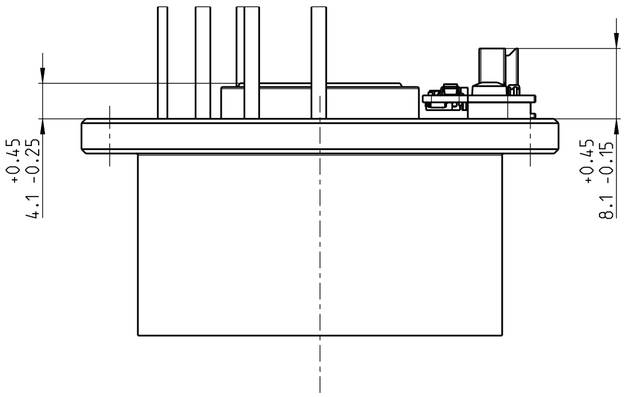
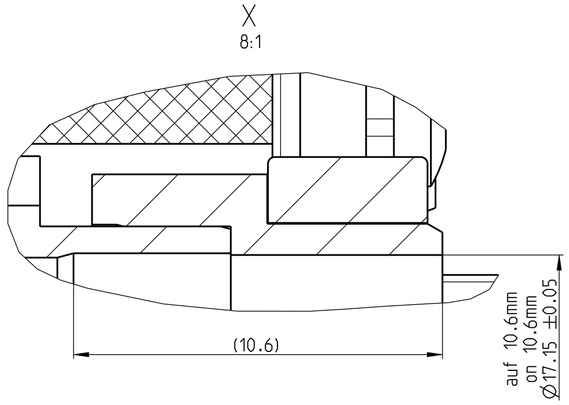
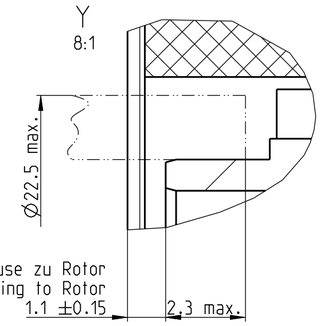
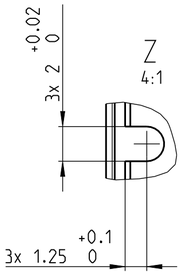
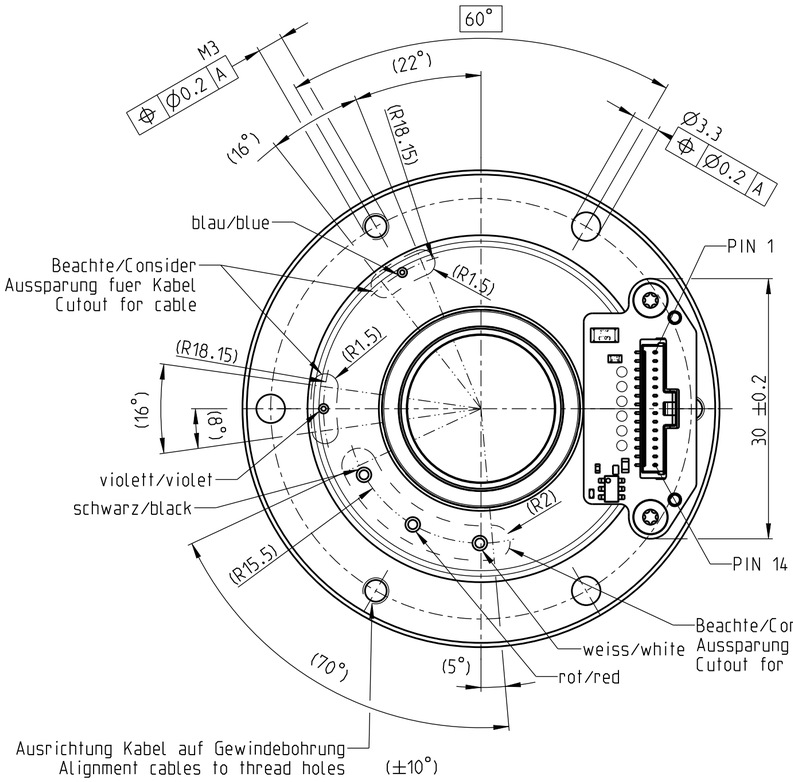
maxon			www.maxongroup.com					

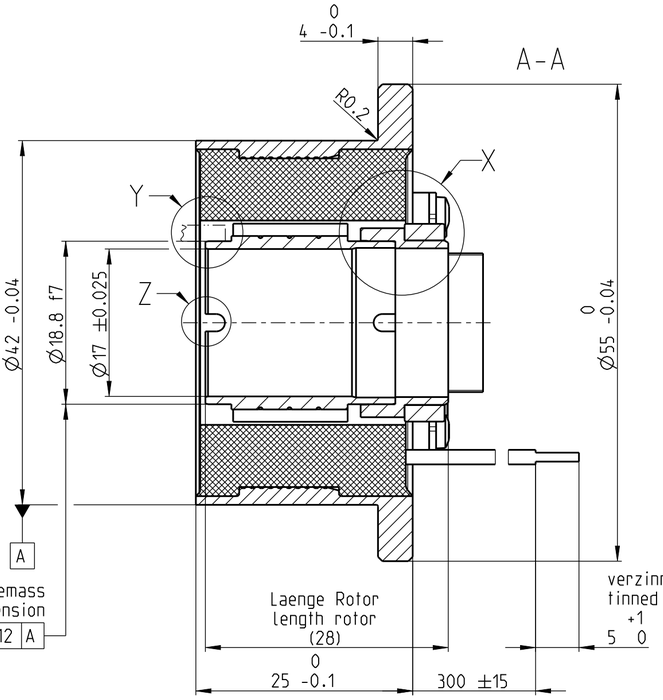


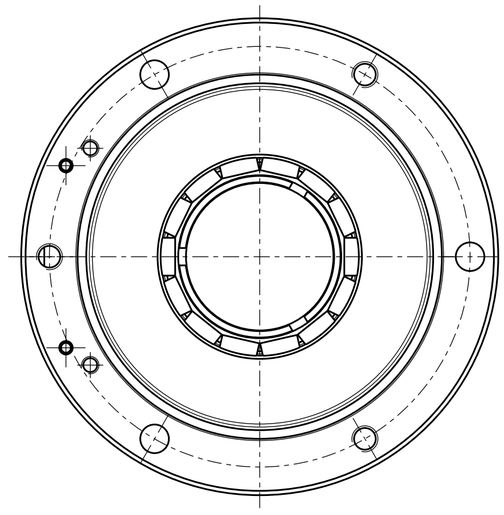












Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
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PIN 7	N.C.
PIN 6	H1
PIN 5	H2
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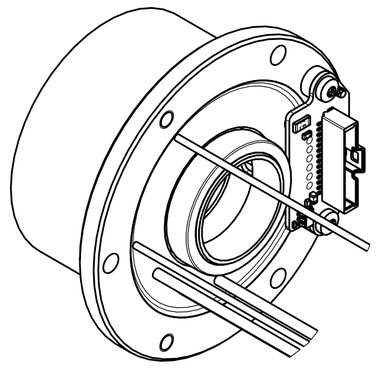
AWG24	Kabel blau cable blue	= NTC out

3:2



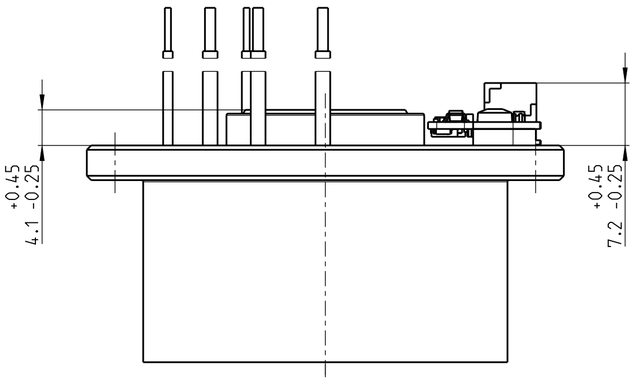
ACHTUNG / ATTENTION

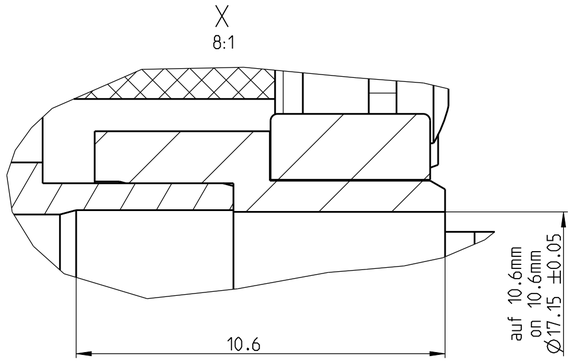
Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

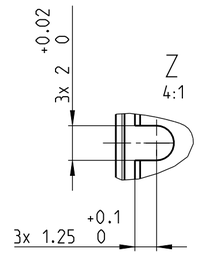
Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

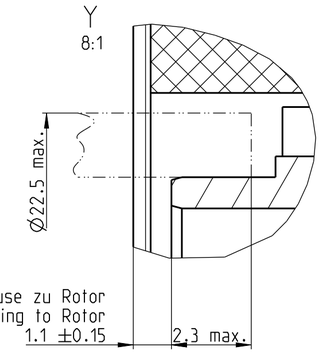
Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

	maxon tacho ENC TSC MAG							
	maxon motor EC frameless DT38M							
PART NUMBER	FINISHED PRODUCT						BASIC NUMBER	
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A		
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	N/A	N/A	N/A		
DOCUMENT TYPE	Dimensional Drawing		CO-NO: A100031350	DATE	NAME	SCALE	2:1	3D MODEL
TITLE				CREATED	24.11.2022	mmagsath	SHEETS	A2/1/1	9488995
EC frameless DT38M + TSX MAG (axial)				MODIFIED	17.11.2023	MMAGRENI	DIMENSION UNITS	PROJECTION METHOD
				RELEASED	17.11.2023	MMAGMUAG	mm	ISO 5456-1
PART NUMBER		PART REVISION	DOCUMENT NUMBER					DOC REVISION
			9723273					02
maxon			www.maxongroup.com					

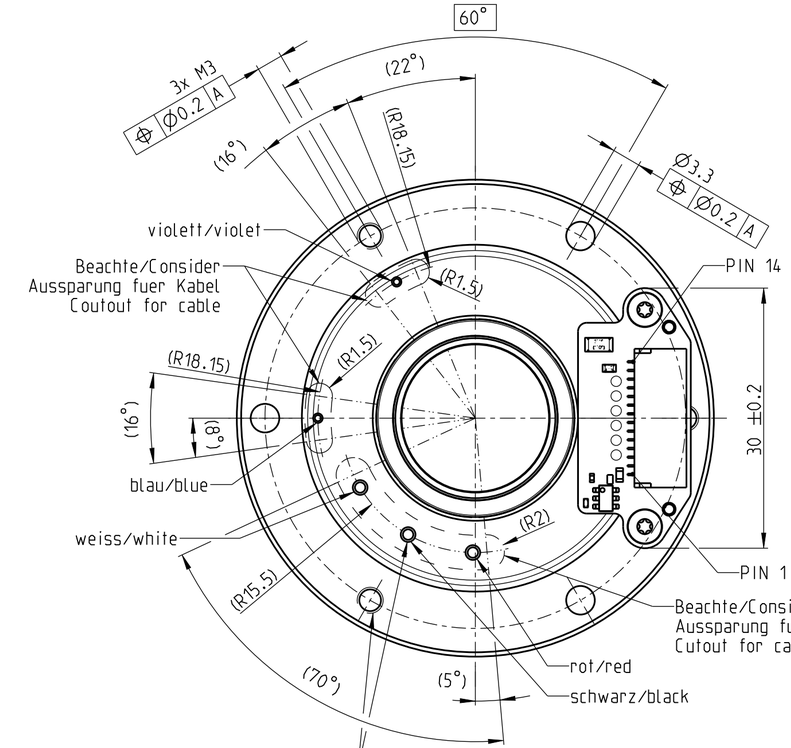


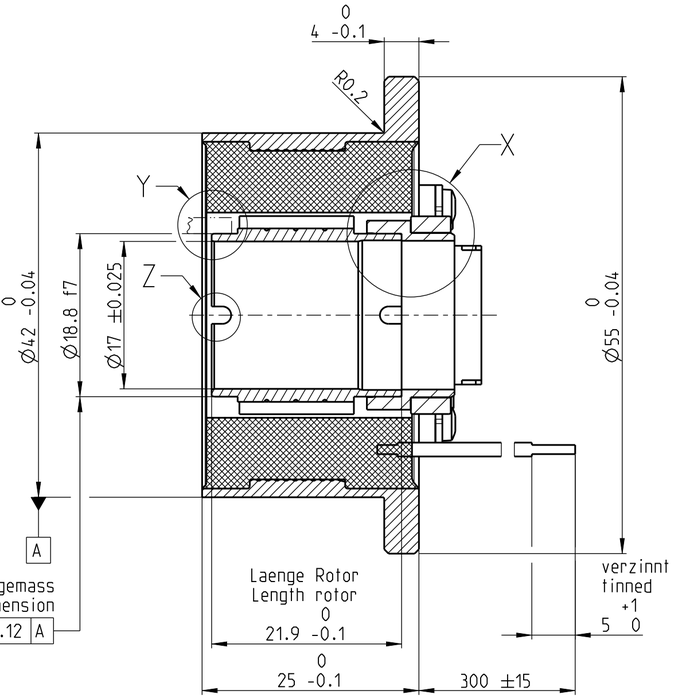


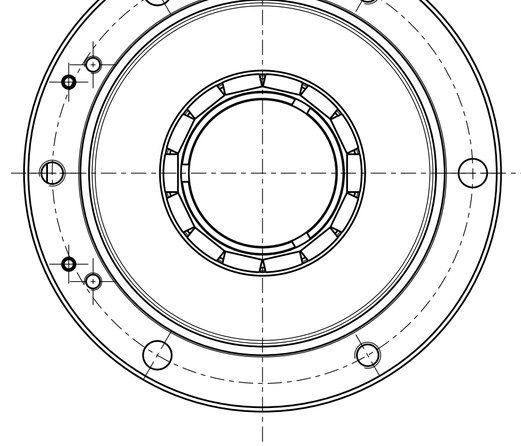




Montagemass Gehaeuse zu Rotor
Mounting dimensions housing to Rotor
1.1 ±0.15 2.3 max.



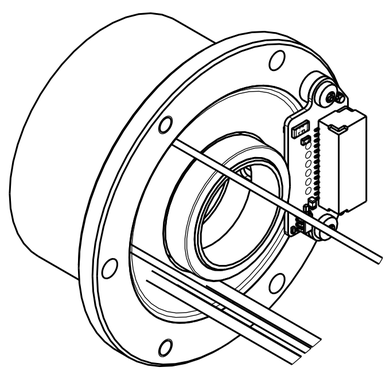




Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
PIN 7	N.C.
PIN 8	N.C.
PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel weiss cable white	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

3:2



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

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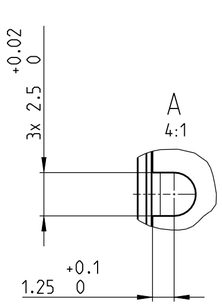
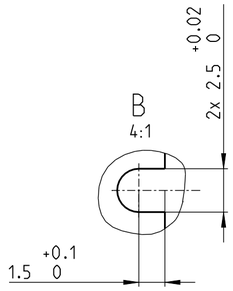
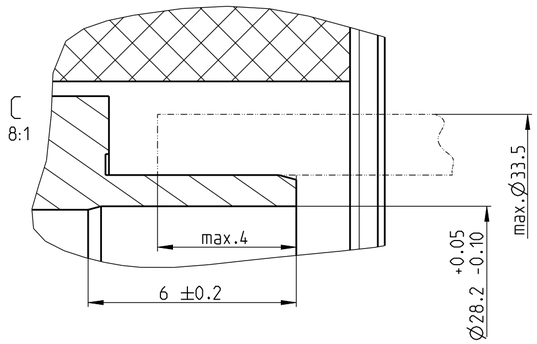
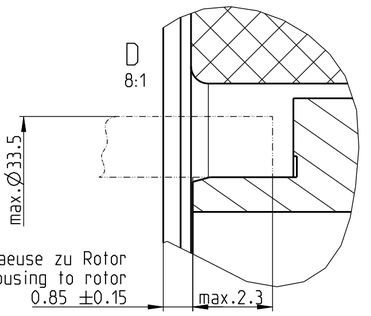
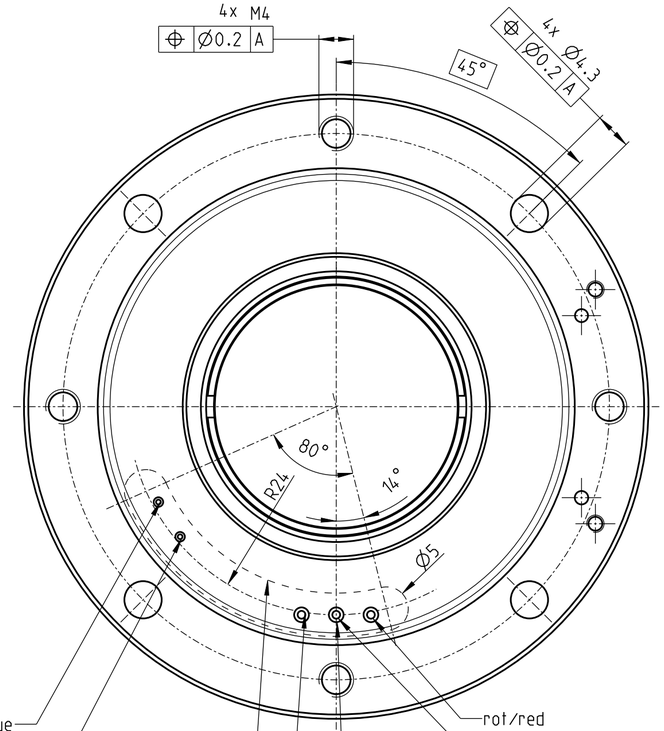
	maxon tacho ENC TSC MAG						
	maxon motor EC frameless DT38M						
PART NUMBER	FINISHED PRODUCT					BASIC NUMBER	
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A	
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A	
DOCUMENT TYPE: Dimensional Drawing			CO-ND: A100027864	DATE	NAME	SCALE: 2:1	3D MODEL
TITLE: EC frameless DT38M + TSX MAG (radial)			CREATED	24.11.2022	mmagsath	SHEETS: A2/1/1	9488995
			MODIFIED	01.06.2023	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1
			RELEASED	01.06.2023	MMAGMUAG		
PART NUMBER		PART REVISION	DOCUMENT NUMBER: 9723262				DOC REVISION: 01
maxon			www.maxongroup.com				

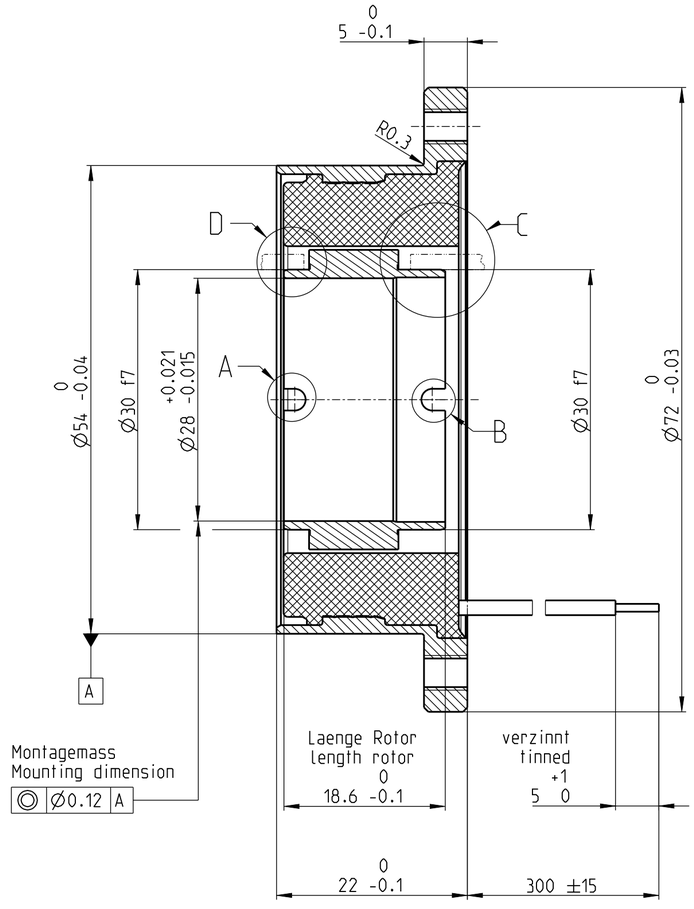


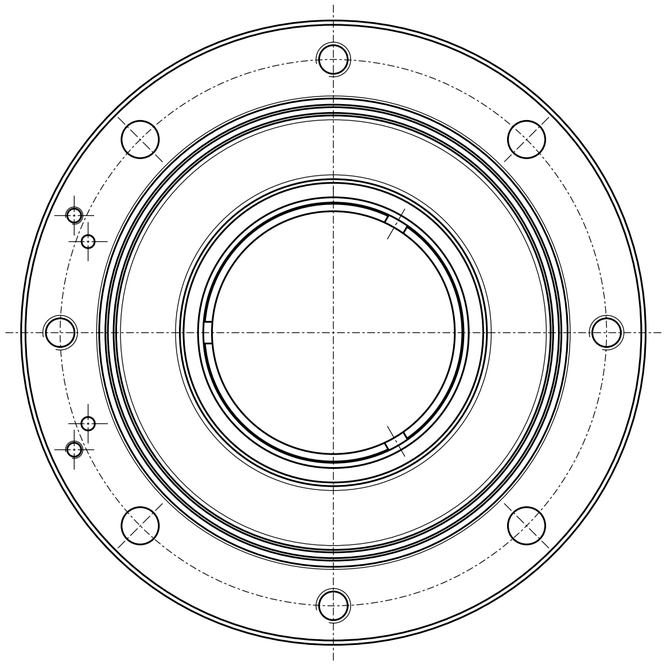












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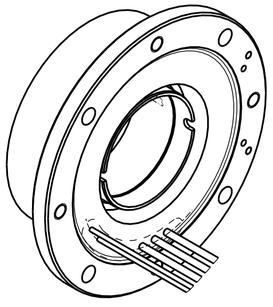


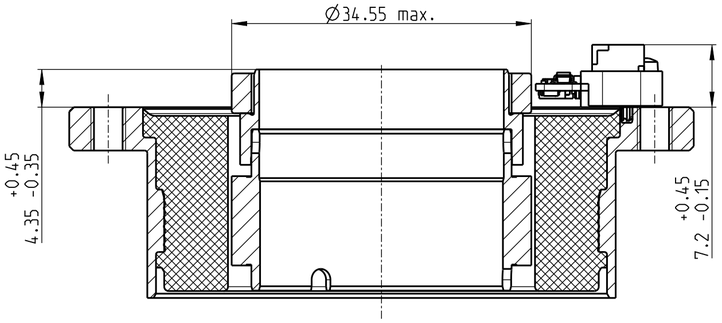
Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel weiss cable white	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

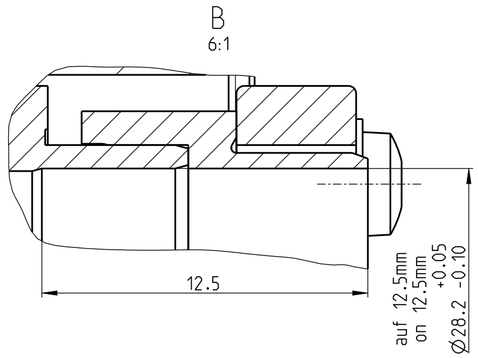
Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

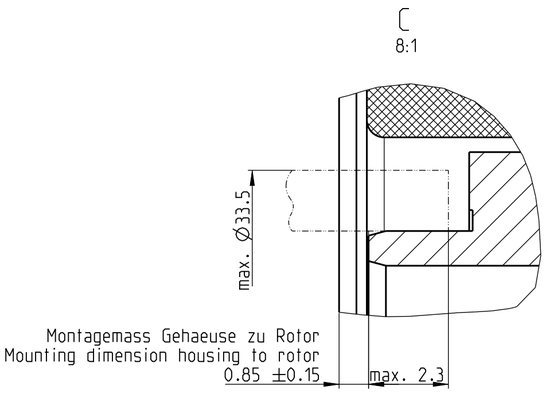
EC frameless DT50S						
Artikel Nr./part no.	Fertigprodukt/finished product					Basis Nr./basic no.
TOLERANCING: ISO 8015	GENERAL TOLERANCES: ISO 2768-m	SCREW THREAD TOLERANCES: ISO 965-1	GEOMETRICAL TOLERANCES: ISO 1101	SURFACES: N/A	EDGES: N/A	N/A N/A

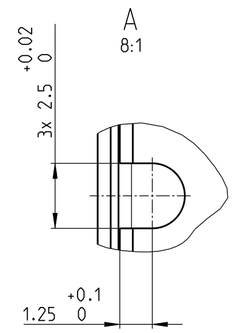
DOCUMENT TYPE: Dimensional Drawing	CO-NO. 19642	DATE	NAME	SCALE	2:1	3D MODEL
TITLE: EC frameless DT50S	CREATED	11.09.2021	MMAGMUAG	SHEETS	A2/1/1	8335060
	MODIFIED	06.04.2022	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1	
	RELEASED	07.04.2022	MMAGROES			

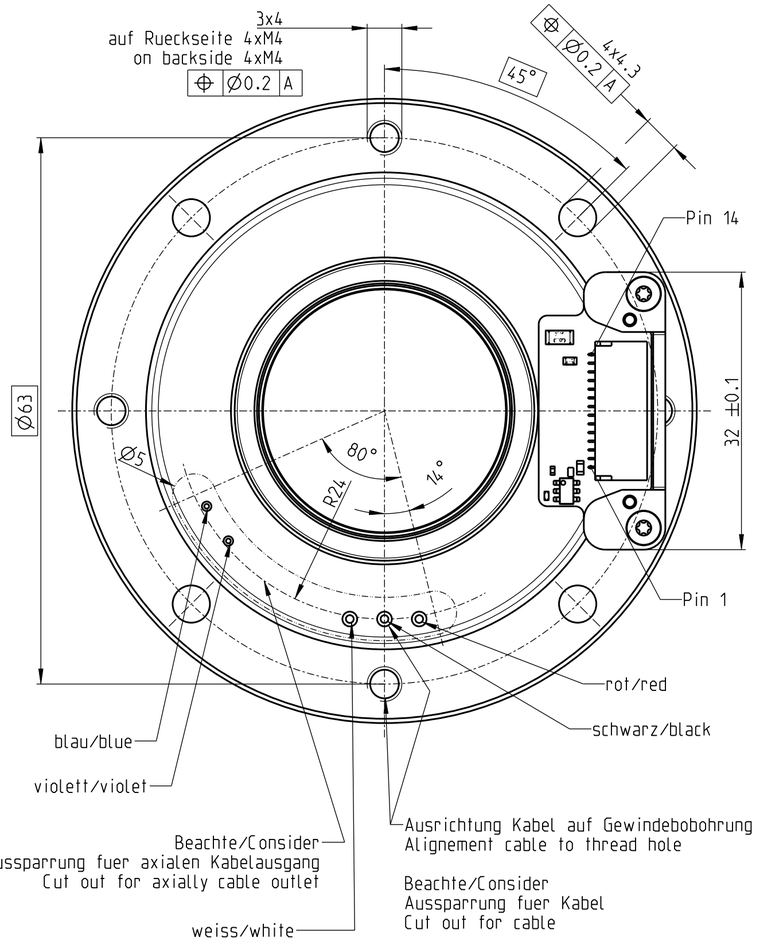
PART NUMBER	PART REVISION	DOCUMENT NUMBER: 8335057	DOC REVISION: 04
maxon		www.maxongroup.com	

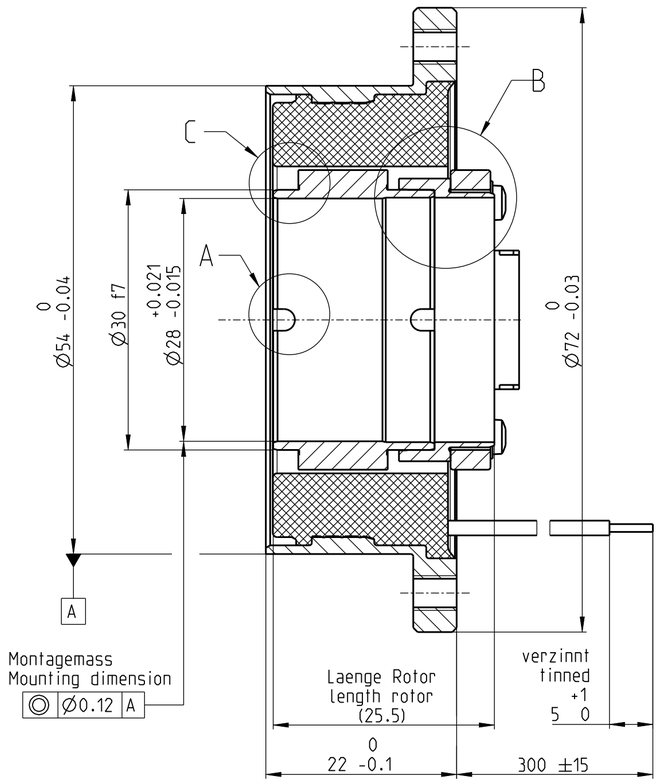


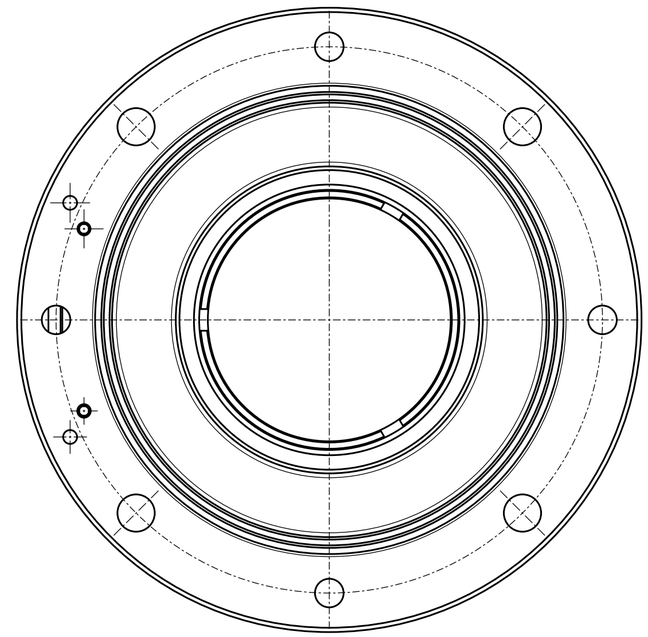












Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
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PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
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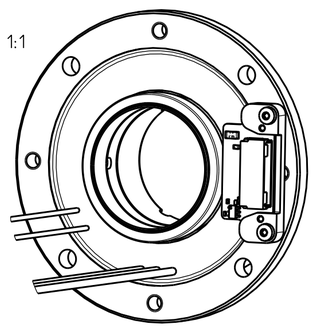
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

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electrostatic sensitive devices

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N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT50S	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE	Assembly Drawing	CO-ND: 119642	DATE	NAME	SCALE	2:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	07.12.2021	MMAGMUAG	SHEETS	A2/1/1	8685003
TITLE DE	Massbild	MODIFIED	06.04.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	07.04.2022	MMAGROES	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8685004	02

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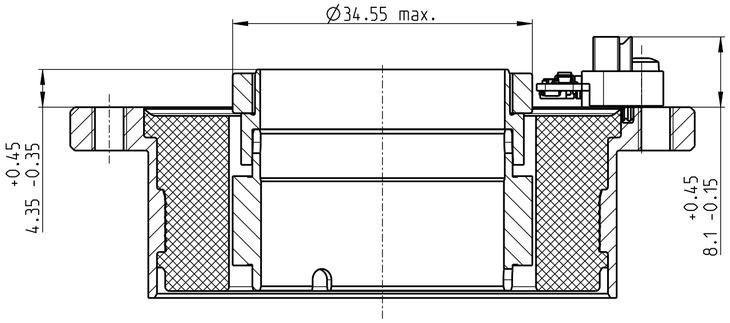

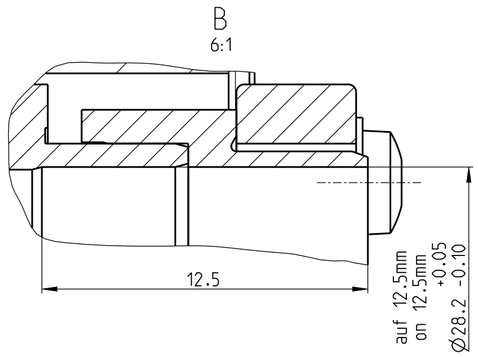

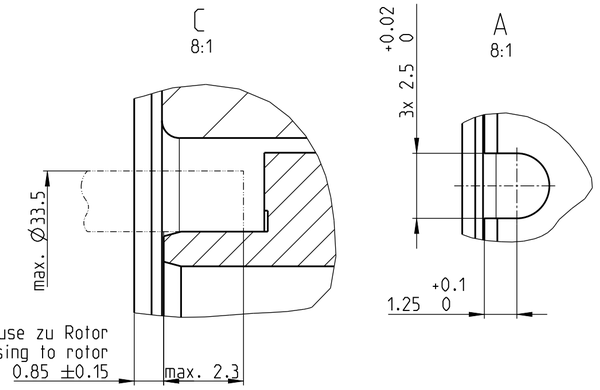

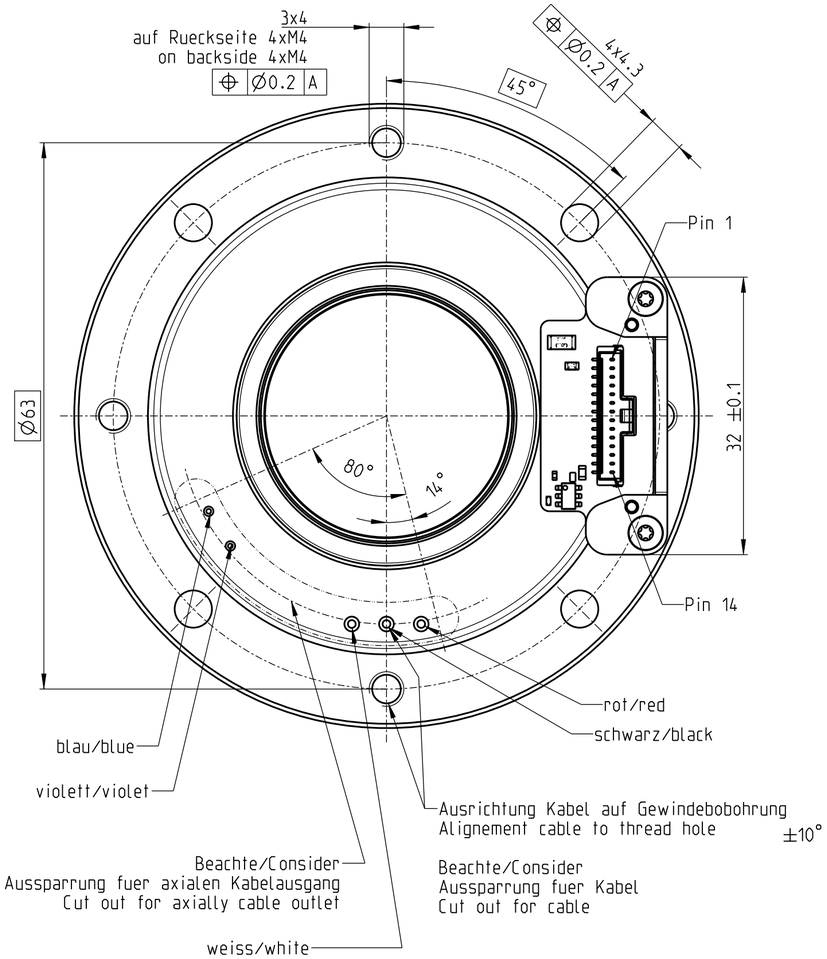

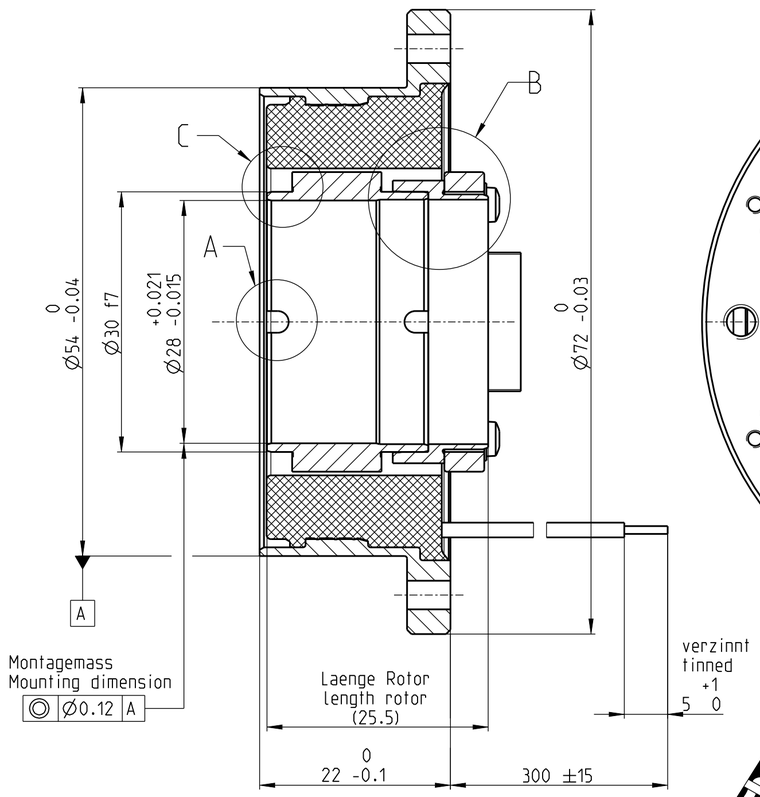

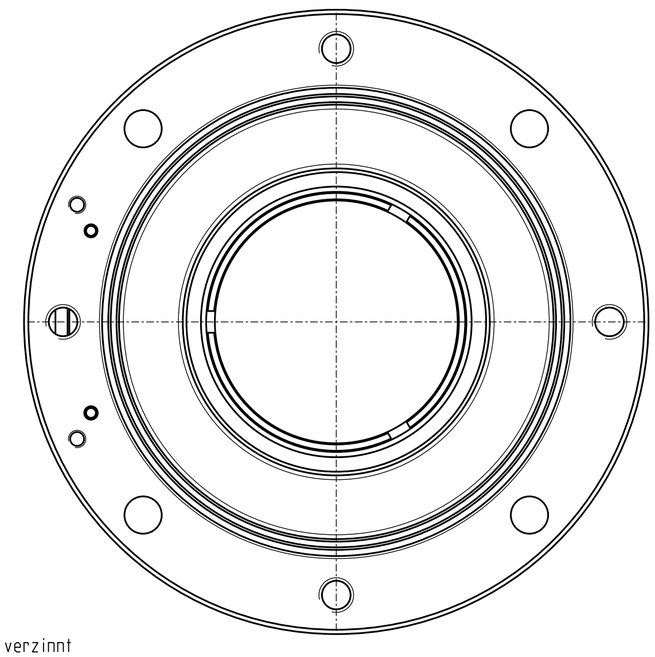

Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
PIN 8	N.C.
PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-

Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
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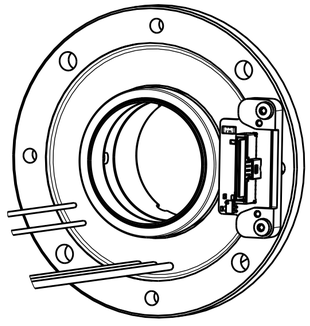
AWG18	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out



ACHTUNG / ATTENTION

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N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT50S	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO. 119642	DATE	NAME	SCALE	2:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	07.12.2021	MMAGMUAG	SHEETS	A2/1/1	8685003
TITLE DE	Massbild	MODIFIED	06.04.2022	MMAGMUAG	DIMENSION UNITS	mm	PROJECTION METHOD ISO 5456-1
		RELEASED	07.04.2022	MMAGROES			
PART NUMBER	PART REVISION	DOCUMENT NUMBER 8685612					DOC REVISION 02

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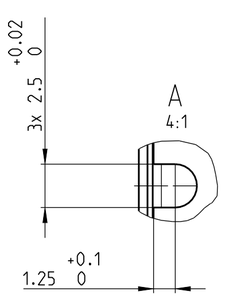

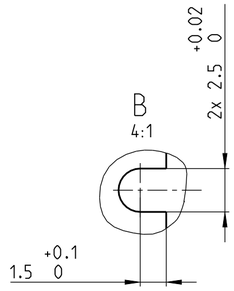

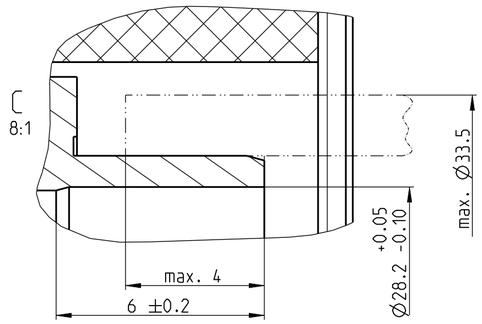

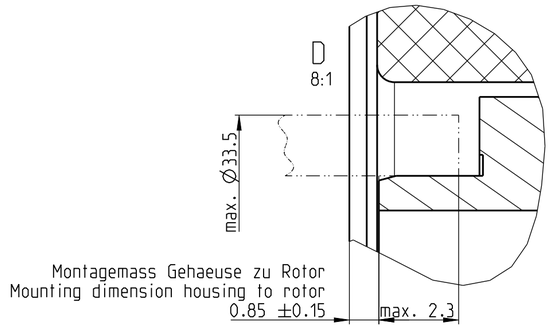

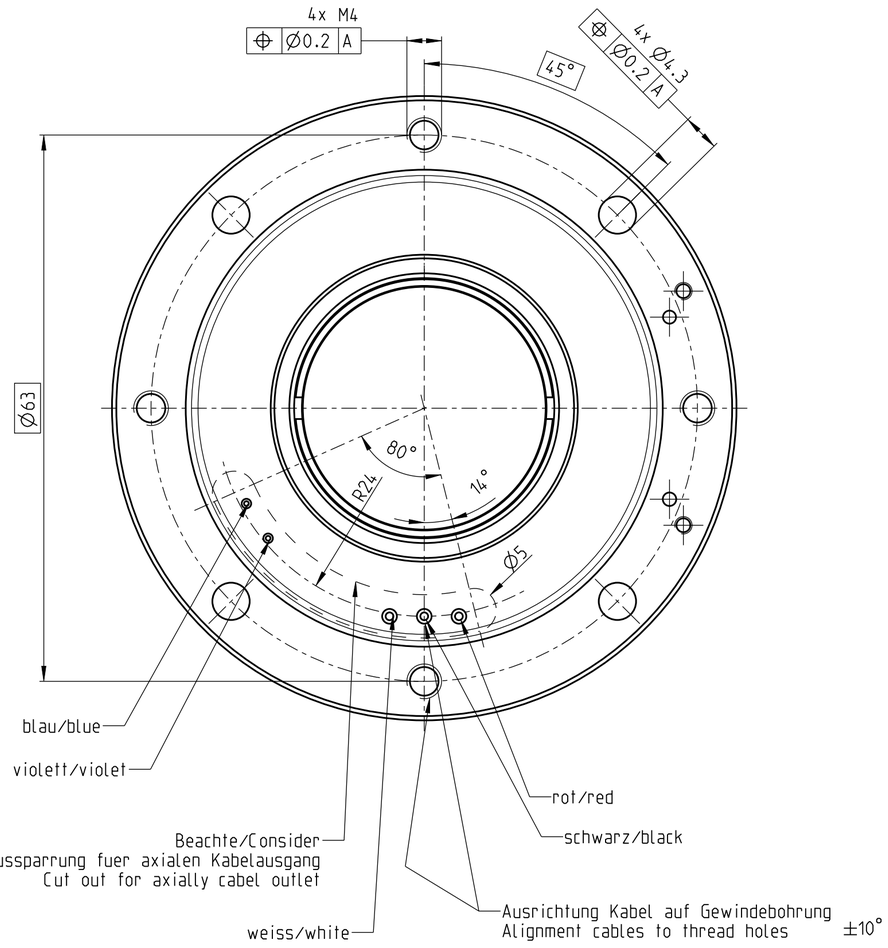

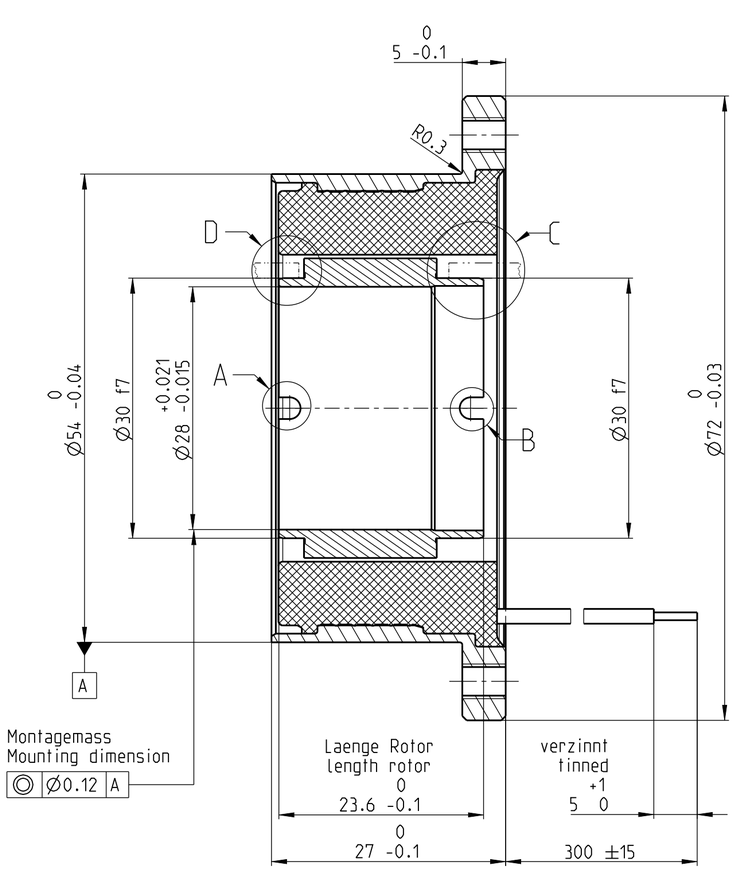

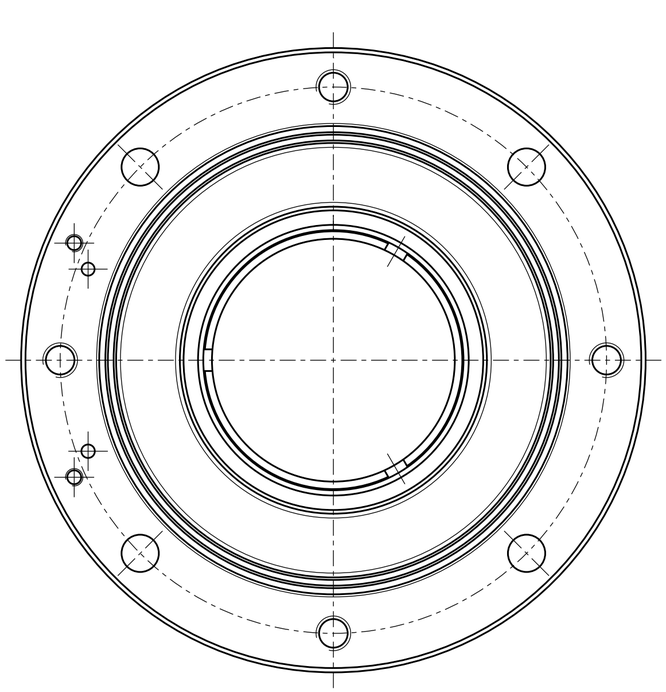

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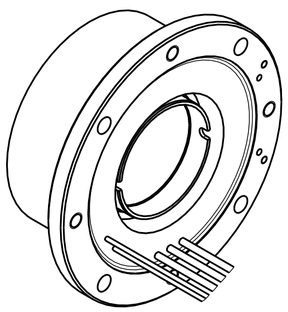
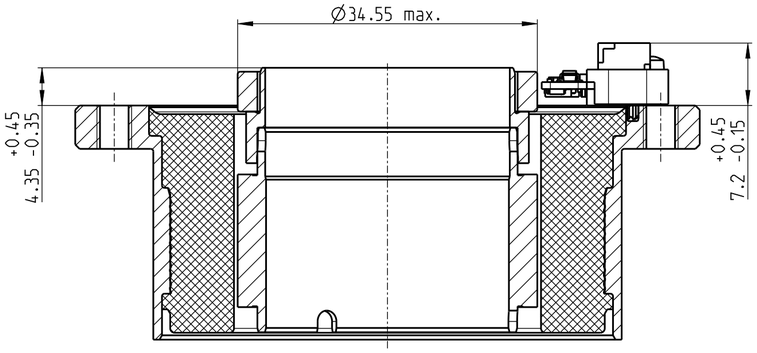
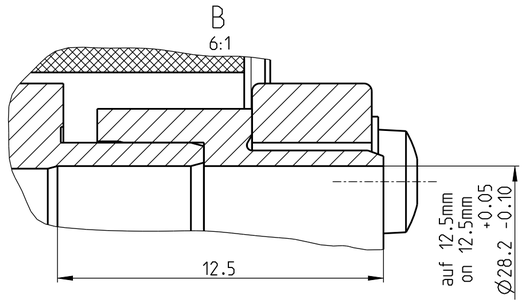


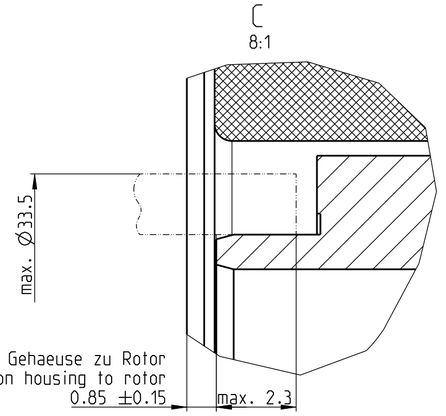
Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel weiss cable white	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

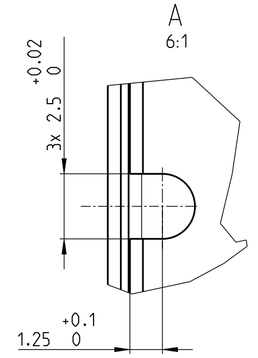
Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

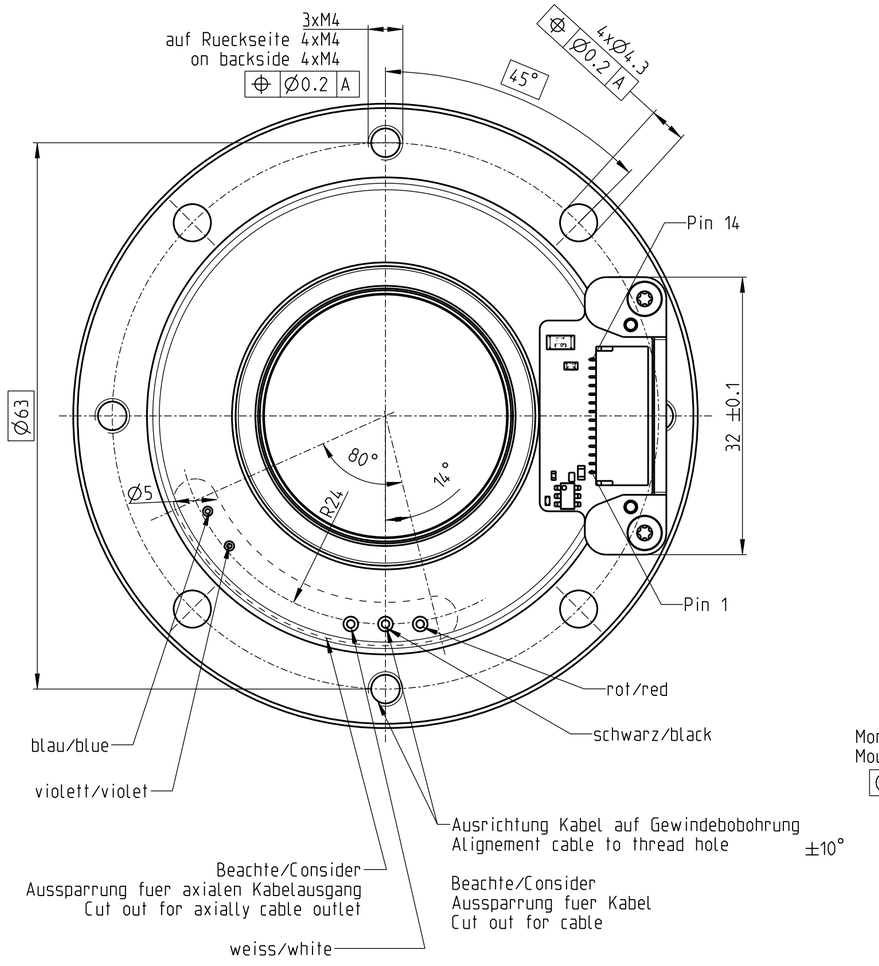
EC frameless DT50M						
Artikel Nr./part no.	Fertigprodukt/finished product					Basis Nr./basic no.
TOLERANCING: ISO 8015	GENERAL TOLERANCES: ISO 2768-m	SCREW THREAD TOLERANCES: ISO 965-1	GEOMETRICAL TOLERANCES: ISO 1101	SURFACES: N/A	EDGES: N/A	N/A N/A
DOCUMENT TYPE: Dimensional Drawing	CO-NO: 119642	DATE	NAME	SCALE: 2:1	3D MODEL	
TITLE: EC frameless DT50M	CREATED	24.08.2021	MMAGMUAG	SHEETS: A2/1/1	8284624	
	MODIFIED	06.04.2022	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1	
PART NUMBER	PART REVISION	RELEASED	07.04.2022	MMAGROES	DOCUMENT NUMBER: 8285347	DOC REVISION: 03
maxon					www.maxongroup.com	

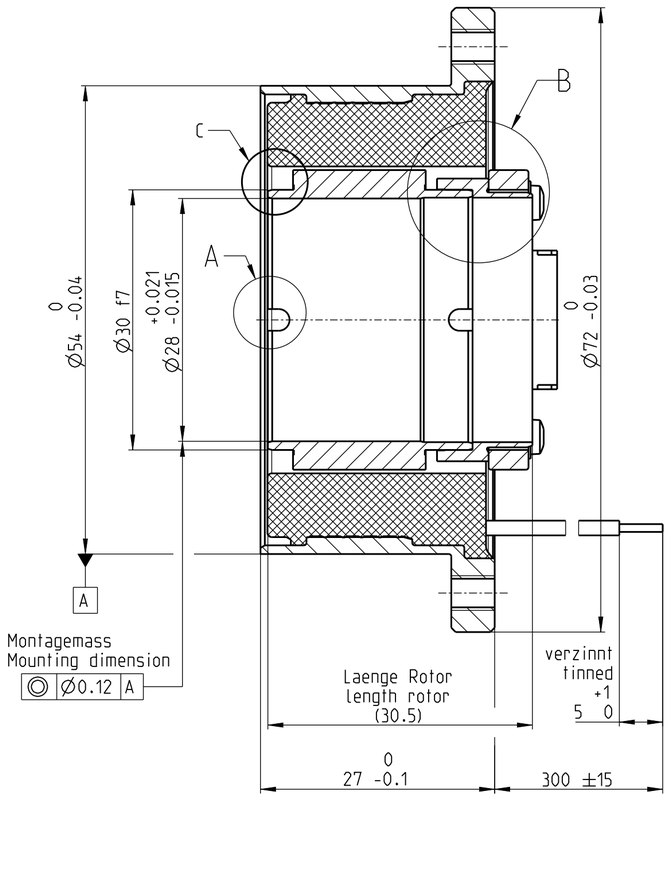


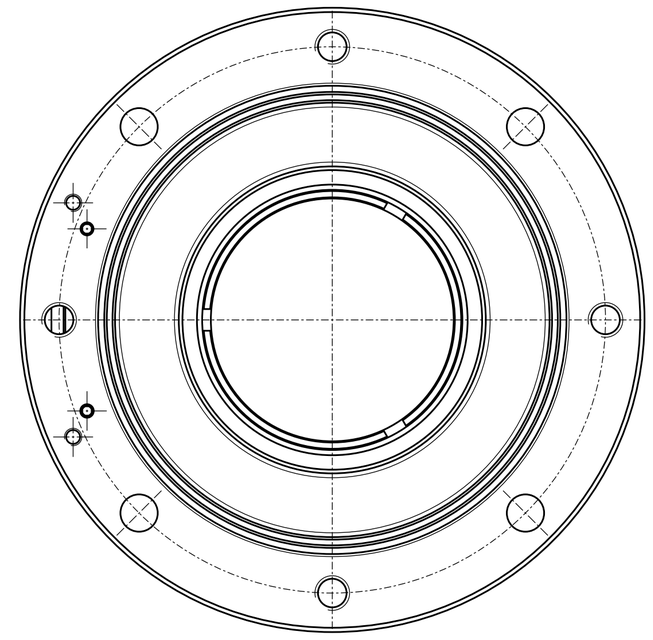








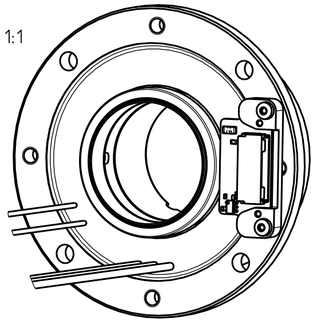




Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
PIN 7	N.C.
PIN 8	N.C.
PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

1:1



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT50M	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO. 119642	DATE	NAME	SCALE	2:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	01.10.2021	MMAGMUAG	SHEETS	A2/1/1	8369329
TITLE DE	Massbild	MODIFIED	06.04.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	07.04.2022	MMAGROES	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8389213	03

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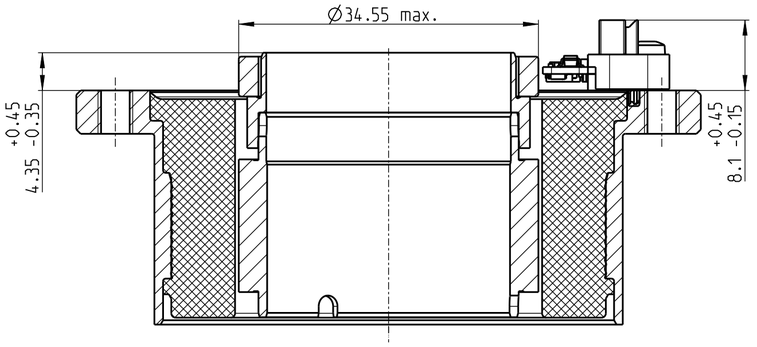

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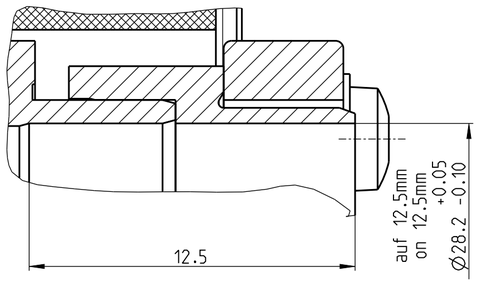

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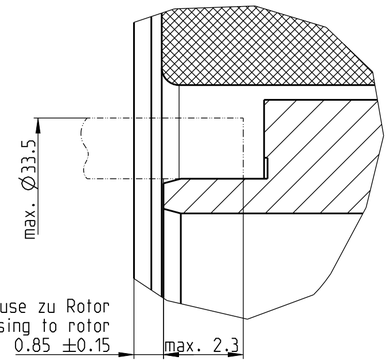

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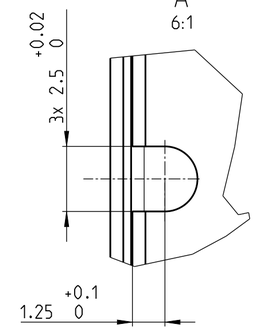
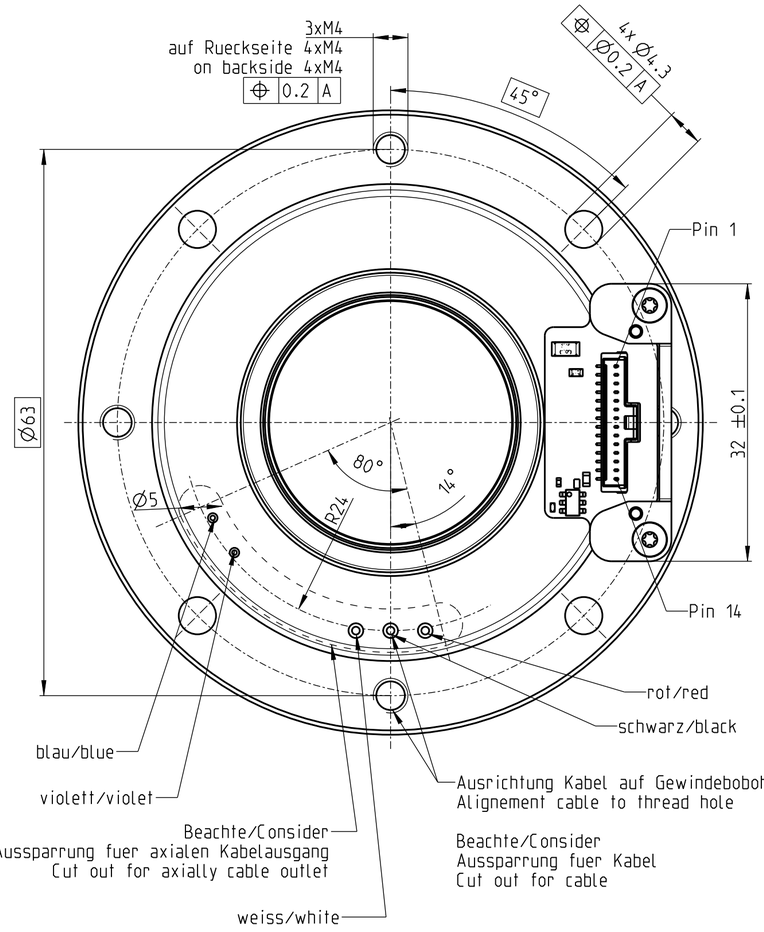
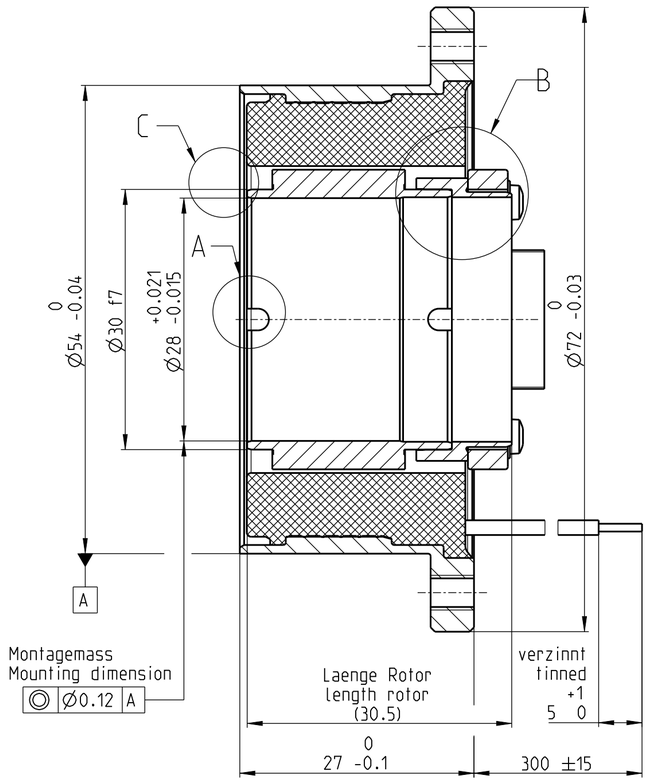
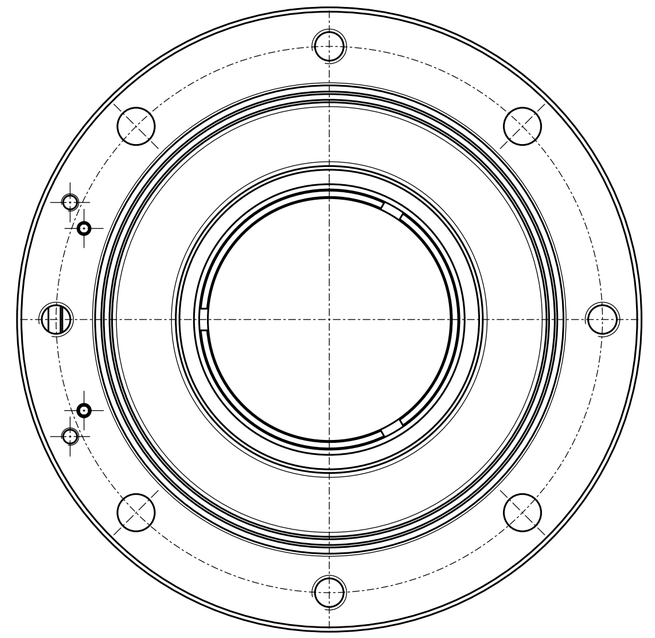




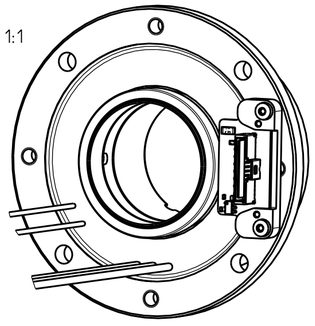




Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
PIN 8	N.C.
PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-

Kabelbelegung/wiring diagram		
AWG18	Kabel rot cable red	= Wicklung 1 = winding 1
AWG18	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG18	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

1:1



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT50M	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO. 119642	DATE	NAME	SCALE	2:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	24.09.2021	MMAGMUAG	SHEETS	A2/1/1	8369329
TITLE DE	Massbild	MODIFIED	07.04.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	07.04.2022	MMAGROES	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8369889	04

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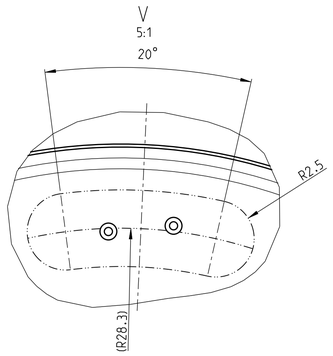
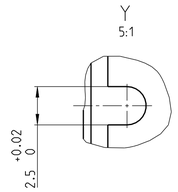
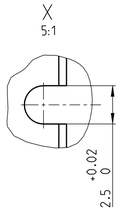
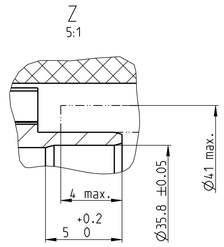
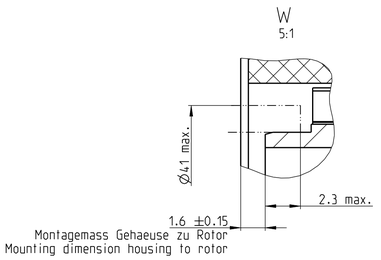
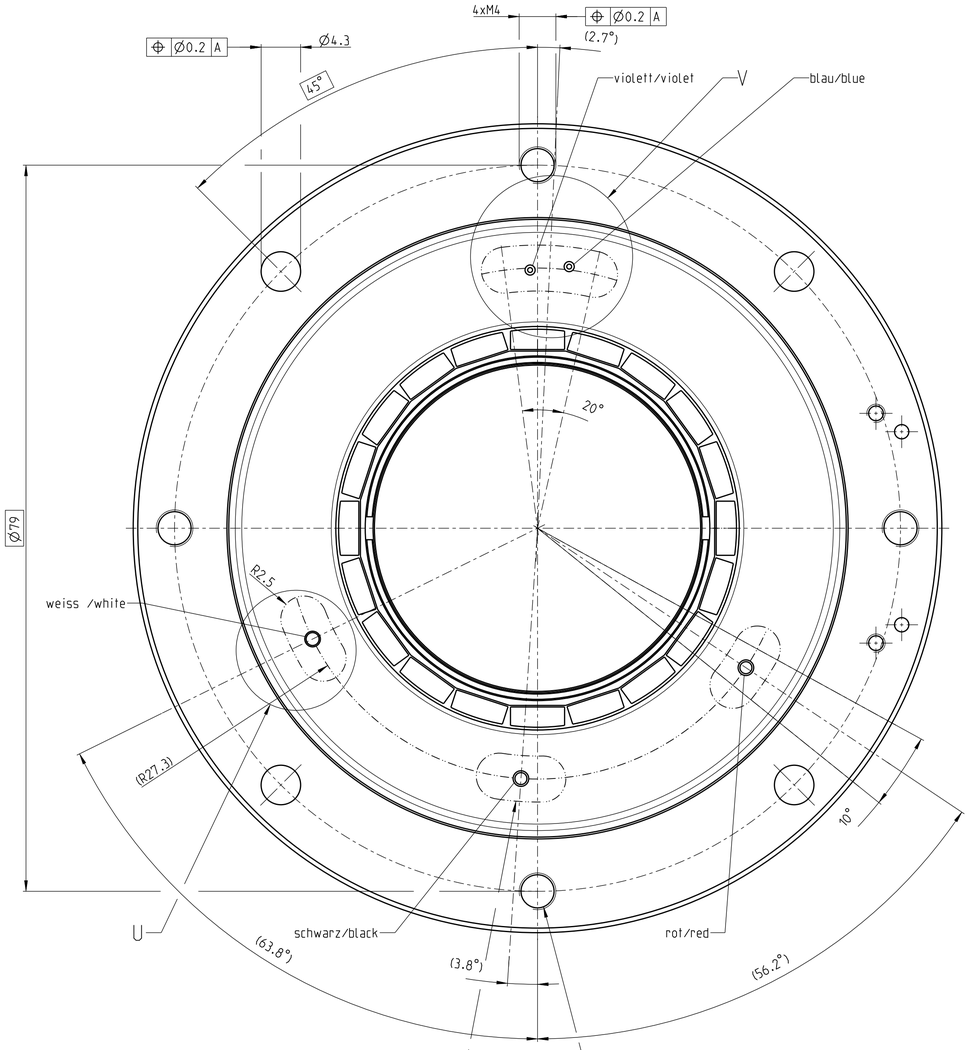


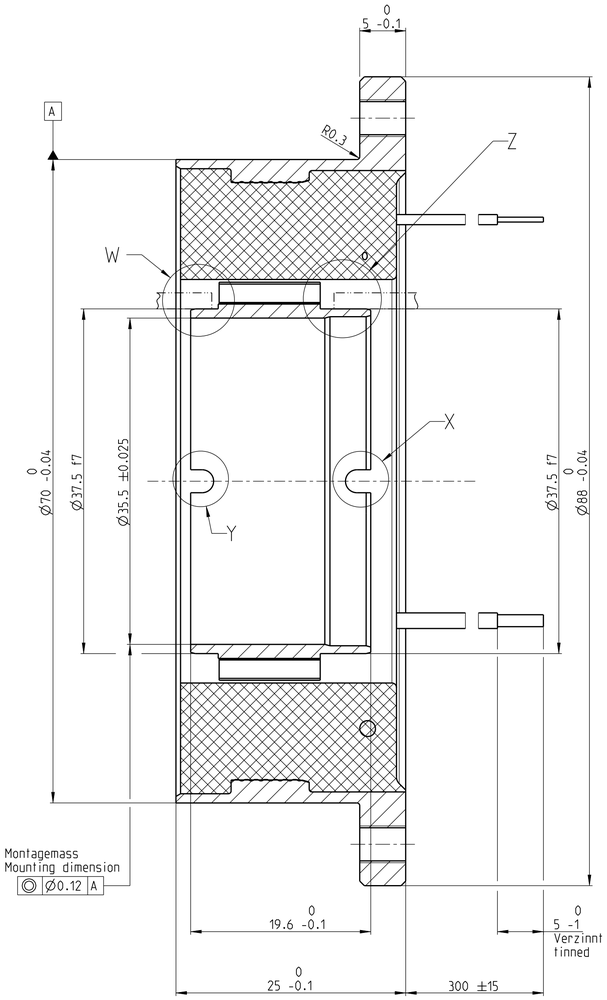


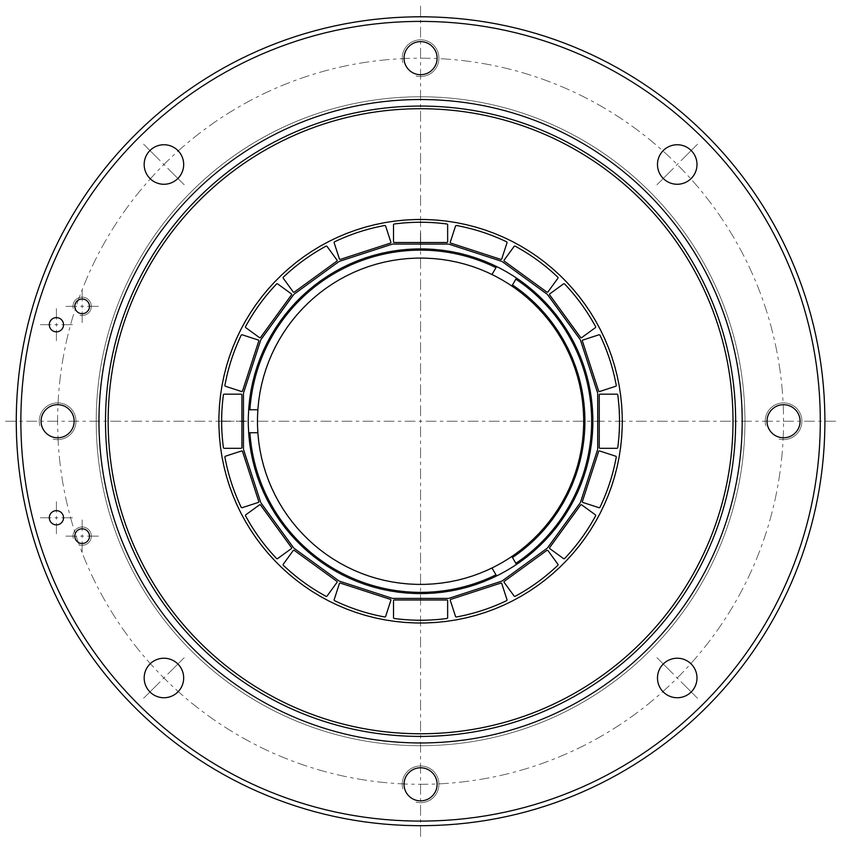


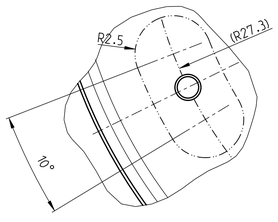




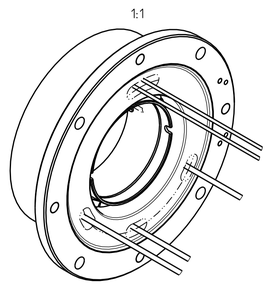






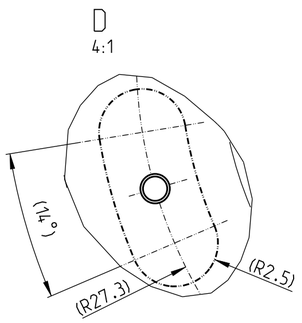


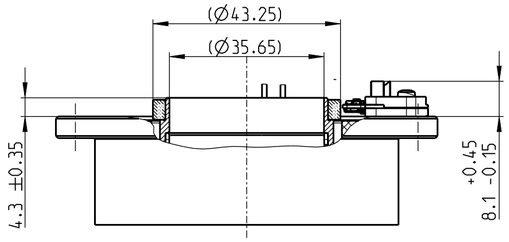
Kabelbelegung / wiring diagram			
AWG18	Kabel cable = rot red		Wicklung 1 winding 1
	Kabel cable = schwarz black		Wicklung 2 winding 2
	Kabel cable = weiss withe		Wicklung 3 winding 3
AWG24	Kabel cable = violett violet		NTC in
	Kabel cable = blau blue		NTC out

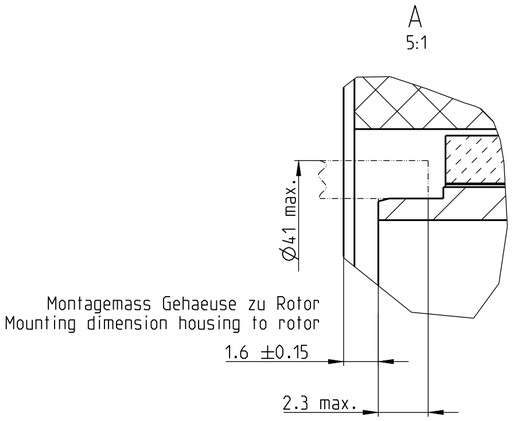


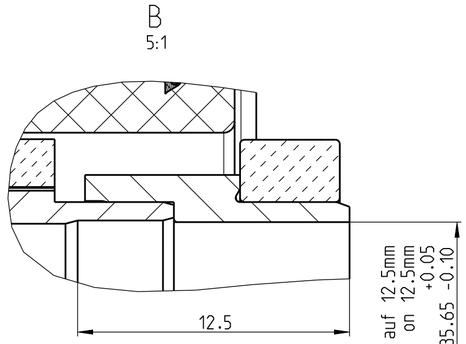
Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

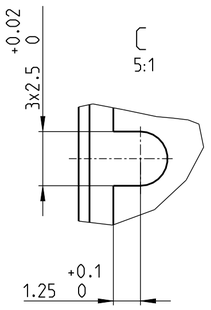
EC frameless DT65S							
Artikel Nr./part no.	Fertigprodukt/finished product					Basis Nr./basic no.	
TOLERANCING: ISO 8015	GENERAL TOLERANCES: ISO 2768:1989-m	SCREW THREAD TOLERANCES: ISO 965-1	GEOMETRICAL TOLERANCES: ISO 1101	SURFACES: N/A	EDGES: N/A	N/A N/A	
DOCUMENT TYPE: Dimensional Drawing			CO-NO 130936	DATE	NAME	SCALE: 3:1	3D MODEL
TITLE: EC frameless DT65S			CREATED	11.05.2022	MMAGHAAC	SHEETS: A1/1/1	9112533
			MODIFIED	02.02.2023	MMAGRENI	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1
			RELEASED	02.02.2023	MMAGMUAG		
PART NUMBER	PART REVISION	DOCUMENT NUMBER: 9112534				DOC REVISION: 05	
maxon		www.maxongroup.com					

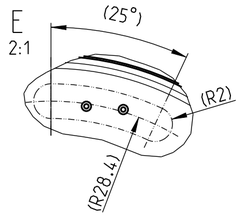


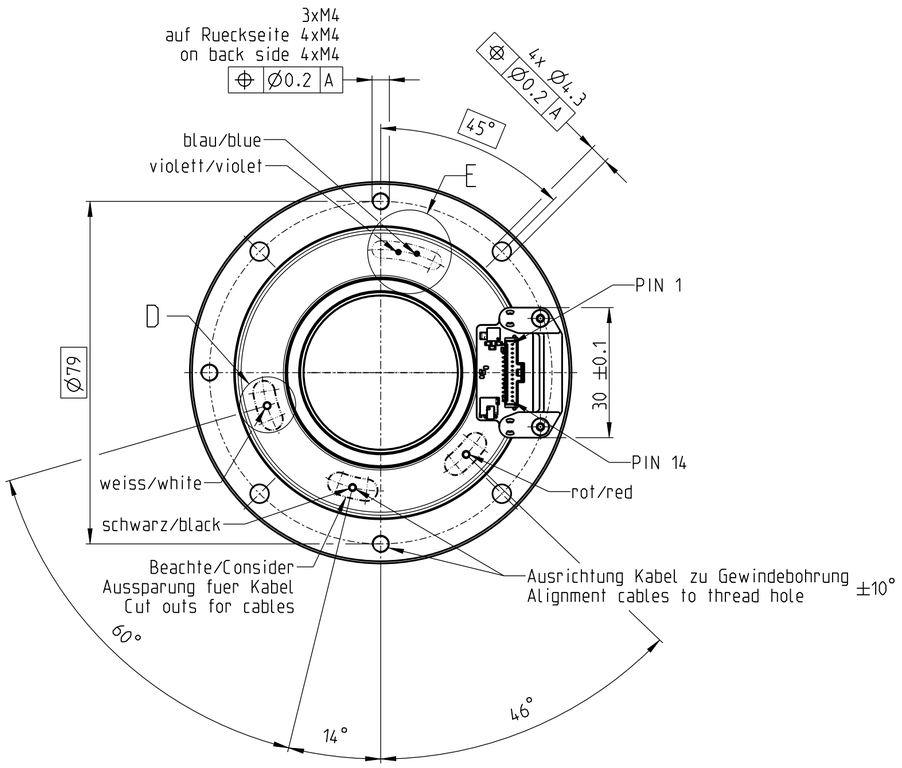


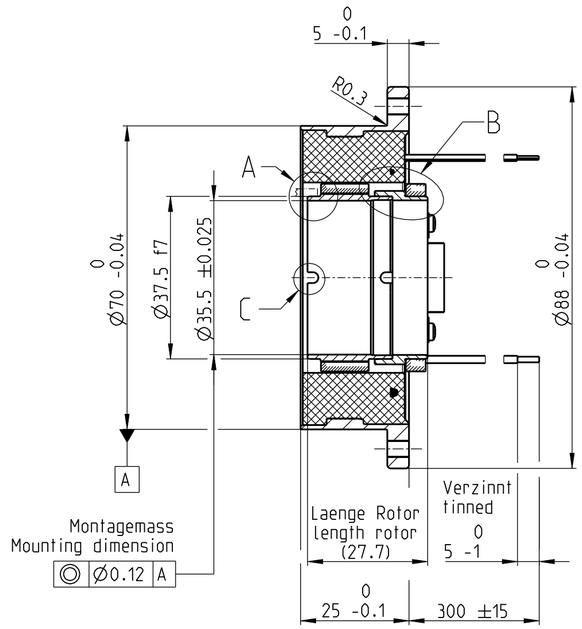


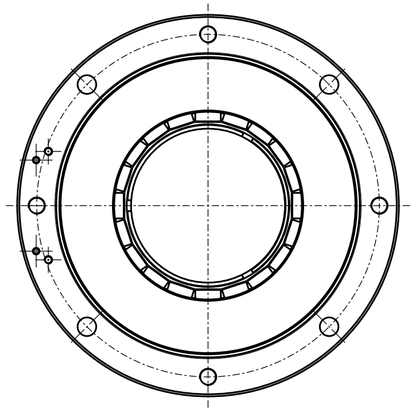


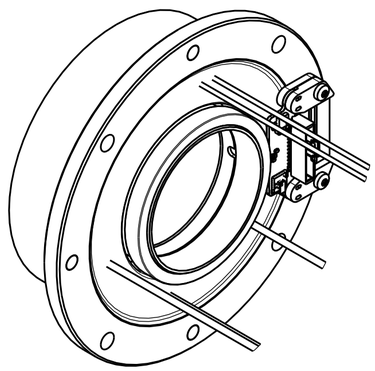












Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
PIN 8	N.C.
PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

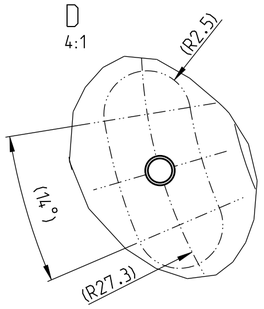
ACHTUNG / ATTENTION

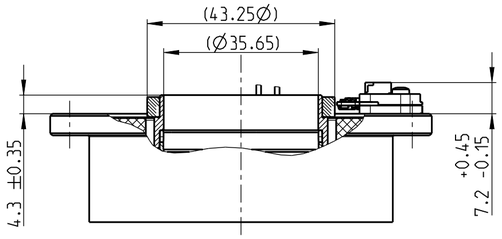
Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

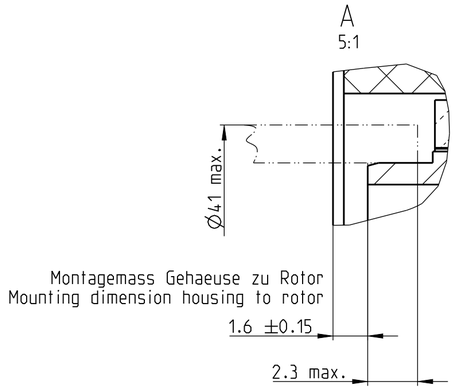
Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

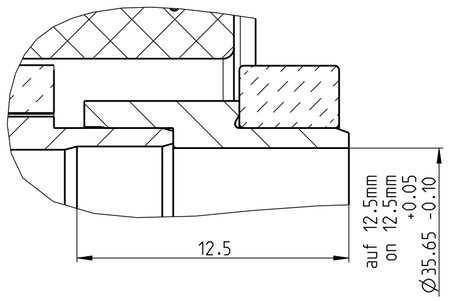
Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

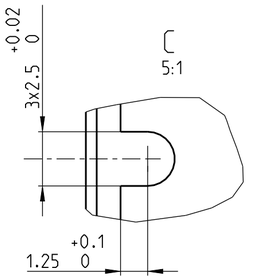
	maxon tacho ENC TSX MAG						
	maxon motor EC frameless DT65S						
Artikel Nr./part no.	Fertigprodukt/finished product						Basis Nr./basic no.
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES		N/A N/A
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	N/A	N/A		N/A
DOCUMENT TYPE: Dimensional Drawing			CO-ND: 130936	DATE	NAME	SCALE 1:1	3D MODEL
TITLE: EC frameless DT65S + TSX MAG			CREATED	17.10.2022	MMAGMRHI	SHEETS A2/1/1	9591458
			MODIFIED	03.02.2023	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1
			RELEASED	03.02.2023	MMAGHAAC		
PART NUMBER		PART REVISION	DOCUMENT NUMBER: 9591822				DOC REVISION: 02
maxon			www.maxongroup.com				

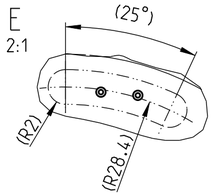


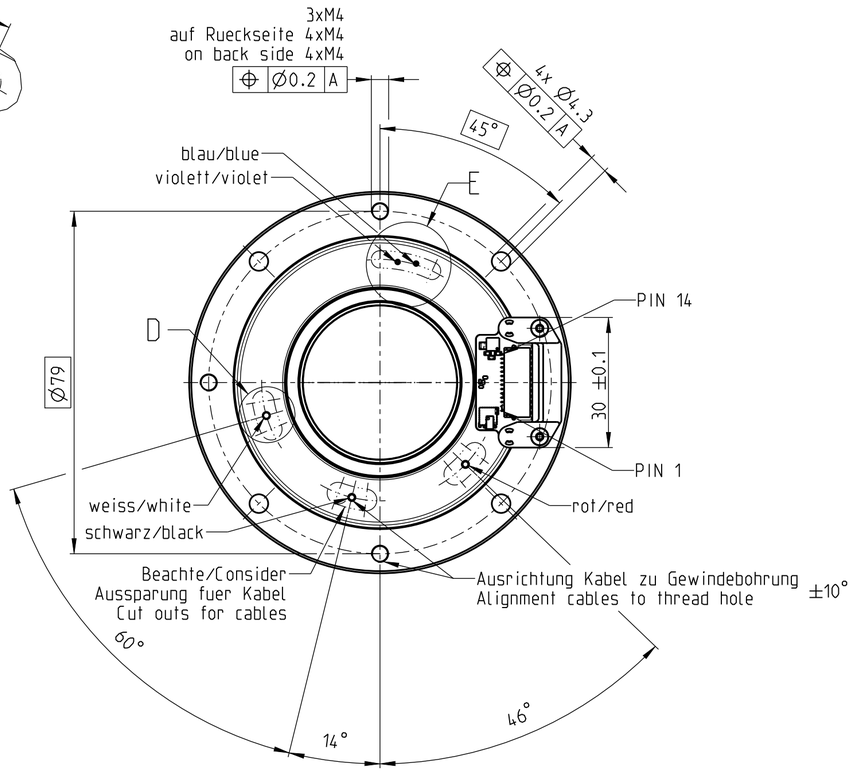


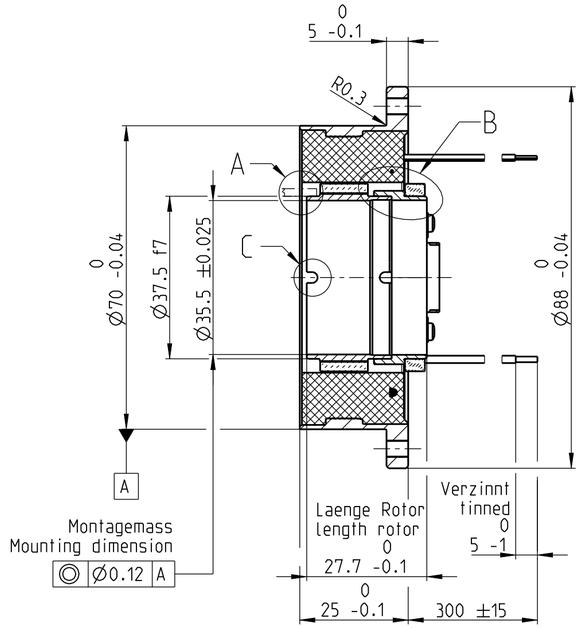


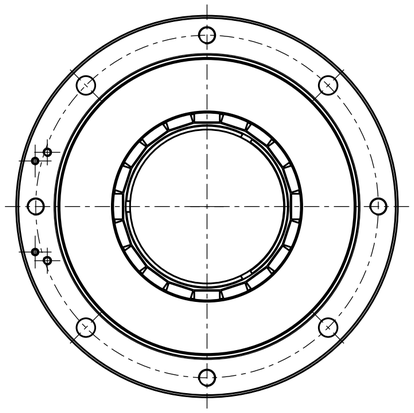






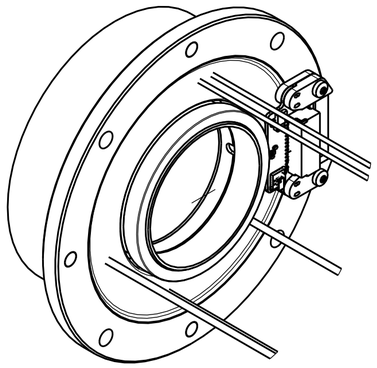






Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
PIN 7	N.C.
PIN 8	N.C.
PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

	maxon tacho ENC TSX MAG						
	maxon motor EC frameless DT65S						
Artikel Nr./part no.	Fertigprodukt/finished product					Basis Nr./basic no.	
TOLERANCING: ISO 8015	GENERAL TOLERANCES: ISO 2768:1989-m	SCREW THREAD TOLERANCES: ISO 965-1	GEOMETRICAL TOLERANCES: ISO 1101	SURFACES: N/A	EDGES: N/A	N/A N/A	
DOCUMENT TYPE: Dimensional Drawing			CO-NO: 130936	DATE	NAME	SCALE: 1:1	3D MODEL
TITLE: EC frameless DT65S + TSX MAG			CREATED	18.10.2022	MMAGMRHI	SHEETS: A2/1/1	9595453
			MODIFIED	03.02.2023	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1
			RELEASED	03.02.2023	MMAGHAAC		
PART NUMBER	PART REVISION	DOCUMENT NUMBER: 9595454				DOC REVISION: 02	
maxon		www.maxongroup.com					

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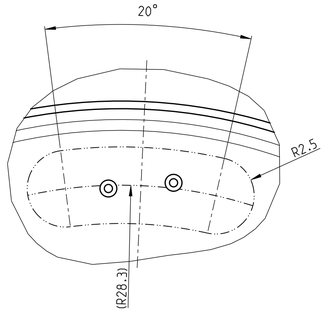

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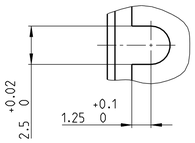

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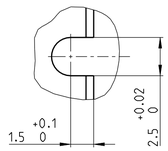

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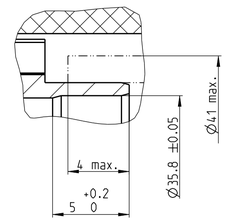

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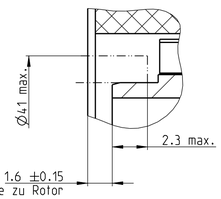
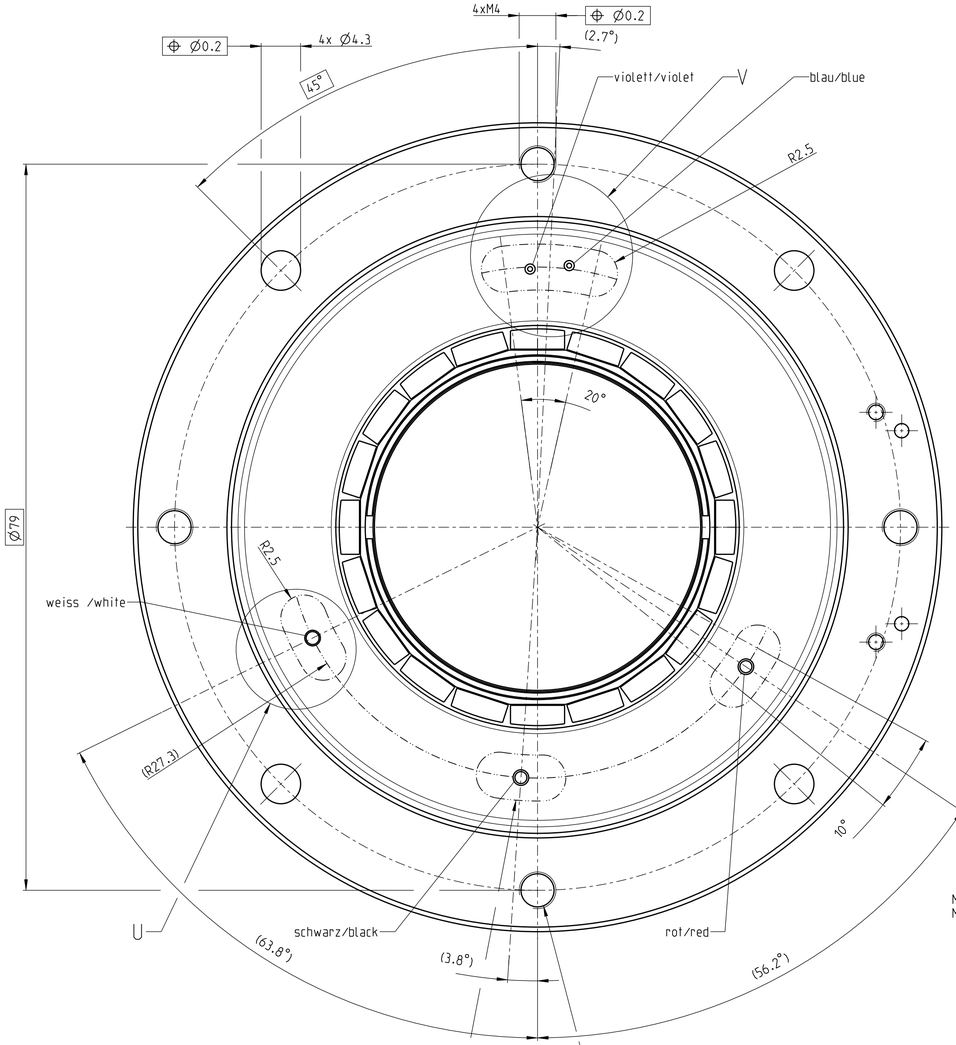
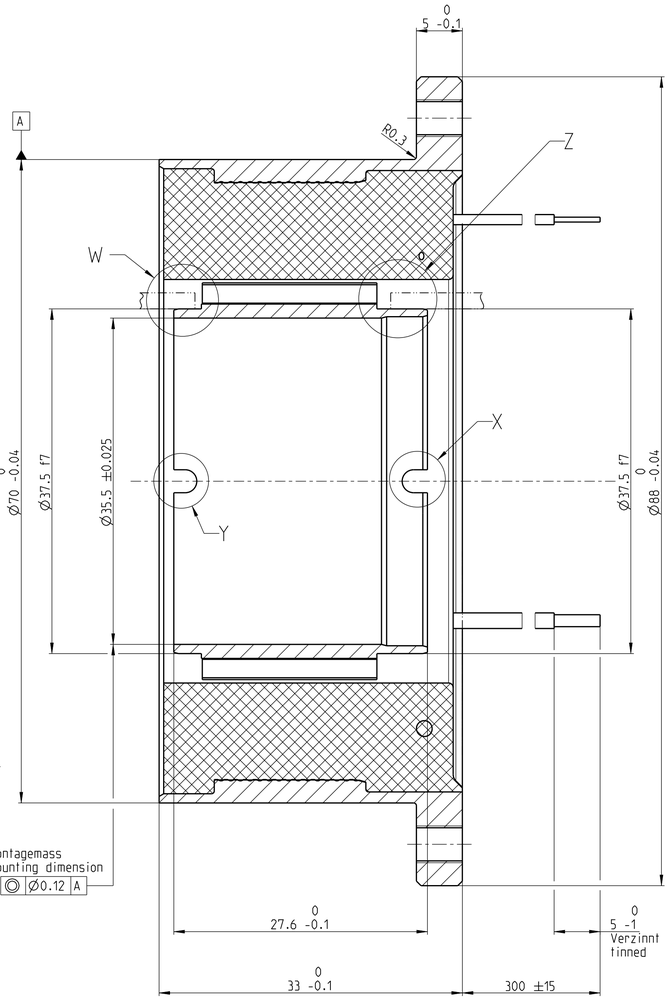
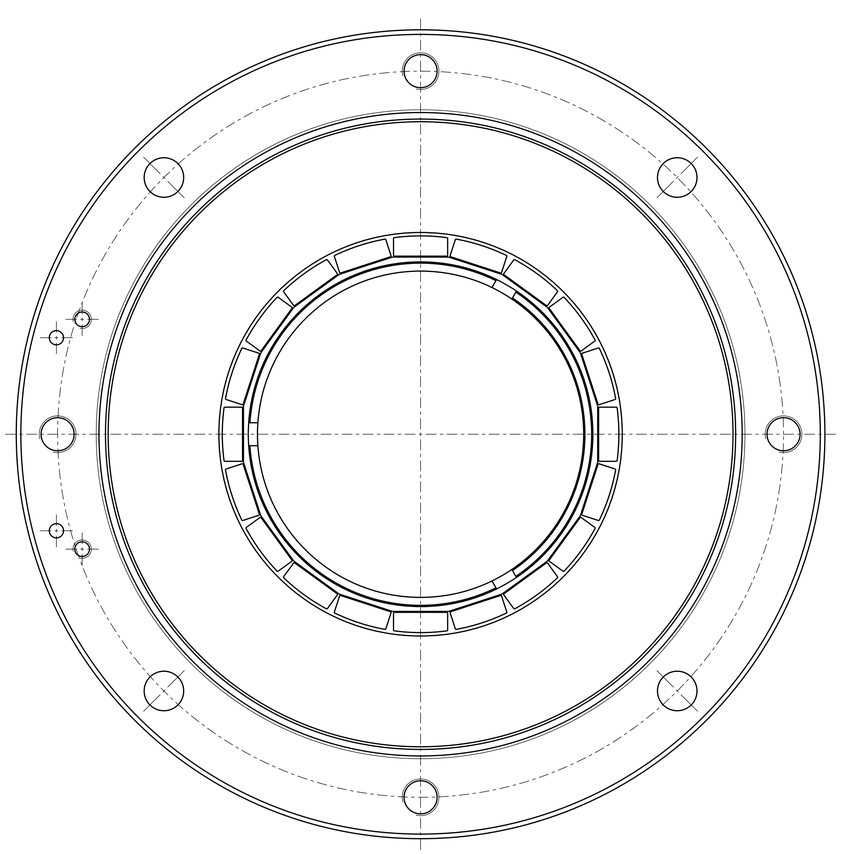


Montagemass Gehaeuse zu Rotor
Monting dimension housing to rotor







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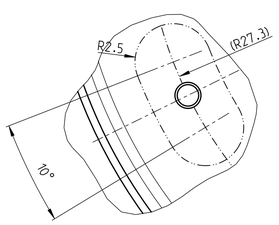
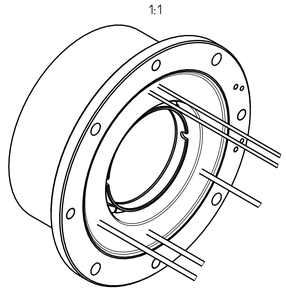


Beachte/Consider
Aussparungen fuer Kabel
Cut outs for cables

Ausrichtung Kabel auf Gewindebohrung
Alignment cables o thread holes ±10

Kabelbelegung / wiring diagram			
AWG18	Kabel cable	= rot red	Wicklung 1 winding 1
	Kabel cable	= schwarz black	Wicklung 2 winding 2
	Kabel cable	= weiss withe	Wicklung 3 winding 3
AWG24	Kabel cable	= violett violet	NTC in
	Kabel cable	= blau blue	NTC out

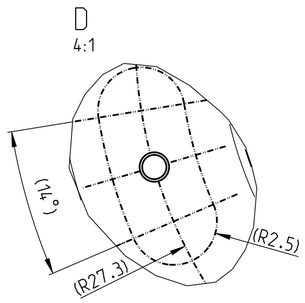
1:1

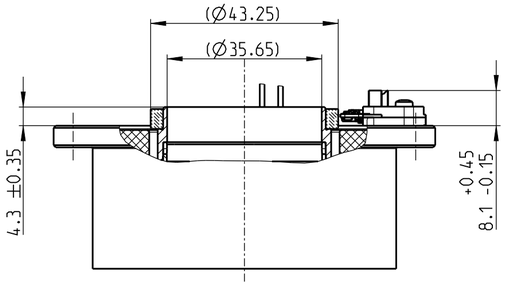


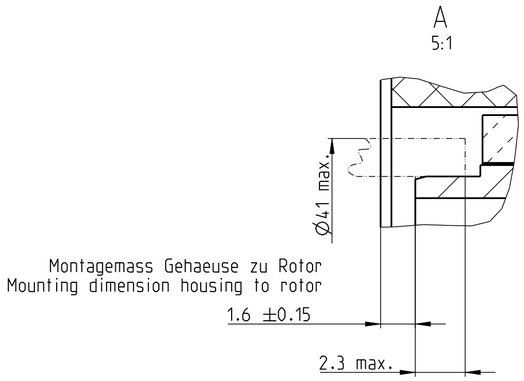
Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

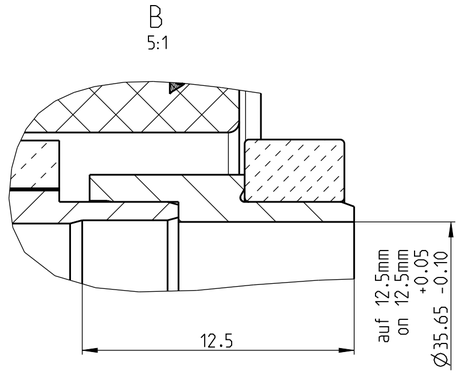
	EC frameless DT65M					
Artikel Nr./part no.	Fertigprodukt/finished product					Basis Nr./basic no.
TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

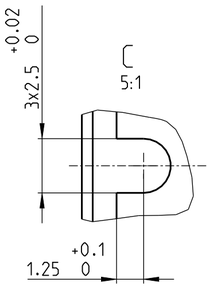
DOCUMENT TYPE	Dimensional Drawing	CO-NO. TOOTAL	DATE	NAME	SCALE	3:1	3D MODEL
TITLE		CREATED	18.05.2022	MMAGHAAC	SHEETS	A1/1/1	9129709
EC frameless DT65M		MODIFIED	02.02.2023	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	02.02.2023	MMAGMUAG	mm	ISO 5456-1	
PART NUMBER	PART REVISION	DOCUMENT NUMBER					DOC REVISION
		9129711					03
maxon		www.maxongroup.com					

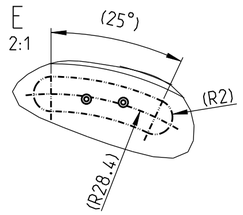


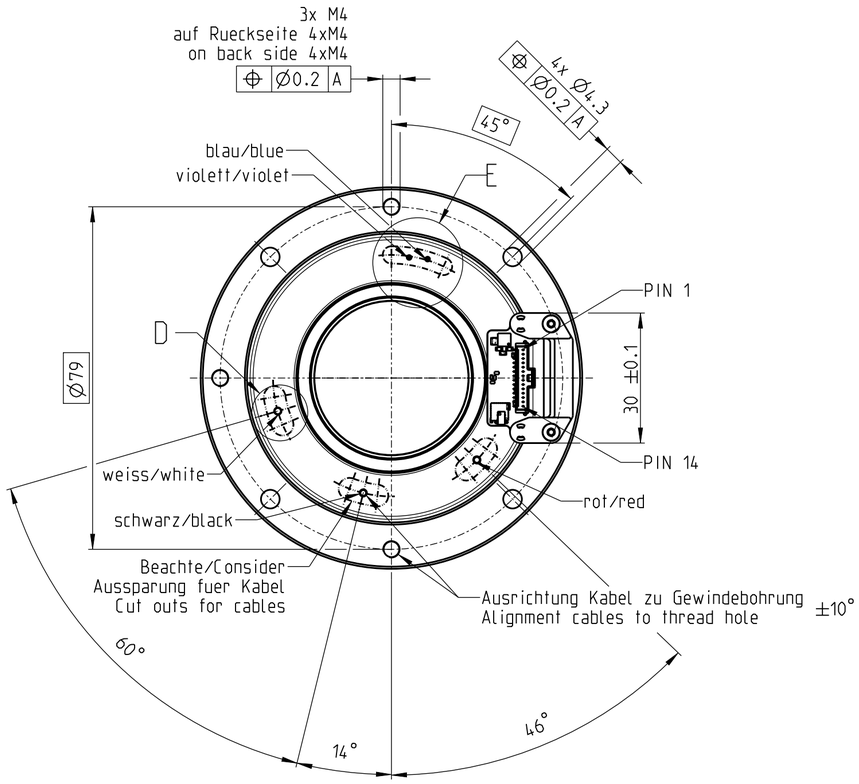


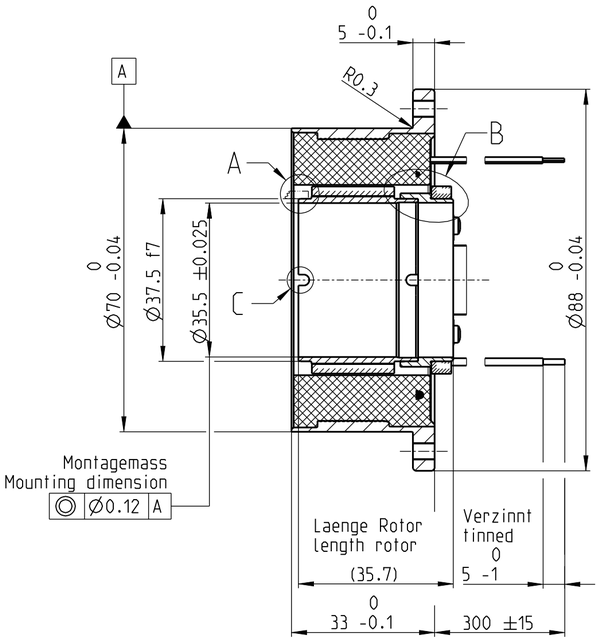


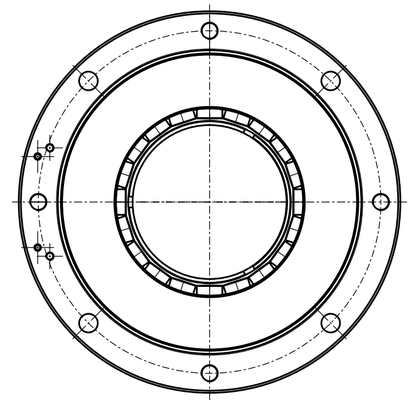


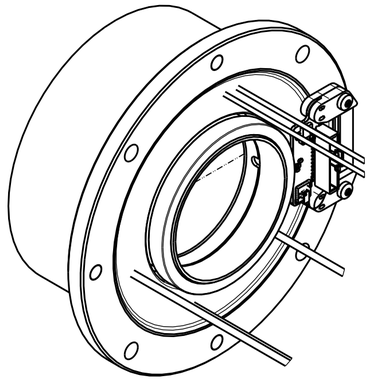












Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
PIN 8	N.C.
PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

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	maxon tacho ENC TSX MAG					
	maxon motor EC frameless DT65M					
Artikel Nr./part no.	Fertigprodukt/finished product					Basis Nr./basic no.
TOLERANCING: ISO 8015	GENERAL TOLERANCES: ISO 2768:1989-m	SCREW THREAD TOLERANCES: ISO 965-1	GEOMETRICAL TOLERANCES: ISO 1101	SURFACES: N/A	EDGES: N/A	N/A N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO: 130936	DATE	NAME	SCALE	1:1	3D MODEL
TITLE		CREATED	18.10.2022	MMAGMRHI	SHEETS	A2/1/1	9595762
EC frameless DT65M + TSX MAG		MODIFIED	03.02.2023	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	03.02.2023	MMAGHAAC	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		9595763	02

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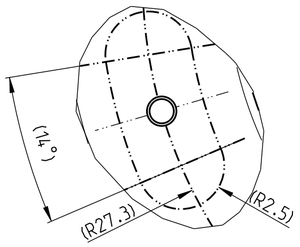

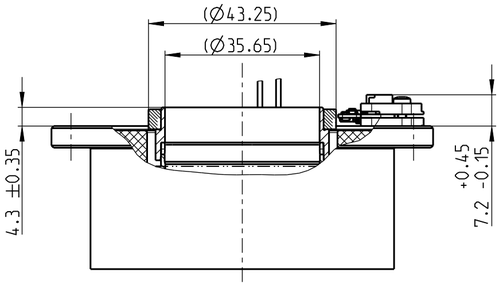

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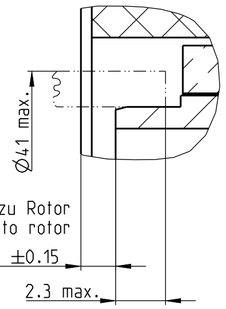

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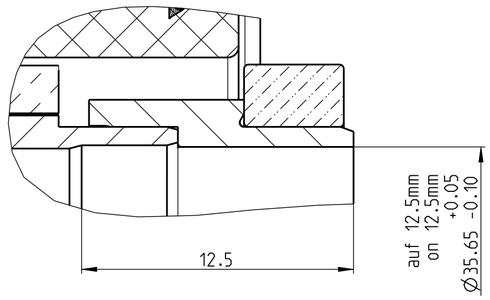

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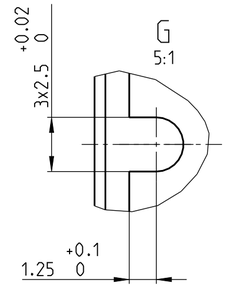

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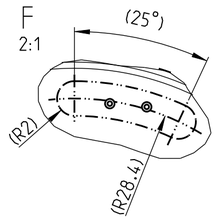

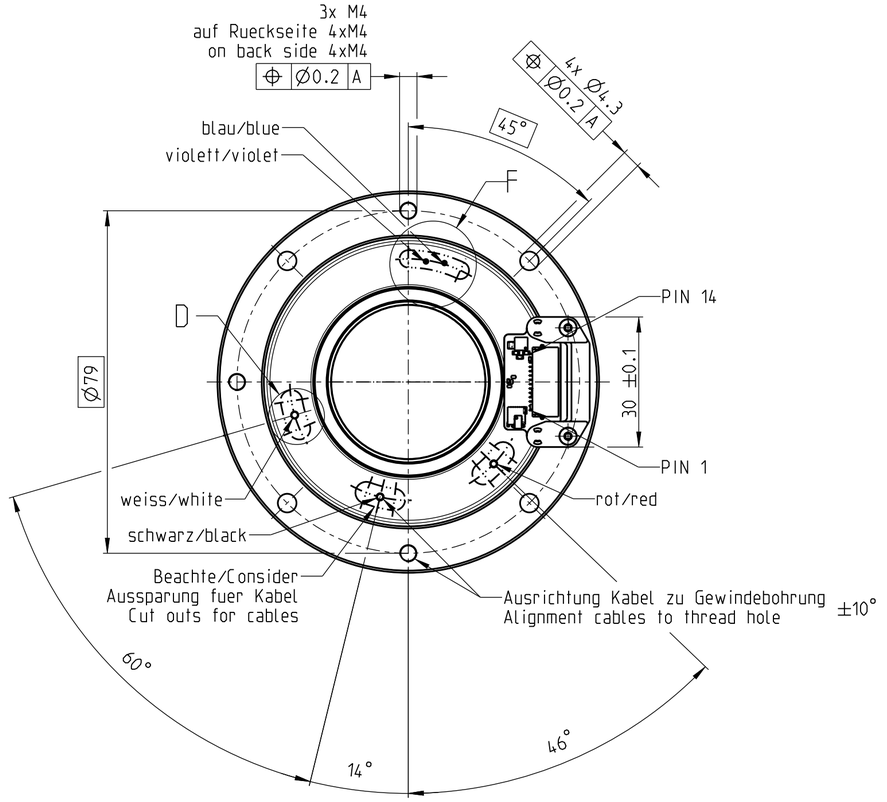

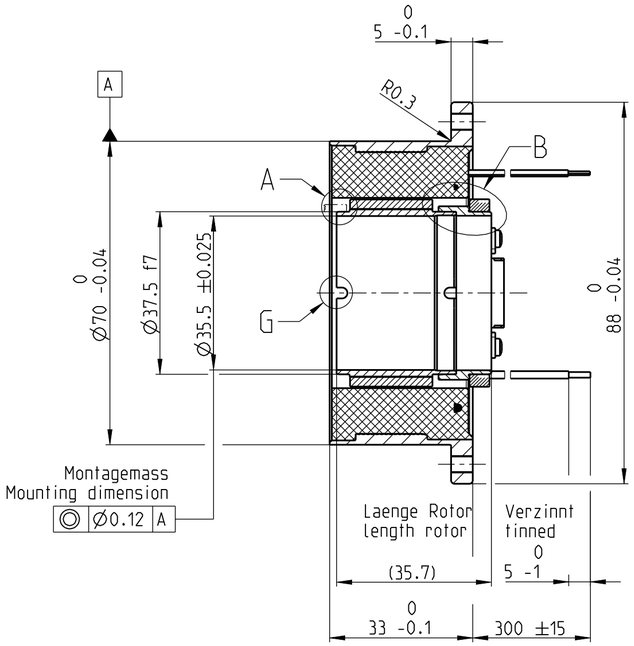

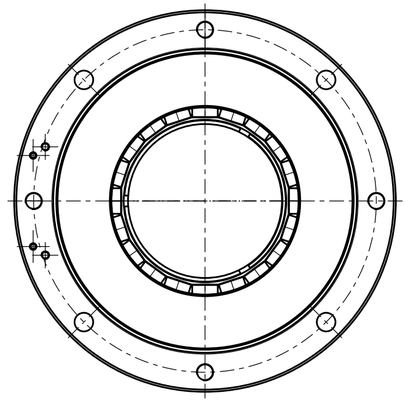

Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
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PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
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PIN 14	NTC-

Kabelbelegung/wiring diagram		
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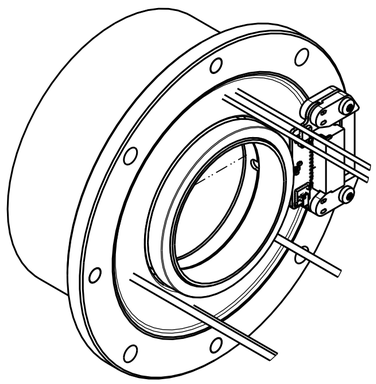
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out



ACHTUNG / ATTENTION

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	maxon tacho ENC TSX MAG	
	maxon motor EC frameless DT65M	
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768:1989-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-ND: 130936	DATE	NAME	SCALE	1:1	3D MODEL
TITLE		CREATED	18.10.2022	MMAGMRHI	SHEETS	A2/1/1	9596765
EC frameless DT65M + TSX MAG		MODIFIED	03.02.2023	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	03.02.2023	MMAGHAAC	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		9596764	02

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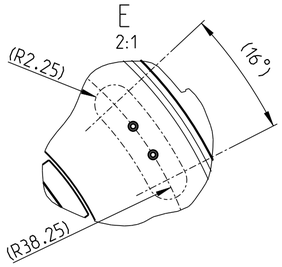

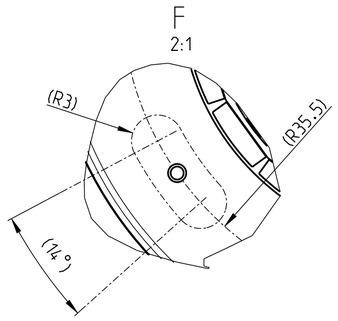

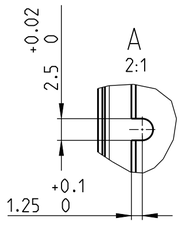

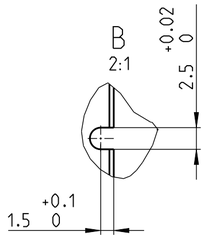

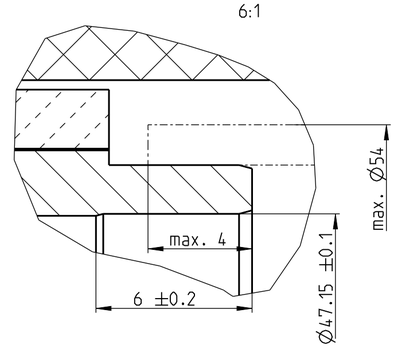

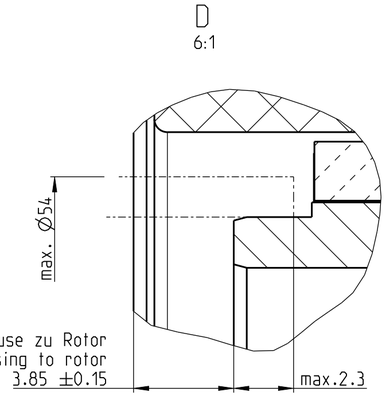

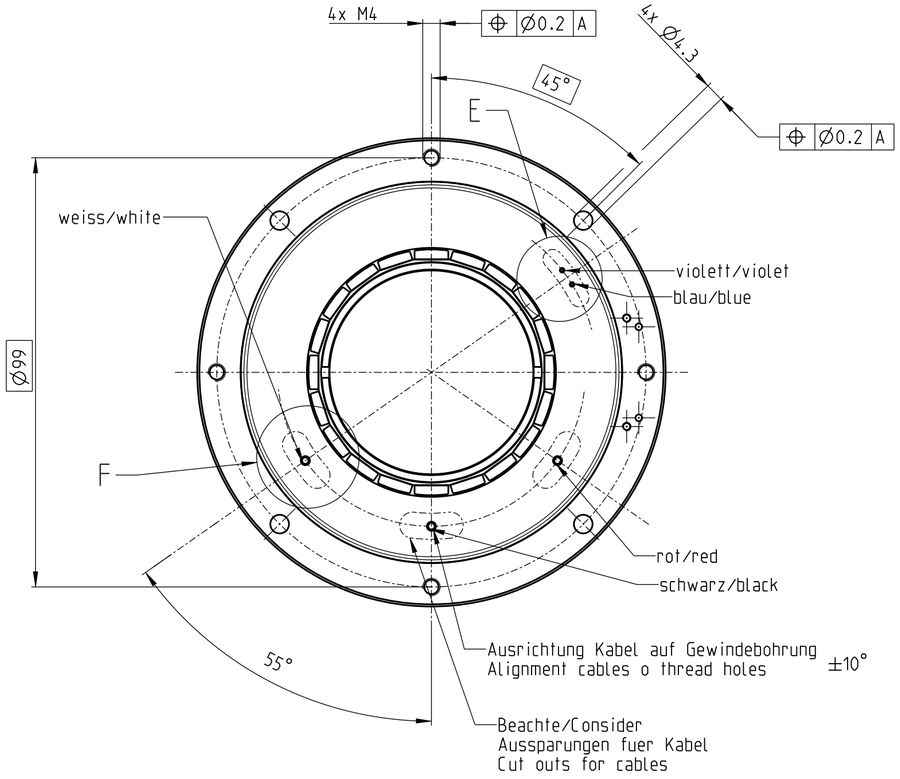

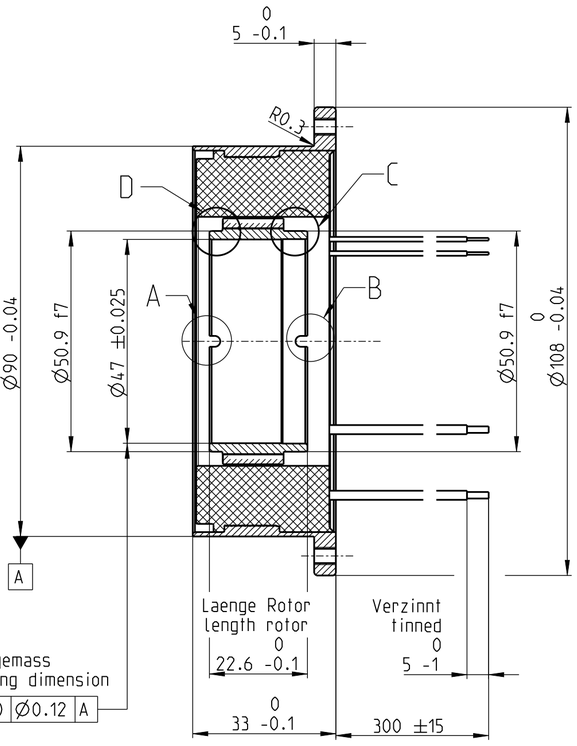

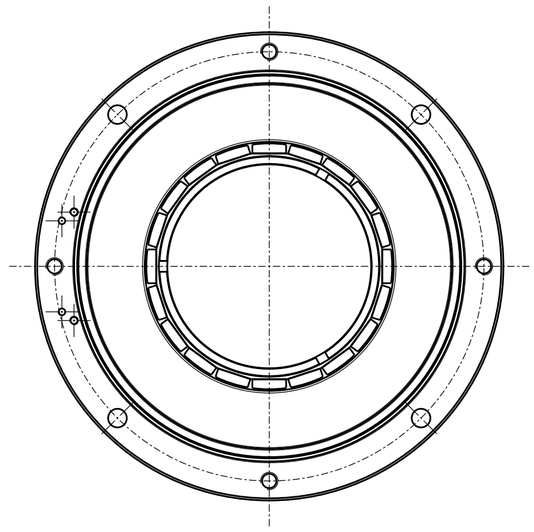

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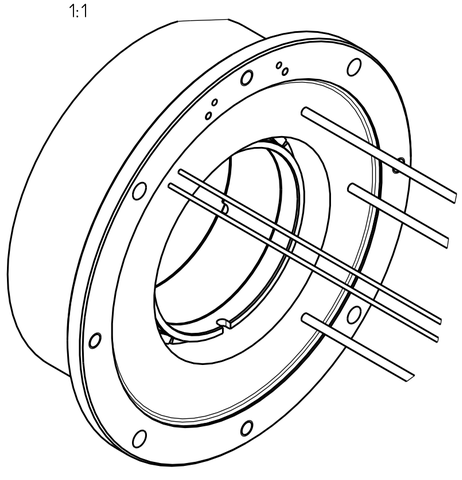

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel weiss cable white	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE: -	CO-NO: A10002741 0	DATE	NAME	SCALE	1:1	3D MODEL
TITLE EN: Dimensional Drawing	CREATED	13.11.2020	MMAGDARR	SHEETS	A2/1/1	7460523
TITLE DE: EC frameless DT85M	MODIFIED	14.07.2022	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1	
	RELEASED	18.07.2022	MMAGHAAC			

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		7460524	05

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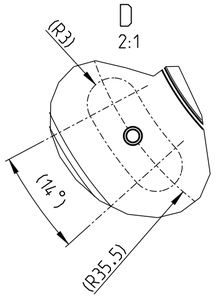

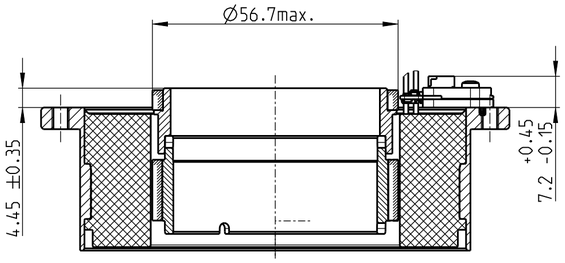

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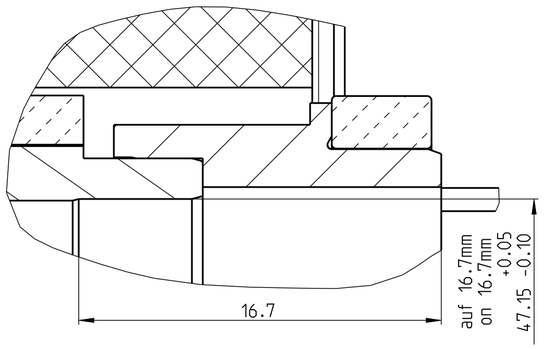

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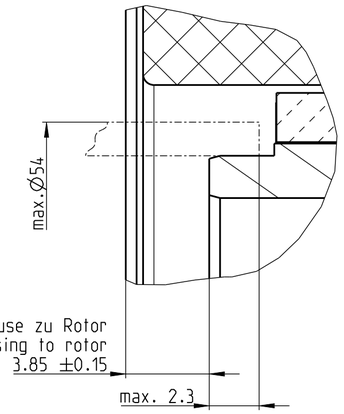

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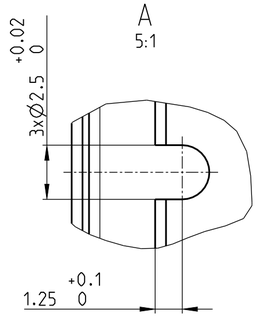

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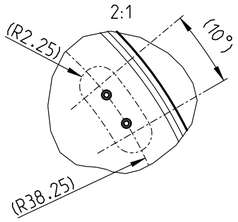

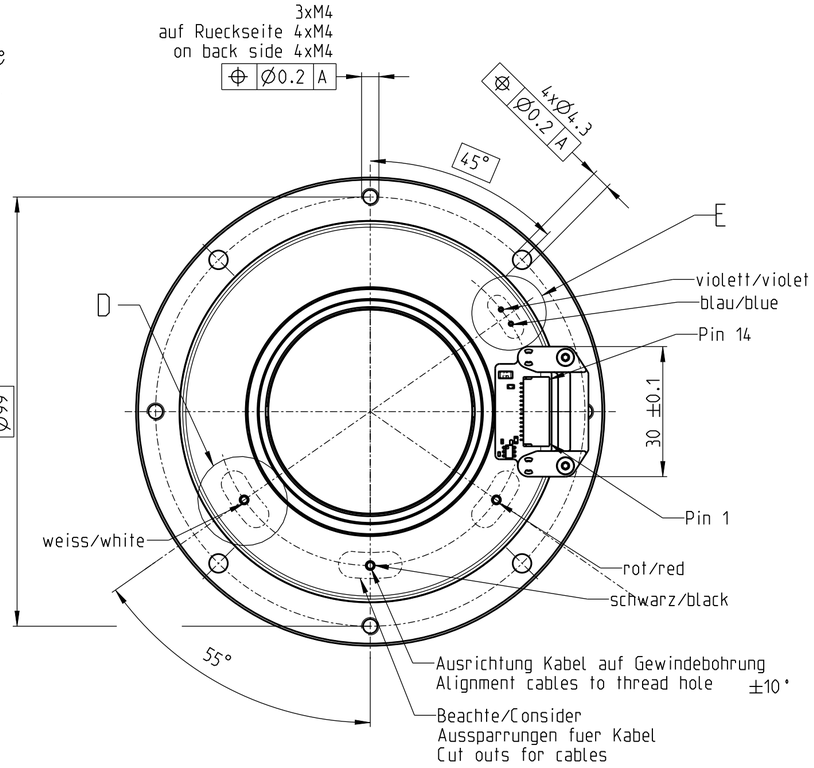

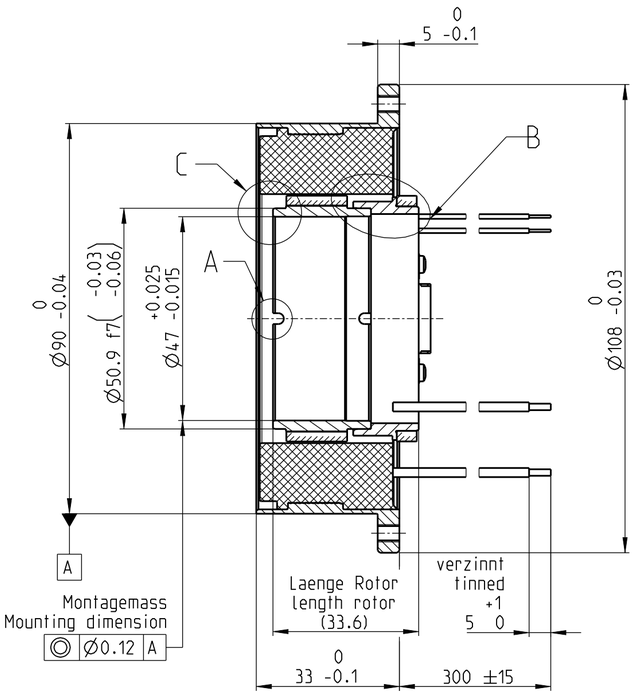

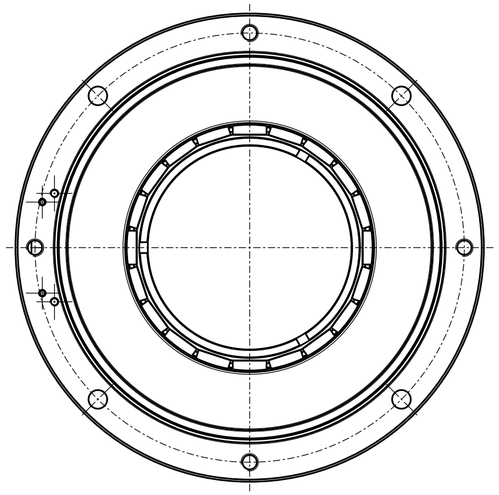

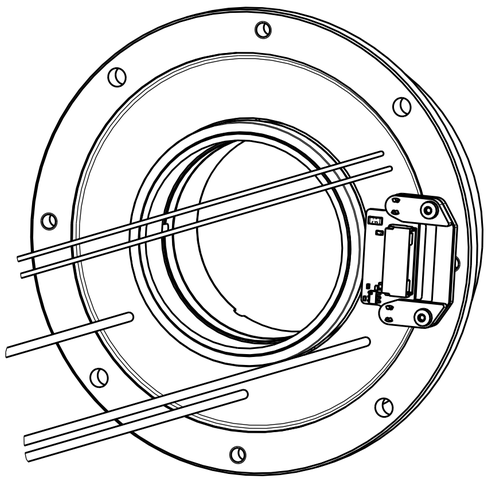

Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
PIN 7	N.C.
PIN 8	N.C.
PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT85M	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	N/A	ISO 1302	ISO 13715	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO. A100027027	DATE	NAME	SCALE	1:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	22.02.2022	MMAGMUAG	SHEETS	A2/1/1	8872144
TITLE DE	EC frameless DT85M+TSX MAG	MODIFIED	18.05.2022	MMAGMUAG	DIMENSION UNITS: mm	PROJECTION METHOD: ISO 5456-1	
		RELEASED	13.07.2022	MMAGMUAG			

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8885047	03

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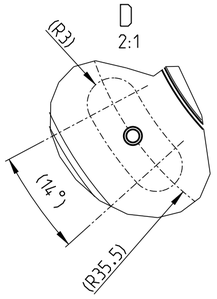
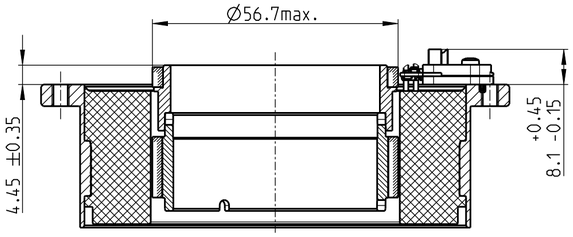
2:1





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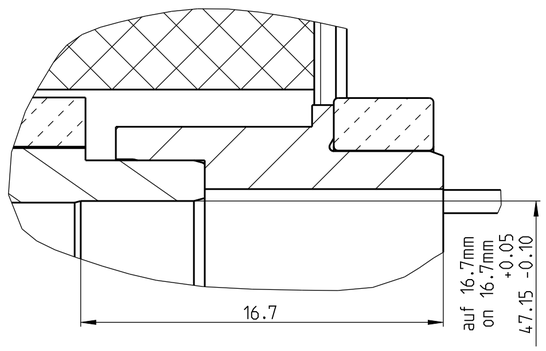

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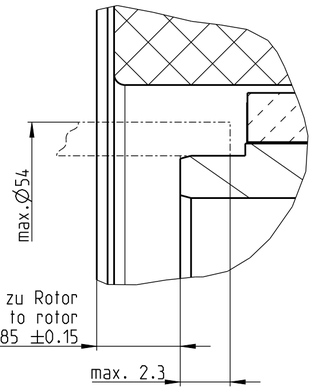

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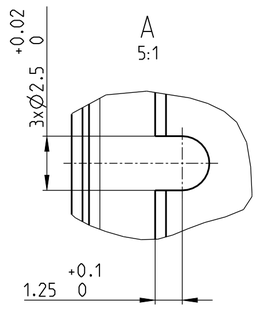

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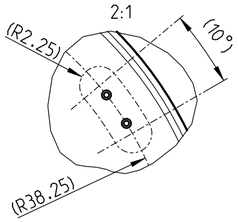
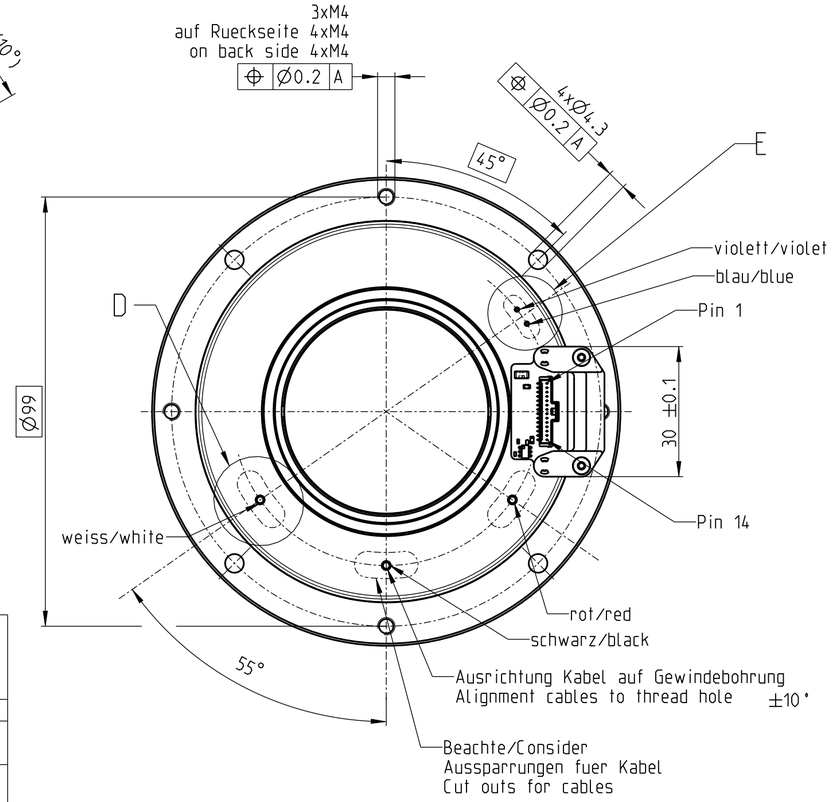
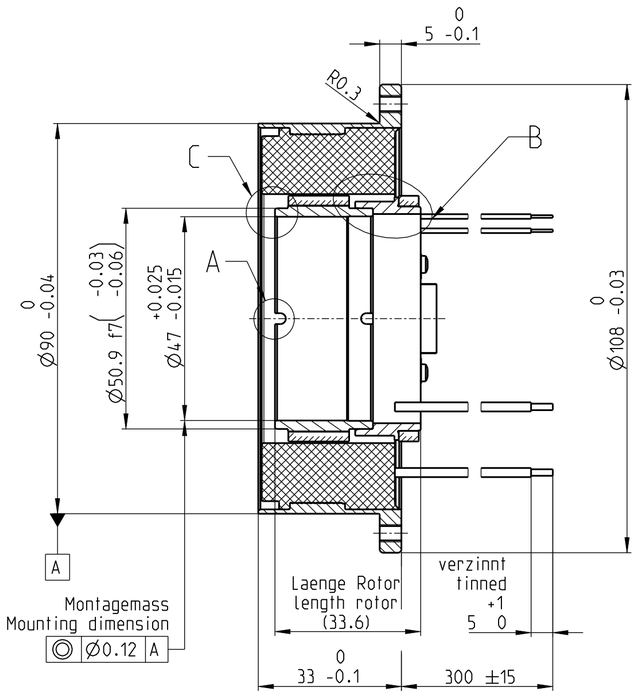
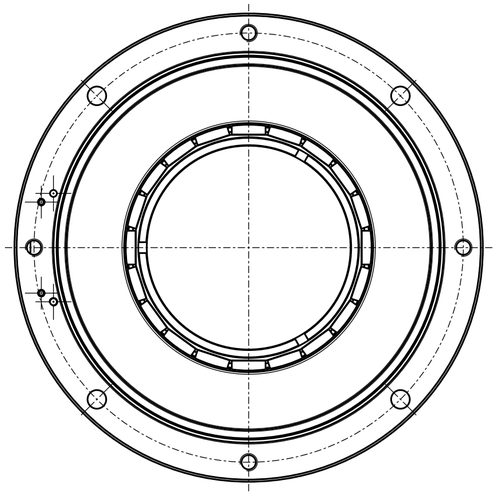
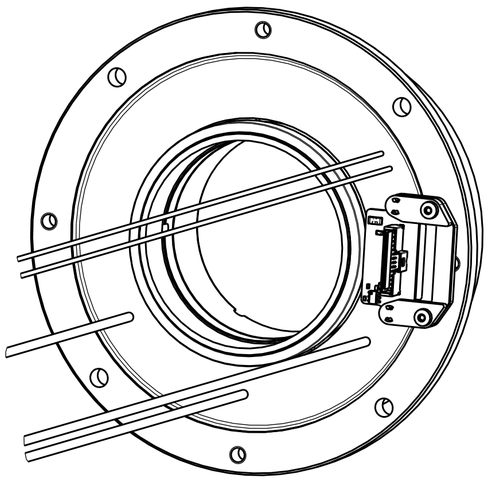








Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
PIN 8	N.C.
PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-



Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out

ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT85M	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	N/A	ISO 1302	ISO 13715	N/A

DOCUMENT TYPE	Dimensional Drawing	CQ-NO. A100027027	DATE	NAME	SCALE	1:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	30.06.2021	MMAGMUAG	SHEETS	A2/1/1	8872144
TITLE DE	Massbild	MODIFIED	19.05.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	19.05.2022	MMAGMUAG	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8140732	03

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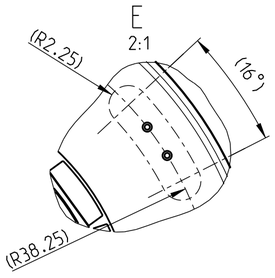

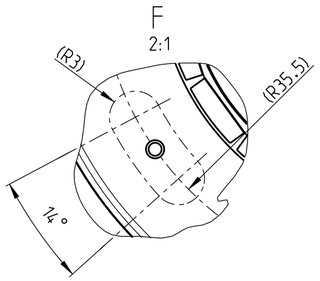

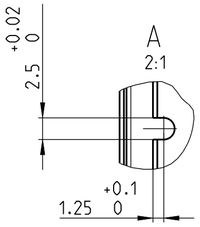

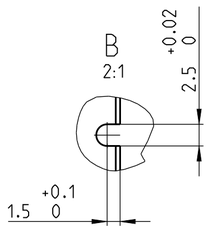

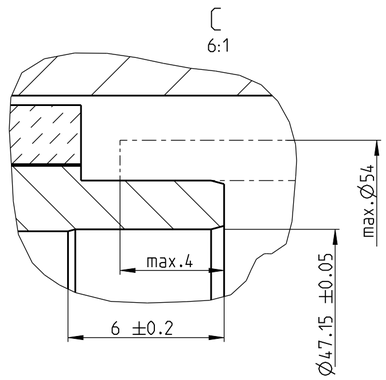

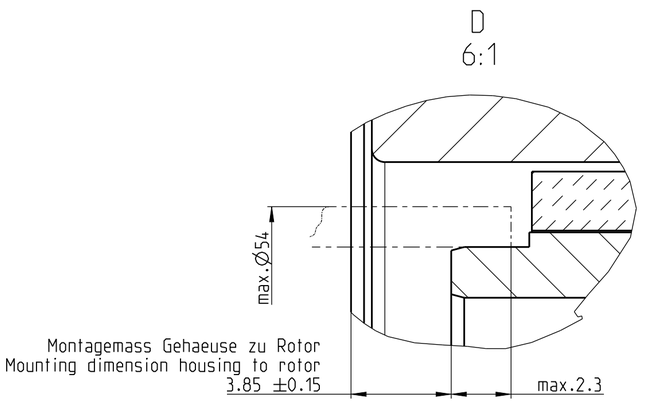

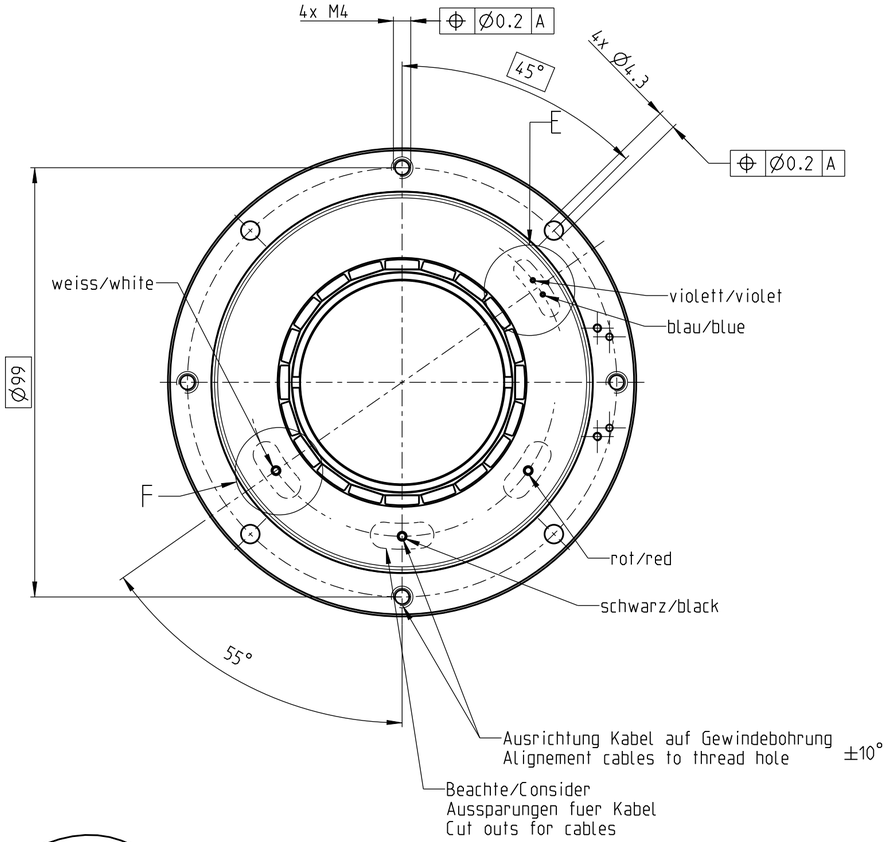

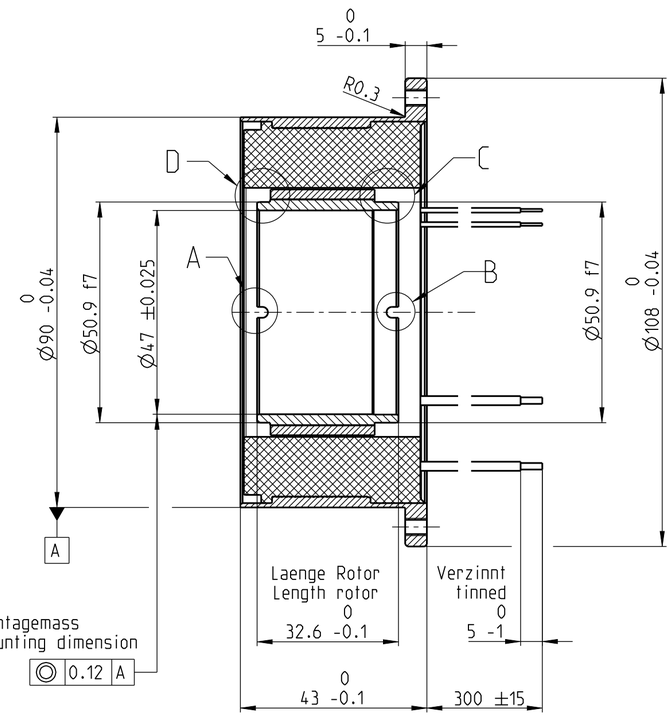

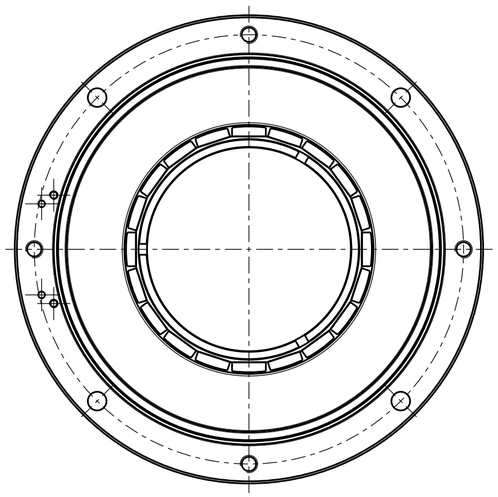

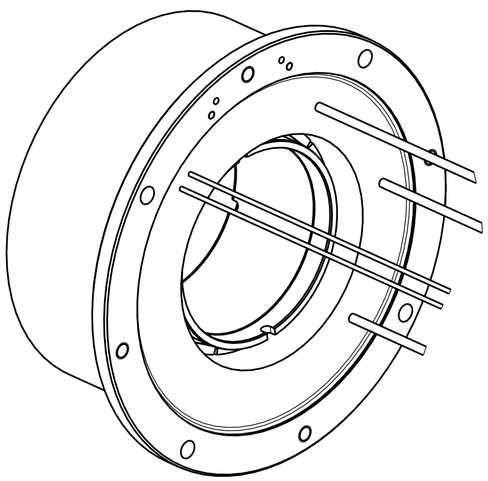

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
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Rotor und Stator werden getrennt angeliefert
Rotor and stator delivered seperated

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	ISO 1101	N/A	N/A	N/A

DOCUMENT TYPE	-	CO-NO: A10002741O	DATE	NAME	SCALE	1:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	06.11.2021	MMAGMUAG	SHEETS	A2/1/1	8591561
TITLE DE	EC frameless DT85L	MODIFIED	13.07.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
		RELEASED	18.07.2022	MMAGHAAC	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8591562	03

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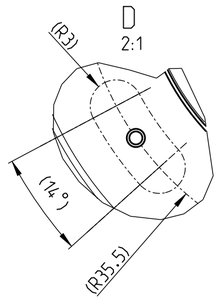

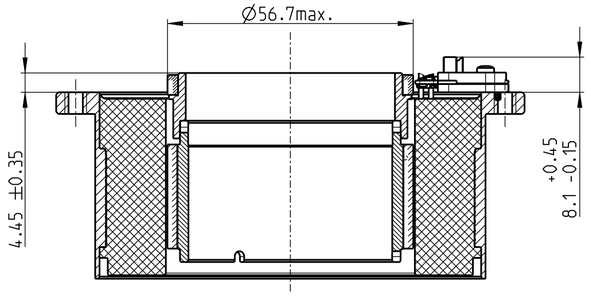

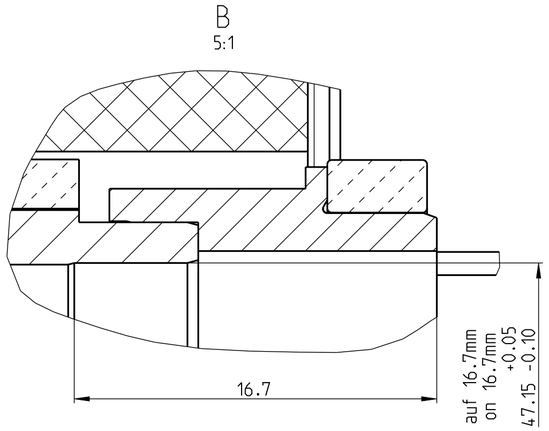

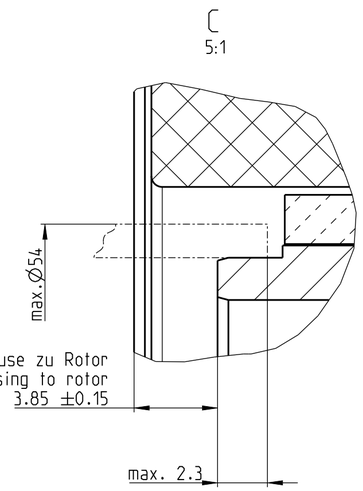

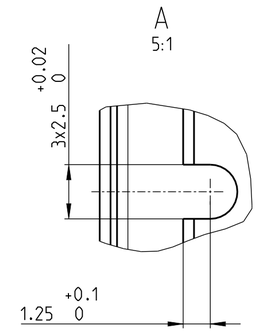

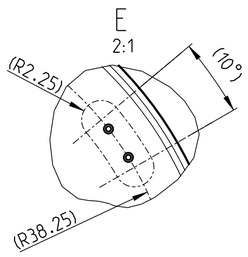

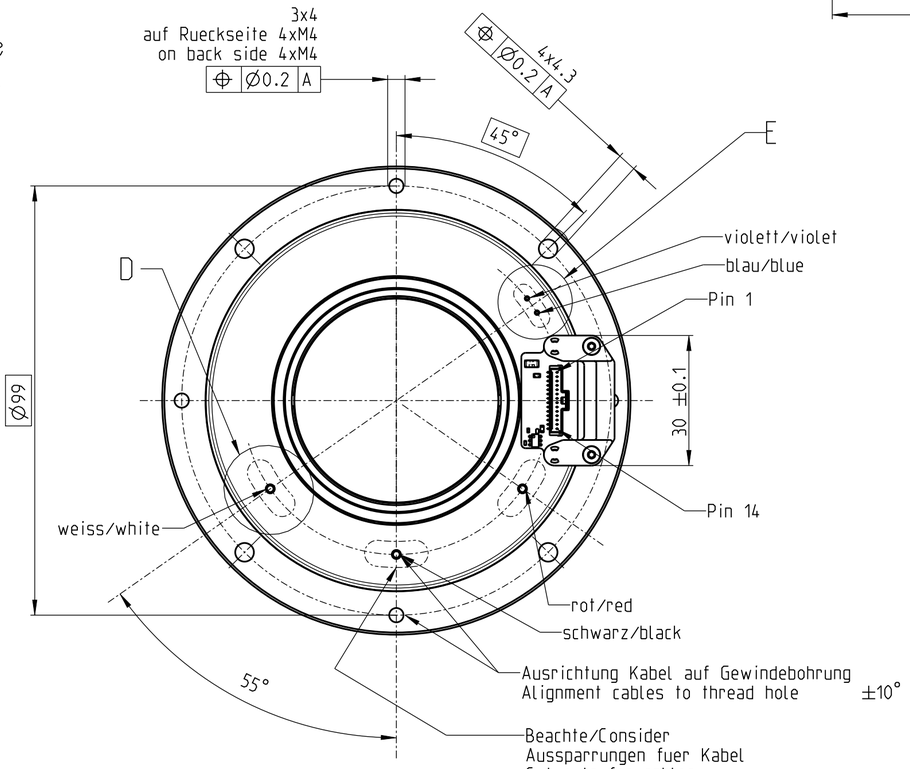

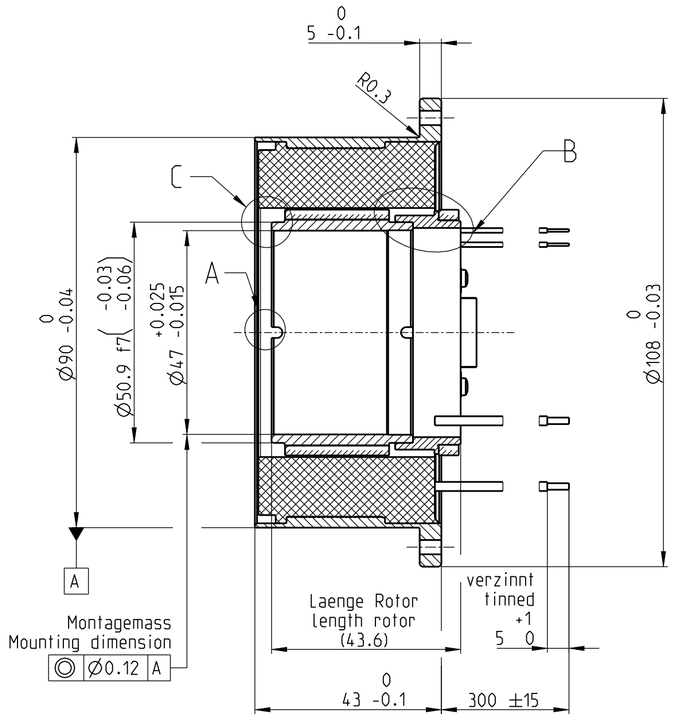

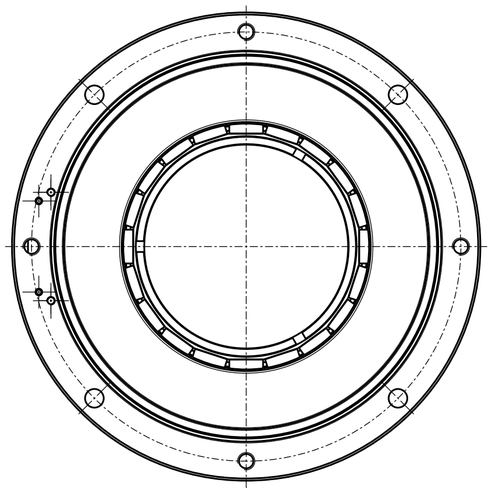

Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 14	Vcc
PIN 13	GND
PIN 12	A/
PIN 11	A
PIN 10	B/
PIN 9	B
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PIN 7	N.C.
PIN 6	H1
PIN 5	H2
PIN 4	H3
PIN 3	N.C.
PIN 2	NTC+
PIN 1	NTC-

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
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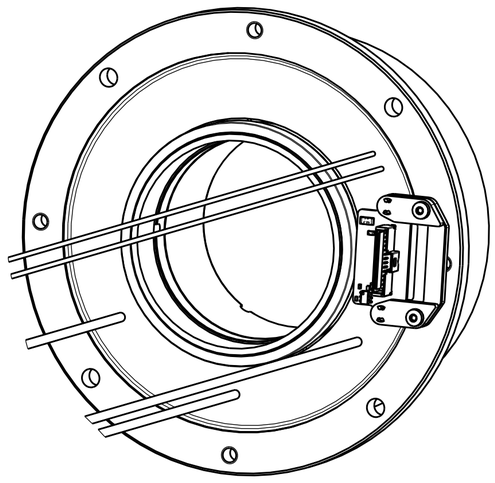
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out



ACHTUNG / ATTENTION

Handhabungsvorschriften und Verpackungsmethoden beachten
observe precautions for handling and packing methods

Elektrostatisch gefaehrdete Bauelemente
electrostatic sensitive devices

Stator und Rotor werden getrennt verpackt und angeliefert.
Stator und Rotor muessen gepaart montiert werden.
Rotor and stator are separeted packed and delivered.
Stator and rotor must assembled paired

N/A	maxon tacho ENC TSX MAG	N/A
N/A	maxon motor EC frameless DT85L	N/A
Artikel Nr./part no.	Fertigprodukt/finished product	Basis Nr./basic no.

TOLERANCING	GENERAL TOLERANCES	SCREW THREAD TOLERANCES	GEOMETRICAL TOLERANCES	SURFACES	EDGES	N/A N/A
ISO 8015	ISO 2768-m	ISO 965-1	N/A	ISO 1302	ISO 13715	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO: A100027027	DATE	NAME	SCALE	1:1	3D MODEL
TITLE EN	Dimensional Drawing	CREATED	22.02.2022	MMAGMUAG	SHEETS	A2/1/1	8886571
TITLE DE	EC frameless DT85L+TSX MAG	MODIFIED	18.05.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD
		RELEASED	13.07.2022	MMAGMUAG	mm	ISO 5456-1

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
		8886572	03

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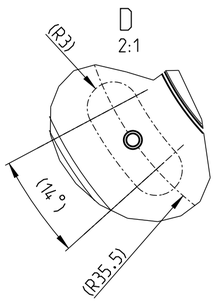
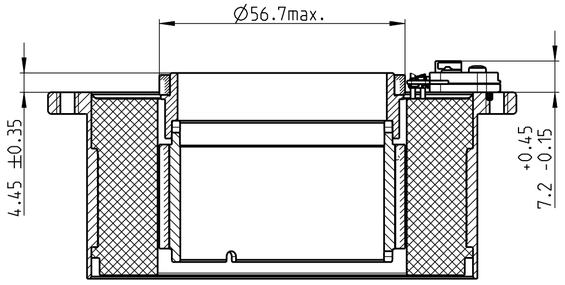
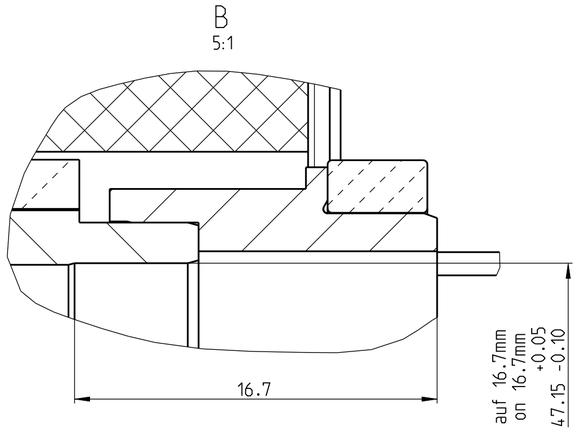
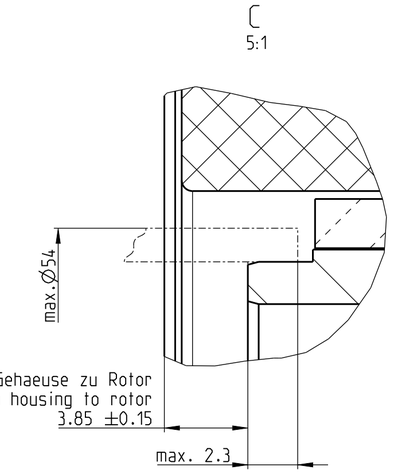
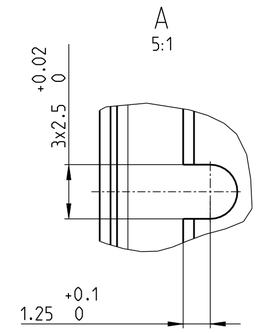
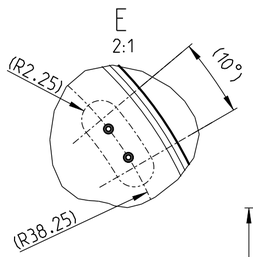


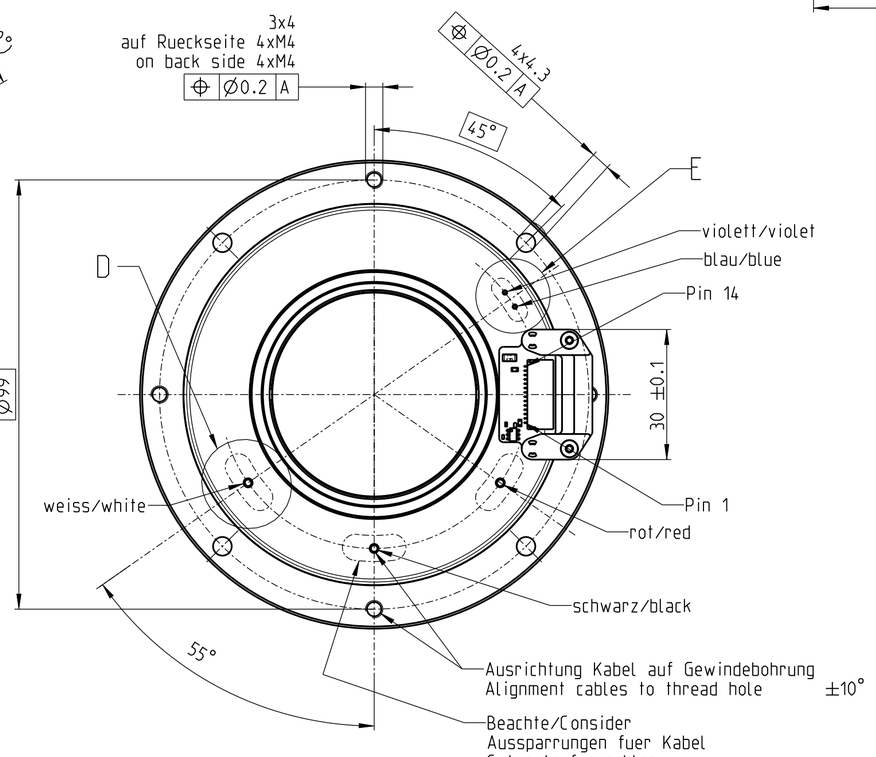


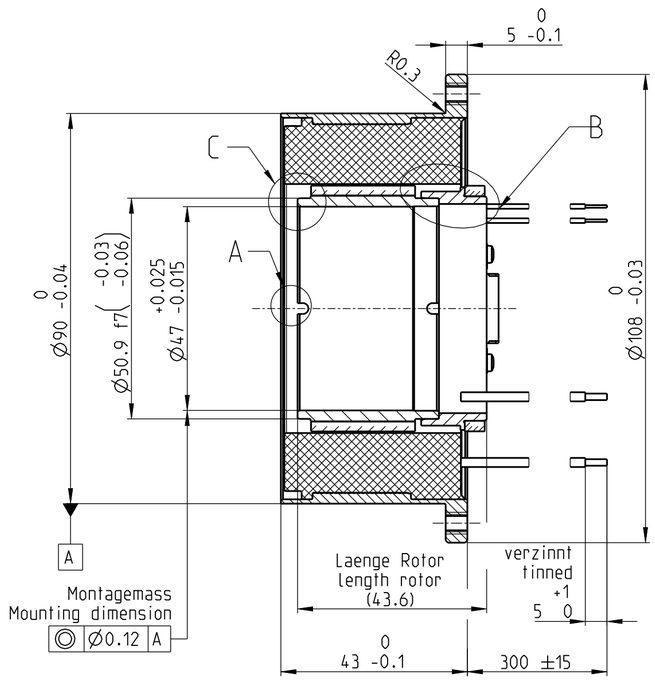


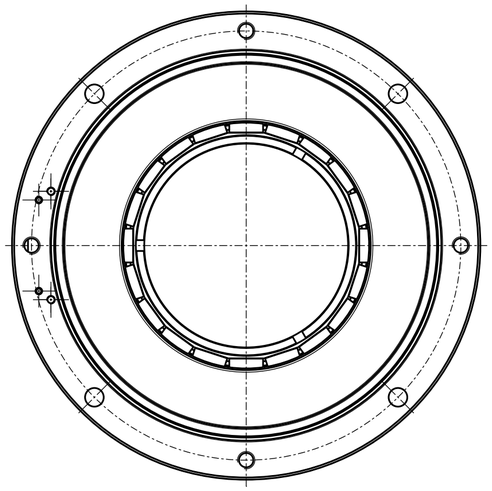






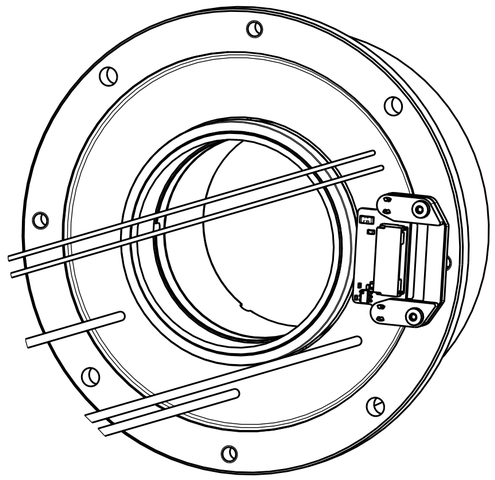






Steckerbelegung Kommutierung + Encoder PIN allocation Commutation + Encoder	
Pin	Signal
PIN 1	Vcc
PIN 2	GND
PIN 3	A/
PIN 4	A
PIN 5	B/
PIN 6	B
PIN 7	N.C.
PIN 8	N.C.
PIN 9	H1
PIN 10	H2
PIN 11	H3
PIN 12	N.C.
PIN 13	NTC+
PIN 14	NTC-

Kabelbelegung/wiring diagram		
AWG16	Kabel rot cable red	= Wicklung 1 = winding 1
AWG16	Kabel schwarz cable black	= Wicklung 2 = winding 2
AWG16	Kabel Kabel cable cable	= Wicklung 3 = winding 3
AWG24	Kabel violett cable violet	= NTC in
AWG24	Kabel blau cable blue	= NTC out



ACHTUNG / ATTENTION

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ISO 8015	ISO 2768-m	ISO 965-1	N/A	ISO 1302	ISO 13715	N/A

DOCUMENT TYPE	Dimensional Drawing	CO-NO: A100027027	DATE	NAME	SCALE	1:1	3D MODEL
TITLE EN	Dimensional Drawing		CREATED	30.03.2022	MMAGMUAG	SHEETS	A2/1/1	8886571
TITLE DE	EC frameless DT85L+TSX MAG		MODIFIED	19.05.2022	MMAGMUAG	DIMENSION UNITS	PROJECTION METHOD	
			RELEASED	13.06.2022	MMAGMUAG	mm	ISO 5456-1	

PART NUMBER	PART REVISION	DOCUMENT NUMBER	DOC REVISION
N/A	N/A	8994972	01

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